

## EXPONENTIAL STABILITY OF POSITIVE SOLUTIONS TO SOME NONLINEAR HEAT EQUATIONS

M.A. JENDOUBI

*Presented by J.P. Dias*

**Abstract:** Following a recent work of A. Haraux in which he proves exponential stability of positive solutions of a heat equation with strictly convex nonlinearity, the same property is shown for a suitable perturbation of the nonlinearity which can, in particular, be non convex.

### 1 – Introduction and main results

Let  $\Omega$  be a bounded and connected open subset of  $\mathbb{R}^N$  with a Lipschitz continuous boundary and let us consider the semilinear heat equation

$$(1.1) \quad \begin{aligned} u_t - \Delta u + f(u) &= k(t, x) && \text{in } \mathbb{R}^+ \times \Omega, \\ u(t, \cdot) &= 0 && \text{on } \mathbb{R}^+ \times \partial\Omega, \\ u(0, \cdot) &= u_0(\cdot) && \text{in } \Omega, \end{aligned}$$

and the elliptic equation

$$(1.2) \quad \begin{aligned} -\Delta u + f(u) &= 0 && \text{in } \Omega, \\ u &= 0 && \text{on } \partial\Omega, \end{aligned}$$

where  $f: \mathbb{R} \rightarrow \mathbb{R}$  is a locally Lipschitz continuous function such that

$$(1.3) \quad f(0) = 0 \quad \text{and} \quad f(s) \rightarrow +\infty \quad \text{as } s \rightarrow +\infty$$

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and  $k: \mathbb{R}^+ \times \Omega \rightarrow \mathbb{R}$  satisfies the conditions

$$(1.4) \quad k \in L^\infty(\mathbb{R}^+ \times \Omega) \quad \text{and} \quad k(t, x) \geq 0 \quad \text{a.e. on } \mathbb{R}^+ \times \Omega .$$

By using standard techniques from the theory of evolution equations, cf. e.g. [5], we know that for all  $u_0 \in L^\infty(\Omega)$  with  $u_0(x) \geq 0$  a.e. on  $\Omega$ , there exists a unique solution  $u \in C((0, +\infty); H_0^1(\Omega) \cap L^\infty(\Omega)) \cap C([0, +\infty); L^2(\Omega))$  of (1.1) such that  $u(0, \cdot) = u_0(\cdot)$ . In addition we have

$$u(t, x) \geq 0 \quad \text{a.e. on } \mathbb{R}^+ \times \Omega .$$

As a consequence of (1.3) and the maximum principle,  $u$  is uniformly bounded on  $\Omega \times \mathbb{R}^+$ . Then by the method of [11], it follows easily that

$$\bigcup_{t \geq 1} \{u(t, \cdot)\} \quad \text{is bounded in } C^{1+\alpha}(\overline{\Omega}) \quad \text{for every } \alpha \in [0, 1) .$$

In particular the curve  $t \mapsto u(t, \cdot)$  has a precompact range in  $H_0^1(\Omega) \cap L^\infty(\Omega)$  for  $t \geq 1$  and it is natural to ask about the *asymptotic behavior* of  $u(t, \cdot)$  as  $t \rightarrow \infty$ .

A. Haraux [8] has proved exponential convergence of nonnegative solutions of (1.1) when  $f$  satisfies the additional hypotheses

$$(1.5) \quad f \quad \text{strictly convex on } [0, +\infty) \quad \text{and} \quad f'_d(0) < -\lambda_1(-\Delta)$$

where  $\lambda_1(-\Delta)$  is the smallest eigenvalue of  $(-\Delta)$  in  $H_0^1(\Omega)$ . The proof of this result is based on the uniqueness of positive solution of the equation (1.2) and the fact that  $\lambda_1(-\Delta + f'(\varphi)) > 0$  ( $\varphi$  is the unique positive solution of (1.2)).

The typical example of nonlinearities which verifies these hypotheses is the following

$$(1.6) \quad f(s) = s^p - \lambda s, \quad \lambda > \lambda_1(-\Delta), \quad p > 1 .$$

The question which we study in this paper is the following: What happens if we perturb the nonlinearity in such a way that convexity of  $f$  is lost? In the special case of example (1.6) a question of interest is the following: Can we find  $\varepsilon > 0$  such that the result of [8] persists for the new nonlinearity

$$h(s) = s^p - \lambda s - \varepsilon s^q$$

with  $p, \lambda$  as in (1.6) and  $1 < q < p$ ?

