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ON A THEOREM OF MYSHKIS–TSALYUK

(Reported on June 19 and 26, 1995)

Consider the system of differential equations with delay

$$\frac{dx(t)}{dt} = f(t, x(t), x(\tau_1(t)), \dots, x(\tau_m(t))), \quad (1)$$

where  $f : [a, b] \times R^{(m+1)n} \rightarrow R^n$  is a vector function from the Caratheodory class and  $\tau_i : [a, b] \rightarrow [a, b]$  ( $i = 1, \dots, m$ ) are measurable functions satisfying the inequalities

$$\tau_i(t) \leq t \quad \text{for } a \leq t \leq b \quad (i = 1, \dots, m).$$

Let  $b_0 \in ]a, b[$ . A vector function  $x : [a, b_0] \rightarrow R^n$  (a vector function  $x : [a, b_0[ \rightarrow R^n$ ) is said to be a solution of the system (1) on  $[a, b_0]$  (on  $[a, b_0[$ ) if it is absolutely continuous on  $[a, b_0]$  (on every segment contained in  $[a, b_0[$ ) and satisfies (1) a.e. on  $[a, b_0]$ .

The solution  $x$  of the system (1) is said to be noncontinuable if one of the following conditions is fulfilled:

- i)  $x$  is defined on the segment  $[a, b]$ ;
- ii)  $x$  is defined on the segment  $[a, b_0[$ , where  $b_0 \in [a, b[$ , and

$$\limsup_{t \rightarrow b_0} \|x(t)\| = +\infty.$$

A. D. Myshkis and Z. B. Tsalyuk [2] have proved a theorem on nonlocal continuability of solutions of the system (1), concerning the case where growth order of the vector function  $f$  with respect to the last  $mn$  arguments exceeds 1. Below we shall give a more general theorem of the same type.

The use will be made of the following notation:

$R$  is the set of real numbers;  $R_+ = [0, +\infty[$ ;

$R^l$  is the space of vectors  $x = (x_i)_{i=1}^l$  with the components  $x_i \in R$  ( $i = 1, \dots, l$ ) and

the norm  $\|x\| = \sum_{i=1}^l |x_i|$ ;

$R_+^l = \{(x_i)_{i=1}^l \in R^l : x_i \in R_+ (i = 1, \dots, l)\}$ ;

$x \cdot y$  is the scalar product of the vectors  $x$  and  $y \in R^n$ ;

if  $x = (x_i)_{i=1}^n$ , then  $\text{sgn}(x) = (\text{sgn}(x_i))_{i=1}^n$ .

**Theorem.** *Let for every  $s \in ]a, b[$  there exist a number  $\delta_s \in ]0, s - a[$ , a vector  $c_s \in R^n$  and functions  $\tau_{is} : [s - \delta_s, s] \rightarrow [s - \delta_s, s]$  and  $\varphi_s : [s - \delta_s, s] \times R_+^{m+1} \rightarrow R_+$  such that*

$$\tau_i(t) \leq \tau_{is}(t) \quad \text{for } s - \delta_s \leq t \leq \delta_s \quad (i = 1, \dots, m)$$

and the inequality

$$f(t, c_s + y_0, c_s + y_1, \dots, c_s + y_m) \cdot \text{sgn}(y_0) \leq \rho_s(t, \|y_0\|, \dots, \|y_m\|)$$

1991 *Mathematics Subject Classification.* 34K10.

*Key words and phrases:* System of differential equations with delay, noncontinuable solution, nonlocal continuability.

is fulfilled on  $[s - \delta_s, s] \times R^{(m+1)n}$ . Moreover, let  $\tau_{i_s}$  ( $i = 1, \dots, m$ ) be measurable,  $\varphi$  be summable in the first argument, continuous and nondecreasing in the last  $m + 1$  arguments and let for every  $\rho \in R_+$  the initial problem

$$\frac{du(t)}{dt} = \varphi_s(t, u(t), u(\tau_{1_s}(t)), \dots, u(\tau_{m_s}(t))); \quad u(s - \delta(s)) = \rho$$

have upper solution defined on  $[s - \delta(s), s]$ . Then every noncontinuable solution of the system (1) is defined on  $[a, b]$ .

**Corollary 1.** Let for every  $s \in ]a, b[$  there exist numbers  $m_s \in \{0, \dots, m - 1\}$ ,  $\delta_s \in ]0, s - a[$ , a vector  $c_s \in R^n$  and functions  $\alpha_s : [s - \delta(s), s] \times R_+ \rightarrow R_+$  and  $\varphi_s : R_+ \rightarrow ]0, +\infty[$  such that

$$\tau_k(t) \leq s - \delta(s) \quad \text{for } a \leq t \leq b \quad (k = m_s + 1, \dots, m)$$

and the inequality

$$f(t, c_s + y_0, \dots, c(s) + y_m) \cdot \text{sgn}(y_0) \leq \alpha_s \left( t, \sum_{k=m_s+1}^m \|y_k\| \right) \varphi_s \left( \sum_{k=0}^{m_s} \|y_k\| \right).$$

is fulfilled on the set  $[s - \delta(s), s] \times R^{(m+1)n}$ . Moreover, let  $\alpha_s$  be summable in the first argument, continuous and nondecreasing in the second argument,  $\varphi_s$  be continuous, nondecreasing and

$$\int_0^{+\infty} \frac{du}{\varphi_s(u)} = +\infty.$$

Then every noncontinuable solution of the system (1) is defined on  $[a, b]$ .

**Corollary 2.** Let for every  $s \in ]a, b[$  there exist numbers  $m_s \in \{1, \dots, m - 1\}$ ,  $\delta_s \in ]0, s - a[ \cap ]0, 1[$ ,  $\lambda_{k_s} \in [1, +\infty[$ ,  $\beta_s \in ]-1, 0[$  and a continuous function  $\alpha_s : R_+ \rightarrow R_+$  such that the inequalities

$$\tau_k(t) \leq s - (s - t)^{\frac{1}{\lambda_{k_s}}} \quad (k = 1, \dots, m_s), \quad \tau_k(t) \leq s - \delta(s) \quad (k = m_s + 1, \dots, m)$$

and

$$f(t, c_s + y_0, \dots, c_s + y_m) \cdot \text{sgn}(y_0) \leq \alpha_s \left( \sum_{k=m_s+1}^m \|y_k\| \right) (s - t)^{\beta_s} \left( 1 + \sum_{k=1}^{m_s} \|y_k\|^{\lambda_{k_s}} \right) \ln \left( 2 + \sum_{k=1}^{m_s} \|y_k\| \right).$$

are fulfilled on  $[s - \delta(s), s]$  and on  $[s - \delta(s), s] \times R^{(m+1)n}$ , respectively. Then every noncontinuable solution of the system (1) is defined on  $[a, b]$ .

Corollary 1 is an analogue of the wellknown A. Wintner's theorem ([1], Ch. III, §3.5) for the system (1), while Corollary 2 is a generalization of the above-mentioned Myshkis-Tsalyuk theorem.

#### REFERENCES

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