

## ON TRANSFORMATIONS OF WIENER SPACE

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### ABSTRACT

We consider transformations of the form

$$(T_a x)_t = x_t + \int_0^t a(s, x) ds$$

on the space  $C$  of all continuous functions  $x = x_t: [0, 1] \rightarrow \mathbb{R}$ ,  $x_0 = 0$ , where  $a(s, x)$  is a measurable function  $[0, 1] \times C \rightarrow \mathbb{R}$  which is  $\tilde{\mathcal{C}}_s$ -measurable for a fixed  $s$  and  $\tilde{\mathcal{C}}_s$  is the  $\sigma$ -algebra generated by  $\{x_u, u \leq t\}$ . It is supposed that  $T_a$  maps the Wiener measure  $\mu_0$  on  $(C, \tilde{\mathcal{C}}_1)$  into a measure  $\mu_a$  which is equivalent with respect to  $\mu_0$ . We study some conditions of invertibility of such transformations. We also consider stochastic differential equations of the form

$$dy(t) = dw(t) + a(t, y(t))dt, \quad y(0) = 0$$

where  $w(t)$  is a Wiener process. We prove that this equation has a unique strong solution if and only if it has a unique weak solution.

**Key words:** Wiener Space, Invertible Transformation, Girsanov's Theorem, Sets of the Second Category, Stochastic Differential Equation, Weak and Strong Solutions of Stochastic Differential Equations.

**AMS (MOS) subject classifications:** 60G99, 60H99, 60H10.

### 1. Introduction

Denote by  $C$  the space of continuous functions  $x = x_t: [0, 1] \rightarrow \mathbb{R}$  for which  $x_0 = 0$  and by  $\tilde{\mathcal{C}}_t$ ,  $t \in [0, 1]$  the  $\sigma$ -algebra of subsets  $C$  which is generated by subsets  $\{x \in C: x_s < \lambda\}$ ,  $\lambda \in \mathbb{R}$ ,  $s \leq t$ . Let  $\mu_0$  be a Wiener measure and  $C_t$  be the completion of  $\tilde{\mathcal{C}}_t$  with respect to the measure  $\mu_0$ . Note that the measurable space with the measure  $\{C, \tilde{\mathcal{C}}_1, \mu_0\}$  is called the Wiener space. We consider transformations  $T_a: C \rightarrow C$  of the form

$$T_a(x)_t = x_t + \int_0^t a(s, x) ds, \quad (1)$$

where the function  $a: [0, 1] \times C \rightarrow R$  satisfies condition

$$A1) \quad a \text{ is } \mathfrak{B}_{[0,1]} \otimes \tilde{\mathfrak{C}}_1\text{-measurable, where } \mathfrak{B}_{[0,1]} \text{ is the Borel } \sigma\text{-algebra on } [0, 1], \text{ and } a(s, x) \text{ is } \tilde{\mathfrak{C}}_s\text{-measurable for a fixed } s \in [0, 1].$$

Such transformations were considered by R. Sh. Liptser and A.N. Shiryaev [3] and M.P. Ershov [2]. They established conditions under which the image  $\mu_a$  of the measure  $\mu_0$  under transformation  $T_a$  is an equivalent measure with respect to measure  $\mu_0$ . If this is true then there exists a function  $c(s, x)$  which satisfies condition A1) and

$$\frac{d\mu_a(x)}{d\mu_0(x)} = e(c, x) = \exp \left\{ \int_0^1 c(s, x) dx(s) - \frac{1}{2} \int_0^1 c^2(s, x) ds \right\} \quad (2)$$

with

$$\int e(c, x) \mu_0(dx) = 1 \quad (3)$$

(the integral with respect to  $dx(s)$  is Ito's integral). A.A. Novikov proved in [4] that the condition

$$\int e^{\frac{1}{2} \int_0^1 c^2(s, x) ds} \mu_0(dx) < \infty \quad (4)$$

implies (3).

We consider the set  $\mathbb{A}$  of functions  $a(s, x): [0, 1] \times C \rightarrow R$  which satisfy condition A1) and condition

$$A2) \quad \lim_{r \rightarrow \infty} r^{-1} \sup \left\{ \int_0^1 a^2(s, x) ds; x \in U_r \right\} = 0, \text{ where } U_r = \left\{ x \in C: \int_0^1 x_s^2 ds \leq r \right\}.$$

Note that if  $a \in \mathbb{A}$  then  $\int (e(a, x))^k \mu_0(dx) < \infty$  for all integer numbers  $k$ , which is a consequence of Novikov's results.