We are able to give a positive answer to this question. We use the same method as in [8]: At first we prove the uniqueness of positive solution of (1.2)

with this new type of nonlinearity. We assume the following hypotheses: Let  $f$  satisfying (1.3), (1.5), and let  $g: \mathbb{R}^+ \rightarrow \mathbb{R}$  be a function of class  $C^1$  such that

$$(1.7) \quad \begin{aligned} g'(0) &\geq 0, & \lim_{s \rightarrow \infty} f(s) - Cg(s) &= \infty, \\ g(0) &= 0, & g(s) &\geq 0 \quad \forall s \geq 0, \end{aligned}$$

with  $C > 0$  and we consider the nonlinear heat equation

$$(1.8) \quad \begin{aligned} u_t - \Delta u + f(u) &= \varepsilon g(u) + k(t, x) && \text{in } \mathbb{R}^+ \times \Omega, \\ u(t, \cdot) &= 0 && \text{on } \mathbb{R}^+ \times \partial\Omega, \\ u(0, \cdot) &= u_0(\cdot) && \text{in } \Omega \end{aligned}$$

The main results of this paper are the following

**Theorem 1.1.** *Let  $f, g$  satisfy the hypotheses (1.3), (1.5), (1.7). Then there exists  $\varepsilon_1 > 0$  such that for all  $\varepsilon \in [0, \varepsilon_1]$  the equation*

$$(1.9) \quad \Psi \in H_0^1(\Omega), \quad -\Delta\Psi + f(\Psi) = \varepsilon g(\Psi),$$

has one and only one solution  $\Psi \geq 0$  other than 0. In addition we have  $\Psi > 0$  everywhere in  $\Omega$  and

$$(1.10) \quad \lambda_1(-\Delta + f'(\Psi) - \varepsilon g'(\Psi)) > 0 \quad \forall \varepsilon \in [0, \varepsilon_1].$$

**Theorem 1.2.** *Let  $f, g$  and  $k$  satisfy the hypotheses (1.3), (1.4), (1.5), (1.7). Then if  $u_0, v_0 \in L^\infty$  with  $u_0(x) \geq 0$  and  $v_0(x) \geq 0$  a.e. on  $\Omega$ , consider the solution  $u, v$  of (1.1) with respective initial data  $u(0, x) = u_0(x)$  and  $v(0, x) = v_0(x)$ . Assuming either that both  $u_0, v_0$  are not identically 0 or that  $k(t, x) > 0$  on a subset of positive measure of  $\mathbb{R}^+ \times \Omega$ . Then there exists  $\varepsilon_2 > 0$  such that for all  $\varepsilon \in [0, \varepsilon_2]$ , there is  $\gamma > 0$  independent of  $k$  and  $(u_0, v_0)$ :*

$$(1.11) \quad \forall t \geq 0 \quad \|u(t, \cdot) - v(t, \cdot)\|_\infty \leq C(u_0, v_0, \varepsilon) \exp(-\gamma t).$$

The paper is organized as follows: in Section 2 we prove Theorem 1.1, in Section 3 we establish Theorem 1.2 when  $k = 0$ . In Section 4, we establish Theorem 1.2 in the general case. In each section some remarks are presented.

## 2 – The stationary problem

The object of this section is to prove Theorem 1.1.

**Proof of Theorem 1.1.** First we prove the existence of a positive solution for the equation (1.9). In fact, if  $\varepsilon = 0$  then by a theorem of Berestycki [1] (Theorem 4, page 14, cf. also [2], [3]), there exists a unique positive solution  $\varphi$  of (1.2) which verifies

$$(2.1) \quad \lambda_1(-\Delta + f'(\varphi) id) > 0 .$$

Since  $g \geq 0$  then  $\varphi$  is a subsolution of (1.9).

