

CONTINUITY PROPERTIES OF SOLUTIONS OF MULTIVALUED EQUATIONS WITH WHITE NOISE PERTURBATION

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In the paper, we consider a set-valued stochastic equation with stochastic perturbation in a Banach space. We prove first the existence theorem and then study continuity properties of solutions.

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1. Preliminaries

Problems of existence of solutions to set-valued differential equations were studied by many (see e.g., [3, 8, 9]). In particular, random cases were considered by the author in [11, 12].

In this paper we study the set-valued stochastic equation with white noise drift:

$$\begin{aligned}DX_t &= F(t, X_t)dt + \sigma_t dw_t, t \in I, \\X_0 &= U \quad P.1,\end{aligned}\tag{I}$$

where F and U are given random set-valued mappings with values in the space $K_c(E)$, of all nonempty, compact and convex subsets of the separable Banach space $(E, \| \cdot \|)$, $I = [0, T]$; $T > 0$. We assume also that there is a predictable stochastic process σ with values in E . Finally, $(w_t)_{t \in I}$ denotes a real Wiener process. We interpret the above equation through its integral form as

$$X_t = U + \int_0^t F(s, X_s)ds + \int_0^t \sigma_s dw_s \quad P.1, t \in I.\tag{II}$$

Integrals above are Aumann's integral of F and stochastic (Itô) integral of σ , respectively.

The aim of this work is to study continuity properties of set-valued solutions of

(I). First, we recall several notions needed in the sequel. In the space $K_c(E)$ we consider the Hausdorff metric H (see e.g., [5, 7]): $H(A, B) = \max(\bar{H}(A, B), \bar{H}(B, A))$ for $A, B \in K_c(E)$, where $\bar{H}(A, B) = \sup_{a \in A} \inf_{b \in B} \|a - b\|$. By $\|A\|$ we denote the distance $H(A, 0)$. It can be proved that $(K_c(E), H)$ is a Polish metric space.

By $C_I = C(I, K_c(E))$ we denote the space of all H -continuous set-valued mappings. In this space we consider metric ρ of uniform convergence:

$$\rho(X, Y) := \sup_{0 \leq t \leq T} H(X(t), Y(t)), \text{ for } X, Y \in C_I.$$

Then we have a Polish metric space.

Let $(\Omega, \mathfrak{F}, \mathfrak{F}_t, P)_{t \in I}$ be a given complete filtered probability space satisfying the usual conditions. We recall the notion of a multivalued \mathfrak{F}_t -adapted stochastic process. The family of set-valued mappings $X = (X_t)_{t \in I}$ is said to be a *multivalued \mathfrak{F}_t -adapted stochastic process* if for every $t \in I$, the mapping $X_t: \Omega \rightarrow K_c(E)$ is \mathfrak{F}_t -measurable, i.e., $\{\omega: X_t \cap V \neq \emptyset\} \in \mathfrak{F}_t$, for every open set $V \subset E$ (see e.g., [7]). It can be noted that V can be chosen as a closed or Borel subset. If the mapping $t \rightarrow X_t(\omega)$ is H -continuous with probability one (P.1) then we say it has *continuous paths*. In this case, the set-valued process X can be thought as random element $X: \Omega \rightarrow C_I$. Let (X_n) be a sequence of random elements with values in metric space (S, ρ) . Then we say that X_n converges in probability to the random element $X: \Omega \rightarrow S$ ($X_n \xrightarrow{P} X$), of for every $\epsilon > 0$, it holds true that $P(\rho(X_n, X) \geq \epsilon) \rightarrow 0$, as n tends to infinity. It is known (see e.g., [13]) that $X_n \xrightarrow{P} X$ if and only if every subsequence of (X_n) has a subsequence converging to X with probability one (P.1).

In the theory of differential equations in Banach space the notion of measure of noncompactness plays one of the central roles (see e.g., [1]). Let $B(E)$ denote a family of all nonempty and bounded subsets in E .

Definition 1: The mapping $\mathcal{N}: B(E) \rightarrow [0, \infty)$, defined by $\mathcal{N}(A) = \inf\{\epsilon > 0: A \text{ can be covered with a finite number of balls of radii } \leq \epsilon\}$, is called *Hausdorff (ball) measure of noncompactness*.