Denote  $\mathbb{T} = \{T_a, a \in \mathbb{A}\}$ . Note that  $\mathbb{T}$  is a semigroup with respect to the product

$$(T_a \cdot T_b)x_s = x_s + \int_0^s b(u, x) du + \int_0^s a(u, T_b x) du. \quad (5)$$

Obviously,  $T_a$  is an invertible transformation if there exists a function  $c \in \mathbb{T}$  for which  $T_a T_c x = x$  ( $\mu_0$ -a.s.). Then,  $T_c T_a x = x$  ( $\mu_0$ -a.s.), and we call  $T_c$  the *inverse transformation* and denote it  $T_a^{-1}$ .

**Remark:** Below we consider all relations with  $x$  as valid ( $\mu_0$ -a.s.).

We denote by  $\mathbb{T}_R$  the set of all invertible transformations  $T_a$  and by  $\mathbb{A}_R$  the subset of those  $a \in \mathbb{A}$  for which  $T_a \in \mathbb{T}_R$ .

The main goal of this article is to formalize the set  $\mathbb{T}_R$ . Besides, we consider the stochastic differential equation

$$dy(t) = w(t) + a(t, y(\cdot)) dt; \quad t \in [0, 1], \quad y(0) = 0, \quad (6)$$

where  $w(t)$  is a Wiener process,  $a \in \mathbb{A}$ , and describe its weak and strong solutions.

## 2. Representations of Densities

Denote  $\rho_a(x) = \frac{d\mu_a}{d\mu_0}(x)$ . We consider  $\{C, \mathcal{C}_1, \mu_0\}$  as a probability space and denote by  $E_{\mu_0}$  and  $E_{\mu_0}(\cdot | \cdot)$ , respectively, the expectation and the conditional expectation on this space. For  $a \in \mathbb{A}$  we define the function  $\bar{a}(t, x)$  by the relation

$$\bar{a}(t, T_a x) = E_{\mu_0}(a(t, x) | \sigma(T_a x_s, s \leq t)). \tag{7}$$

Here  $\sigma(T_a x_s, s \leq t)$  is the  $\sigma$ -algebra induced by  $\{T_a x_s, s \leq t\}$ . It is easy to verify that we can choose  $\bar{a}$  in such a way that  $\bar{a} \in \mathbb{A}$ .

**Theorem 1:** *The following equation holds true:*

$$\rho_a(x) = e(\bar{a}, x). \tag{8}$$

**Proof:** The stochastic process

$$z(t) = x_t + \int_0^t (a(s, x) - \bar{a}(s, T_a x)) ds$$

on the probability space  $\{C, \mathcal{C}_1, \mu_0\}$  is a martingale with respect to the filtration  $\{\sigma(T_a x_s, s \leq t), t \in [0, 1]\}$  because

$$z(t) = (T_a x)_t - \int_0^t \bar{a}(s, T_a x) ds. \tag{9}$$

It is easy to verify that  $\langle z, z \rangle_t = t$ , so,  $z(t)$  is a Wiener process. Girsanov's theorem (see [1]) and relation (9) imply that the process  $(T_a x)_t$  is a Wiener process on the probability space  $\{C, \mathcal{C}_1, \bar{\mu}\}$ , where

$$\frac{d\bar{\mu}}{d\mu_0} = exp \left\{ - \int_0^1 \bar{a}(s, T_a x) dx_s - \frac{1}{2} \int_0^1 \bar{a}^2(s, T_a x) ds \right\}.$$

Therefore, for bounded  $\mathcal{C}_1$ -measurable functions  $f(x): C \rightarrow R$ , we have that

$$\begin{aligned} \int f(x) \mu_0(dx) &= \int f(T_a x) \bar{\mu}(dx) \\ &= \int f(T_a x) exp \left\{ - \int_0^1 \bar{a}(s, T_a x) dT_a x_s + \frac{1}{2} \int_0^1 \bar{a}^2(s, T_a x) ds \right\} \mu_0(dx) \\ &= \int f(x) e^{-1(\bar{a}, x)} \rho_a(x) \mu_0(dx). \end{aligned}$$

Due to the relation

$$\int f(T_a x) \mu_0(dx) = \int f(x) \mu_a(dx) = \int f(x) \rho_a(x) \mu_0(dx),$$

we have that

$$e^{-1}(\bar{a}, x)\rho_a(x) = 1 \quad (\mu_0\text{-a.s.}) \quad \square$$

**Remark:** Denote by  $\mu_a^t$  the restriction of measure  $\mu_a$  on the  $\sigma$ -algebra  $\mathfrak{C}_t$  and by

$$\rho_a^t(x) = \frac{d\mu_a^t}{d\mu_0^t}(x). \tag{10}$$

Let

$$e_t(c, x) = \exp\left\{ \int_0^t c(s, x)dx(s) - \frac{1}{2} \int_0^t c^2(s, x)ds \right\}. \tag{11}$$

Then

$$\rho_a^t(x) = e_t(\bar{a}, x). \tag{12}$$

This relation can be proved in the same way as relation (8).