Now we assume that  $\varepsilon < C$ , then by (1.7) there exists  $M > 0$  such that

$$(2.2) \quad f(M) - \varepsilon g(M) > 0 .$$

So  $M$  is a supersolution of (1.9). We claim that  $\|\varphi\|_\infty < M$ . Indeed, let  $x_0 \in \Omega$  such that  $\varphi(x_0) = \|\varphi\|_\infty$ , we have  $\Delta\varphi(x_0) \leq 0$ . Now if  $\|\varphi\|_\infty \geq M$  then we have  $f(M) \leq 0$ . Hence  $f(M) - \varepsilon g(M) \leq 0$ , and this contradicts (2.2). Then there exist a solution  $\Psi$  for (1.9) which verifies  $\varphi \leq \Psi \leq M$ . By using again the maximum principle, we have for all  $\xi$  positive solution of (1.9)  $\xi < M$ . Then the problem (1.9) has a “maximal” solution  $\Psi$  in the sense: any solution  $\xi \neq \Psi$  of (1.9) is less than  $\Psi$ . (This solution can be constructed by a standard iterative scheme.)

Now we have to use the following lemma due to Haraux [9, 10].

**Lemma 2.1.** *Let  $f$  satisfy the hypotheses (1.3), (1.5) and let  $\varphi$  be the positive solution of the equation*

$$\varphi \in C(\Omega) \cap H_0^1(\Omega), \quad -\Delta\varphi + f(\varphi) = 0 .$$

*Let on the other hand  $\xi \geq 0$  be a solution of*

$$\xi \in C(\Omega) \cap H_0^1(\Omega), \quad -\Delta\xi + f(\xi) \geq 0 .$$

*Then either  $\xi = 0$  or  $\xi \geq \varphi$ .*

**Proof of Theorem 1.1** (continued). Let  $\xi$  be a positive solution of (1.9), then by using Lemma 2.1 we have

$$\varphi \leq \xi < M .$$

Now we prove uniqueness. In fact we assume that we have a solution  $\xi$  of (1.9) other than the “maximal” solution  $\Psi$ . Then we have:

$$(2.3) \quad -\Delta(\Psi - \xi) + f(\Psi) - f(\xi) = \varepsilon[g(\Psi) - g(\xi)] .$$

Multiplying (2.3) by  $(\Psi - \xi)$  and integrating over  $\Omega$  we find

$$(2.4) \quad \int_{\Omega} |\nabla(\Psi - \xi)|^2 + [f(\Psi) - f(\xi)] (\Psi - \xi) dx = \varepsilon \int_{\Omega} [g(\Psi) - g(\xi)] (\Psi - \xi) dx .$$

Since  $\varphi \leq \xi \leq \Psi < M$ , then by using (1.5), (1.7) and (2.4) we find

$$(2.5) \quad \int_{\Omega} |\nabla(\Psi - \xi)|^2 + f'(\varphi) |\Psi - \xi|^2 dx \leq \varepsilon \int_{\Omega} C_1 |\Psi - \xi|^2 dx$$

with  $C_1 = \sup\{|g'(s)|, s \in [0, M]\} > 0$ . So

$$(2.6) \quad [\lambda_1(-\Delta + f'(\varphi)) - \varepsilon C_1] \int_{\Omega} |\Psi - \xi|^2 dx \leq 0 .$$

Thank's to (2.1)  $\lambda_1(-\Delta + f'(\varphi) id) > 0$ . Now let  $\varepsilon'$  such that  $\lambda_1(-\Delta + f'(\varphi) id) = \varepsilon' C_1$  and  $\varepsilon_1 = \inf(\varepsilon', C)$ , with  $C$  as in (1.7). Then for all  $\varepsilon \in [0, \varepsilon_1)$ , we have

$$(2.7) \quad \lambda_1(-\Delta + f'(\varphi)) - \varepsilon C_1 > 0 .$$

The uniqueness follows from (2.7), we note this solution by  $\Psi$ . By using (1.5), (1.7) and (2.7) we deduce

$$(2.8) \quad \lambda_1(-\Delta + [f'(\Psi) - \varepsilon g'(\Psi)] id) > 0 \quad \forall \varepsilon \in [0, \varepsilon_1) . \blacksquare$$

### 3 – The autonomous case

The object of this section is to prove Theorem 1.2 in the case  $k = 0$ . We use the method of [8].

**Proof of Theorem 1.2.** Let  $Z = \{z \in C(\overline{\Omega}) \cap H_0^1(\Omega) / z \geq 0\}$ . Subsequently  $h = f - \varepsilon g$  with  $\varepsilon \in [0, \varepsilon_1)$  and  $\varepsilon_1$  is as in Theorem 1.1.

The equation (1.1) generates a dynamical system  $\{S(t)\}_{t \geq 0}$  which assigns to each element  $z \in Z$  the value  $v(t) = S(t)z$  where  $v$  is the solution of (1.8) such that  $v(0) = z$ . Now let  $E$  be the functional defined by

$$\forall \varphi \in Z \quad E(\varphi) = \frac{1}{2} \int_{\Omega} |\nabla \varphi|^2 dx + \int_{\Omega} H(\varphi) dx \quad \text{where } H(u) := \int_0^u h(s) ds .$$

$E$  is a strict Liapunov functional on  $Z$  relative to  $S(t)$  and we refer to [9] for a simple proof.

Let  $u_0 \in L^\infty(\Omega)$ ,  $u_0 \geq 0$ , then by using the maximum principle (cf. for example [5]) we have  $u(t, x) \geq 0$  a.e.  $(t, x) \in \mathbb{R}^+ \times \Omega$ . By the standard invariance principle (cf. [9]), we conclude that the solution  $u(t, \cdot)$  asymptotes the set of nonnegative solutions of (1.9) as  $t \rightarrow \infty$ . We now show that if  $u_0 \neq 0$ ,  $u(t, \cdot)$  cannot tend to 0 as  $t \rightarrow \infty$ .

In fact assuming that  $\lim_{t \rightarrow \infty} \|u(t, \cdot)\|_\infty = 0$ , then for each  $\alpha > 0$ , there is  $T(\alpha)$  such that

$$\forall t \geq T(\alpha) \quad h(u(t, x)) \leq \{h'_d(0) + \alpha\} u(t, x) \quad \text{on } \Omega .$$

Choosing  $\alpha > 0$  small enough such that  $-h'_d(0) - \alpha - \lambda_1(\Omega) > 0$ , multiplying the equation by the positive eigenfunction  $\varphi_1$  corresponding to the first eigenvalue  $\lambda_1(-\Delta)$  of  $-\Delta$  in  $H_0^1(\Omega)$  and integrating over  $\Omega$  we find

$$\frac{d}{dt} \int_{\Omega} u(t, x) \varphi_1 dx \geq 0 \quad \forall t \geq T(\alpha) .$$

Since the function  $t \mapsto \int_{\Omega} u(t, x) \varphi_1 dx$  is nondecreasing on  $[T(\alpha), \infty]$  and tends to 0 as  $t \rightarrow \infty$ , it must vanish identically on  $[T(\alpha), \infty]$ . Because  $\varphi_1$  is positive in  $\Omega$ , this imply that  $u(t, \cdot) = 0 \forall t \geq T(\alpha)$ . Then a classical connectedness argument shows that  $u_0 = 0$ . Therefore if  $u_0 \neq 0$ , the  $\omega$ -limit set of  $u_0$  under  $S(t)$  is reduced to a single point:  $\omega(u_0) = \{\Psi\}$ . Since  $u(t, \cdot)$  remain bounded in  $C^1(\Omega)$  for all  $t \geq 1$  we deduce that

$$\lim_{t \rightarrow \infty} \|u(t, \cdot) - \Psi(\cdot)\|_{1, \infty} = 0 .$$

For the end of the proof, we just need to use (2.8).

**Remark 3.1.** It is clear that  $\lim_{t \rightarrow \infty} \|u(t, \cdot) - \Psi(\cdot)\|_{1, \infty} \exp(ct) = 0$ ,  $\forall c < \lambda_1(-\Delta + h'(\psi) id)$ . In [19], Wiegner has proved that in such a case the difference of two solutions tend to 0 as  $\exp(-c_1 t)$  with  $c_1 = \lambda_1(-\Delta + h'(\psi) id)$ . For related works in the asymptotic of autonomous parabolic equation we refer to [7–9, 12–19].