### 3. The Conditions of Invertibility of $T_a$

**Theorem 2:** *The statements*

- (i)  $a(t, x)$  is  $\sigma(T_a x_s, s \leq t)$ -measurable for  $t \in [0, 1]$ .
- (ii)  $T_a \in \mathbb{T}_R$ , and
- (iii)  $\rho_a^t(T_a x) = e_t^{-1}(-a, x)$ ,  $t \in [0, 1]$

are equivalent.

**Proof:** (ii) $\Rightarrow$ (i), since  $a(t, x) = a(t, T_a^{-1}(T_a x))$ . (i) implies that  $-a(t, x) = \tilde{a}(t, T_a x)$  and

$$(T_a^{-1} T_a x)_t = x_t + \int_0^t a(s, x)ds + \int_0^t \tilde{a}(s, T_a x)ds = x_t.$$

Thus, (ii) is true. (ii) implies that  $\bar{a}(t, x) = a(t, T_a^{-1}x)$  and (iii) is a consequence of formula (12). Suppose (iii) is true, then the martingale  $e_t(-a, x)$  is  $\sigma(T_a x_s, s \leq t)$ -measurable.

Using the representation

$$e_t(-a, x) = 1 - \int_0^t e_s(-a, x)a(s, x)dx_s$$

we can establish  $\sigma(T_a x_s, s \leq t)$ -measurability of  $a(t, x)$ . Therefore, (iii) $\Rightarrow$ (i). □

**Theorem 3:** *Let  $a_n \in \mathbb{A}$ ,  $n = 1, 2, \dots$ ,  $a \in \mathbb{A}$  and let the following conditions be satisfied:*

- 1)  $a_n \in \mathbb{A}_R$ ,  $n = 1, 2, \dots$ ;
  - 2)  $T_{a_n} x \rightarrow T_a x$  in  $C(\mu_0\text{-a.s.})$ ;
  - 3)  $\lim_{n \rightarrow \infty} \int |e_t^{-1}(-a_n, x) - e_t^{-1}(-a, x)| \mu_0(dx) = 0$ ,  $t \in [0, 1]$ ;
- and
- 4)  $\lim_{n \rightarrow \infty} \int (\rho_{a_n}(x) - \rho_a(x))^2 \mu_0(dx) = 0$ .

Then  $a \in \mathbb{A}_R$ .

**Proof:** Condition 2) implies the relation

$$\lim_{n \rightarrow \infty} \int |\phi(T_{a_n} x) - \phi(T_a x)| \mu_0(dx) = 0$$

for all bounded continuous functions  $\phi: C \rightarrow \mathbb{R}$ . Using approximations of  $\rho_a(x)$  by bounded continuous functions in  $L_1(\mu_0)$  we can prove that

$$\lim_{n \rightarrow \infty} \int |\rho_a(T_{a_n} x) - \rho_a(T_a x)| \mu_0(dx). \tag{13}$$

Since

$$\begin{aligned} & \lim_{n \rightarrow \infty} \int |\rho_a(T_{a_n} x) - \rho_{a_n}(T_{a_n} x)| \mu_0(dx) \\ &= \lim_{n \rightarrow \infty} \int |\rho_a(x) - \rho_{a_n}(x)| \mu_0(dx) = 0 \end{aligned}$$

because of condition 4), we have that

$$\lim_{n \rightarrow \infty} \int |\rho_{a_n}(T_{a_n} x) - \rho_a(T_a x)| \mu_0(dx) = 0. \tag{14}$$

Besides, conditions 2) and 3) and theorem 2 imply the relation

$$\lim_{n \rightarrow \infty} \int |\rho_{a_n}(T_{a_n} x) - e^{-1}(-a, x)| \mu_0(dx) = 0. \tag{15}$$

It follows from (14) and (15) that  $e^{-1}(-a, x) = \rho_a(T_a x)$ . In the same way, we prove that statement (iii) of theorem 2 holds true for all  $t \in [0, 1]$ .  $\square$

#### 4. Topological Properties of $\mathbb{A}_R$

We introduce the distance in  $\mathbb{A}$ :

$$\begin{aligned} d(a_1, a_2) &= \int \|a_1(\cdot, x) - a_2(\cdot, x)\|_c \mu_0(dx) \\ &+ \left( \int (e^{-1}(-a_1, x) - e^{-1}(-a_2, x))^2 \mu_0(dx) \right)^{1/2}, \end{aligned}$$

where  $\|x\|_c = \sup_{t \in [0, 1]} |x_t|$ .

**Theorem 4:** Denote by

$$Q(a) = \int \rho_a^2(x) \mu_0(dx).$$

Then

$$\mathbb{A}_R = \left\{ a: \lim_{d(\tilde{a}, a) \rightarrow 0} Q(\tilde{a}) = Q(a) \right\}.$$

**Proof:** We have

$$\int (\rho_a(x) - \rho_{\tilde{a}}(x))^2 \mu_0(dx) = Q(a) + Q(\tilde{a}) - 2 \int \rho_a(T_{\tilde{a}} x) \mu_0(dx).$$

Let  $d(\tilde{a}, a) \rightarrow 0$ . Then,

$$\lim_{d(\tilde{a}, a) \rightarrow 0} \int \rho_a(T_{\tilde{a}} x) \mu_0(dx) = \int \rho_a(T_a x) \mu_0(dx) = Q(a).$$

Therefore,

$$\limsup_{d(\tilde{a}, a) \rightarrow 0} \int (\rho_a(x) - \rho_{\tilde{a}}(x))^2 \mu_0(dx) = \limsup_{d(\tilde{a}, a) \rightarrow 0} (Q(\tilde{a}) - Q(a)). \quad (16)$$

Introduce the sequence

$$a_n(s, x) = Ea(s, \frac{1}{n}w(\cdot) + f_n(x, \cdot)), \quad x \in C, \quad (17)$$

where  $w(t)$  is a Wiener process,

$$f_n(x, s) = n \int_{0 \vee s - \frac{1}{n}}^s x_u du.$$

It is easy to verify that

$$\lim_{n \rightarrow \infty} d(a_n, a) = 0 \text{ if } a \in \mathbb{A}. \quad (18)$$

$a_n$  can be rewritten in the form

$$a_n(s, x) = Ea(s, \frac{1}{n}w(\cdot)) \exp \left\{ \int_0^1 g_n(x, u) dw(u) - \frac{1}{2} \int_0^1 g_n^2(x, u) du \right\}, \quad (19)$$

where

$$g_n(x, u) = n^2(x(u) - x(0 \vee u - \frac{1}{n})).$$

(18) implies that there exists a constant  $\ell_n$  for which

$$|a_n(s, x) - a_n(s, \tilde{x})| \leq \ell_n \|x - \tilde{x}\|_C, \quad x, \tilde{x} \in C. \quad (20)$$

Therefore,  $T_{a_n} \in \mathbb{T}_R$ . Let  $\lim_{\tilde{a} \rightarrow a} Q(\tilde{a}) - Q(a)$ , then (16), (18) and theorem 3 imply that  $a \in \mathbb{A}_R$ .

Now we consider the space  $L_2(\mu_0)$  of functions  $f$  for which  $\int f^2(x) \mu_0(dx) < \infty$ . It is a separable Hilbert space. Let  $\{\varphi_k, k = 1, 2, \dots\}$  be an orthonormal base in  $L_2(\mu_0)$ . Then,

$$Q(a) = \sum_k q_k^2(a),$$

where for all  $k$ ,

$$q_k(a) = \int \rho_a(x) \varphi_k(x) \mu_0(dx) = \int \varphi_k(T_a x) \mu_0(dx)$$

are continuous functions. Therefore,

$$\liminf_{d(\tilde{a}, a) \rightarrow 0} Q(\tilde{a}) \geq Q(a).$$

If

$$Q(a) < \lim_{n \rightarrow \infty} Q(a_n) = \lim_{n \rightarrow \infty} \int \rho_{a_n}(T_{a_n} x) \mu_0(dx)$$

$$= \lim_{n \rightarrow \infty} \int e^{-1}(a - a_n, x) \mu_0(dx) = \int e^{-1}(-a, x) \mu_0(dx),$$

then,  $\int (\rho_a(T_a x) - e^{-1}(-a, x)) \mu_0(dx) < 0$ , and  $a \in \mathbb{A} \setminus \mathbb{A}_R$  because of theorem 2. □

**Corollary:** Let  $\lambda(t): \mathbb{R}_+ \rightarrow \mathbb{R}_+$  be a decreasing continuous function for which  $\lim_{t \rightarrow +\infty} \lambda(t) = 0$ . Denote

$$\mathbb{A}^\lambda = \left\{ a \in \mathbb{A}: \int_0^1 a^2(s, x) ds \leq r\lambda(r) \text{ for } x \in U_r \right\}.$$

is of second Baire's category.