#### 4 – The nonautonomous case

The object of this section is to prove Theorem 1.2 in the general case. Subsequently  $\varepsilon \in [0, \varepsilon_1)$  and  $\varepsilon_1$  as in Theorem 1.1. In the proof we can use the following lemmas from [8] which are also valid for the modified equation (1.8):

**Lemma 4.1.** *Let  $\psi$  be the unique positive solution of (1.9) and let us consider the solution  $z$  of (1.8) with initial condition  $z(0) = \psi$ . Then we have:*

$$\forall t \geq 0 \quad z(t, x) \geq \psi(x) \quad \text{on } \Omega .$$

**Lemma 4.2.** *Let  $u_0 \in L^\infty(\Omega)$  with  $u_0(x) \geq 0$  a.e. on  $\Omega$  and consider the solution  $u$  of (1.8) with initial datum  $u(0, x) = u_0(x)$ . Assuming either that  $u_0$  is not identically 0 or that  $k(t, x) > 0$  on a subset of positive measure of  $\mathbb{R}^+ \times \Omega$ , we have*

$$(3.1) \quad \lim_{t \rightarrow \infty} \left\| \left( u(t, \cdot) - \psi(\cdot) \right)^- \right\|_\infty = 0 .$$

**Proof of Theorem 1.2:** Obviously, it is sufficient to prove the result when  $v_0 = \psi$ . Then  $v(t) = z(t)$  and

$$\begin{aligned} \forall t > 0 \quad & \frac{1}{2} \frac{d}{dt} \left( \int_\Omega |u(t, x) - z(t, x)|^2 dx \right) = \\ & = - \int_\Omega |\nabla(u - z)|^2 dx - \int_\Omega [f(u) - f(z)] (u - z) dx + \varepsilon \int_\Omega [g(u) - g(z)] (u - z) dx . \end{aligned}$$

By convexity of  $f$ , since  $z(t) \geq \psi$  for all  $t$ , we have  $f(z)/z \geq f(\psi)/\psi$ . Moreover from (3.1) it follows in particular that fixing some nonempty open set  $\omega$  contained in a compact subset of  $\Omega$ , we have for  $t \geq T$  depending on the solution  $u$  that

$$(3.2) \quad \forall t \geq T \quad u(t, x) \geq \frac{1}{2} \psi(x) \quad \text{on } \omega .$$

Now from (3.2) we deduce easily the inequality

$$\begin{aligned} \forall t \geq T \quad & \frac{1}{2} \frac{d}{dt} \left( \int_\Omega |u(t, x) - z(t, x)|^2 dx \right) = \\ & = - \int_\Omega |\nabla(u - z)|^2 dx - \int_\Omega c(x) |u - z|^2 dx + \varepsilon \int_\Omega [g(u) - g(z)] (u - z) dx \end{aligned}$$

with

$$c(x) = \begin{cases} \frac{f(\psi)}{\psi} & \text{outside } \omega, \\ 2 \frac{f(\psi) - f(\psi/2)}{\psi} & \text{in } \omega . \end{cases}$$

Let

$$\delta = \inf \left\{ \int_\Omega (|\nabla w|^2 + c(x) w^2) dx, \quad w \in H_0^1(\Omega), \int_\Omega w^2 dx = 1 \right\} .$$

We can prove as in [8] that  $\delta > 0$ . In the other hand, there exists  $C_1 > 0$  such that

$$\int_{\Omega} [g(u) - g(z)] (u - z) dx \leq C_1 \int_{\Omega} |u - z|^2 dx .$$

Set  $\varepsilon'' = \frac{\delta}{C_1}$  and let  $\varepsilon_2 = \inf(\varepsilon_1, \varepsilon'')$ , then we obtain for all  $t \geq T$

$$\frac{d}{dt} \left( \int_{\Omega} |u(t, x) - z(t, x)|^2 dx \right) \leq -(\delta - \varepsilon C_1) \int_{\Omega} |u - z|^2 dx .$$

The end of the proof is the same as in [8].

**Remark 4.3.** It is instructive to compare the result of Theorem 1.2 with the result of Chen and Matano [6], recently completed with a simple proof by Brunovsky et al. [4]. The result of [4, 6] are proved for any nonlinearity but only in one space dimension and for time-periodic forcing terms. On the other hand Theorem 1.2 is valid for any space dimension, but it is restricted to positive solution and a special type of nonlinearities.

**Remark 4.4.** This result can be viewed as a “structural stability” property for the result of [8]. However our method of proof is constructive since given  $\lambda_1(-\Delta + f'(\psi) id) = \gamma > 0$ , we can specify explicitly  $\varepsilon_1$  and  $\varepsilon_2$  in terms of the function  $g$ .

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Mohamed Ali Jendoubi,  
Département de Mathématiques, Bat. Fermat, Université de Versailles,  
45 Av. des États Unies, 78035 Versailles – FRANCE  
E-mail: jendoubi@math.uvsq.fr