This follows from the properties of the set of points of continuity of a half-continuous function (see for example [5], p. 57).

### 5. Consequences for Stochastic Differential Equations

We recall that  $y(t)$  is a weak solution of equation (6) if the stochastic process

$$z(t) = y(t) - \int_0^t a(s, y(\cdot)) ds$$

is a Wiener process. Note that the measure  $\mu_z$  corresponding to the process  $z$  is determined by the measure  $m_y$  which corresponds to  $y$ . It is natural to call a weak solution of equation (6) a measure  $\mu$  for which  $\mu T_{-a}^{-1} = \mu_0$ .

**Theorem 5:** Let  $S^a = \{\mu: \mu T_{-a}^{-1} = \mu_0\}$ . Then,

- 1)  $S^a$  is a convex weakly closed set in  $M(C)$ , where  $M(C)$  is the set of all probability measures on  $\mathcal{C}_1$ .
- 2)  $a \in \mathbb{A}_R$  if and only if  $S^a = \{\mu^a\}$ , where  $\mu^a$  is the measure for which

$$\frac{d\mu^a}{d\mu_0}(x) = e(a, x).$$

**Proof:** Girsanov's theorem implies that  $\mu^a \in S^a$  for all  $a \in \mathbb{A}$ . Let  $-a \in \mathbb{A} \setminus \mathbb{A}_R$ . Then for a bounded  $\mathcal{C}_1$ -measurable function  $f: C \rightarrow \mathbb{R}$  we have that

$$\begin{aligned} \int f(x) \mu_0(dx) &= \int e(a, x) f(T_{-a} x) \mu_0(dx) \\ &= \int E_{\mu_0}(e(a, x) / \sigma(T_{-a} x_s, s \leq 1)) \cdot f(T_{-a} x) \mu(dx). \end{aligned}$$

Therefore, the measure  $\hat{\mu}$ , which is determined by the relation

$$\frac{d\hat{\mu}}{d\mu_0}(x) = E_{\mu_0}(e(a, x) / \sigma(T_{-a} x_s, s \leq 1)),$$

belongs to  $S^a$  since

$$\int f(x) \mu_0(dx) = \int f(T_{-a} x) \hat{\mu}(dx).$$

It may be shown that the equality  $\hat{\mu} = \mu^a$  implies the measurability of  $e_t(a, x)$  with respect to the  $\sigma$ -algebra  $\sigma((T_{-a} x)_s, s \leq t)$  and invertibility of  $T_{-a}$ . Thus,  $\hat{\mu}$  and  $\mu^a$  are two distinct points of  $S^a$ . □

$y(t)$  is a strong solution of equation (6) if  $y(t)$  is  $\sigma(w(s), s \leq t)$ -measurable for all  $t \in [0, 1]$ .

**Theorem 6:** 1) Let  $y(t)$  be a strong solution of equation (6). Then,  $T_{-a} \in \mathbb{T}_R$ ,  $y(t) = (T_{-a}^{-1}w)_t$  and  $y(t)$  is the unique solution of equation (6).

2) Equation (6) has no strong solution if  $a \in \mathbb{A} \setminus \mathbb{A}_R$ .

**Proof:** 1)  $y(t)$  may be represented in the form:  $y(t) = Y(t, w(\cdot))$ , where  $Y(t, x)$  is  $\mathfrak{B}_{[0,1]} \otimes \mathfrak{C}_1$ -measurable function and, for a fixed  $t \in [0, 1]$ , it is  $\mathfrak{C}_t$ -measurable. Therefore,

$$y(t) = w(t) + \int_0^t a(s, Y(\cdot, w(\cdot))) ds. \quad (21)$$

Set

$$b(s, x) = a(s, Y(\cdot, x)).$$

It follows from (21) and (6) that

$$y(t) = (T_b w)_t \text{ and } (T_{-a} T_b w)_t = w(t).$$

Hence,

$$T_{-a} \in \mathbb{T}_R, T_b = T_{-a}^{-1}, \text{ and } y(t) = (T_{-a}^{-1}w)_t.$$

This is true for any solution of (6). Therefore,  $y(t)$  is unique.

2) follows from 1). □

**Corollary:** Equation (6) has a strong solution and then it is unique if and only if this equation has a unique weak solution.

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