2. A Set-Valued Stochastic Equation and Stochastic Inclusion

We begin with the designation of restrictions imposed on F, U and σ . Let us assume that $F: I \times \Omega \times K_c(E) \rightarrow K_c(E)$, $U: \Omega \rightarrow K_c(E)$, and $\sigma: I \times \Omega \rightarrow E$ have the following properties:

- 1) F is an integrably bounded multifunction i.e. there exists a joint measurable function $m: I \times \Omega \rightarrow R_+$ such that $\int_0^T m(s, \omega) ds < \infty$ P.1 and $\|F(t, \omega, A)\| \leq m(t, \omega)$ P.1, t -a.e. $A \in K_c(E)$.
- 2) $F(t, \omega, \cdot)$ is H -continuous with P.1, t -a.e.
- 3) $F(t, \cdot, A)$ is \mathfrak{F}_t -adapted for every $t \in I$, $A \in K_c(E)$.
- 4) $F(\cdot, \cdot, A)$ is measurable for every $A \in K_c(E)$.
- 5) U is an \mathfrak{F}_0 -measurable multifunction.
- 6) $\sigma = (\sigma_t)$ is an \mathfrak{F}_t -adapted stochastic process for which $E \int_0^T \|\sigma_s\|^2 ds$ is finite.

Let us notice that under assumptions given above, for every $A \in K_c(E)$, the set-valued process

$$\Phi_t = U + \int_0^t F(s, A)ds + \int_0^t \sigma_s dw_s, t \in I,$$

is \mathcal{F}_t -adapted with values in $K_c(E)$. It is also clear that Φ has continuous “paths”.

We also assume the so-called “Kamke condition” imposed on multifunction F : for every $A_1, A_2, \dots \in K_c(E)$ one has

$$\mathcal{N}(\bigcup_{n \geq 1} F(t, A_n)) \leq k(t, \mathcal{N}(\bigcup_{n \geq 1} A_n)) \text{ with } P.1 \quad t \in I \text{ a.e.}, \tag{*}$$

where $k: I \times \Omega \times R \rightarrow R_+$ satisfies the following conditions:

- a) $k(t, \cdot, x)$ is \mathcal{F} -measurable for every $(t, x) \in I \times R_+$,
- b) $k(\cdot, \omega, \cdot)$ is a Kamke function (see e.g., [14]) with $P.1$.

Definition 2: A multivalued process $X = (X_t)_{t \in I}$ is said to be a *solution of (I)* if it satisfies multivalued stochastic equation (II).

Let us notice that without stochastic perturbation, equation (II) can be written as:

$$D_H X_t = F(t, X_t) \text{ P.1, } t\text{-a.e.}$$

$$X_0 = U \text{ P.1,}$$

where D_H denotes the Hukuchara derivative operator ([6]) for multifunctions.

Before stating the existence theorem to equation (II) let us recall its special case.

Theorem 1: ([11]) *Let F and U be multivalued mappings satisfying conditions 1)-4) and 5), respectively. Let us also suppose that F satisfies the “Kamke condition.” Then the multivalued random differential equation*

$$D_H X_t = F(t, X_t) \text{ with } P.1 \quad t \in I \text{ a.e.}$$

$$X_0 = U \text{ with } P.1$$

has at least one solution.

Remark: In fact, the existence of solutions to the above initial value problem is based on the fact that under these conditions there exists at least one solution to the multivalued equation $X_t = U + \int_0^t F(s, X_s)ds$ and on well-known connection between Aumann’s integral of set-valued mapping and its Hukuchara derivative via Radström Embedding Theorem (see e.g. [14]).

Theorem 2: *Let E be a Banach space such that its dual E^* is separable. If F, U and σ have properties 1)-6) and F satisfies the “Kamke condition” then there exists at least one solution of the equation (II).*

Proof: Let $\xi_t = \int_0^t \sigma_s dw_s$. Let $X_t^\wedge := X_t - \xi_t$, where X_t is a solution of (II), and $X_t^\wedge(\omega) = \{x^\wedge - \xi_t(\omega); x^\wedge \in X_t(\omega)\}$. The process X^\wedge satisfies the equation

$$X_t^\wedge = U + \int_0^t F^\wedge(s, X_s^\wedge)ds \text{ P.1, } t \in I, \tag{**}$$

where $F^\wedge(s, \omega, A) = F(s, \omega, A + \xi_s(\omega))$. The set-valued mapping F^\wedge meets properties

1)-4). By properties of measure of noncompactness it also satisfies (*) (cf. [1]). Hence, equation (II) has at least one solution if and only if equation (**) has one. By Theorem 1 (via Remark 1) the proof is completed.

Let us suppose now that $\Gamma: I \times \Omega \times E \rightarrow K_c(E)$ is a given set-valued mapping. Let us set $F(t, \omega, A) := \overline{\text{co}}\Gamma(t, \omega, A)$, $A \in K_c(E)$, where $\overline{\text{co}}B$ denotes the closed convex hull of the set B . It is noteworthy to observe the connections between solutions of equation (II), with $F = \overline{\text{co}}\Gamma$ and solutions of stochastic inclusion

$$x_t - x_s \in \int_s^t \Gamma(u, x_u) du + \int_s^t \sigma_u dw_u \text{ with } P.1, 0 \leq s \leq t \leq T \tag{II'}$$

$$x_0 \in U \text{ with } P.1.$$

We suppose that Γ is an integrable bounded multifunction such that:

- 1') $\Gamma(t, \omega, \cdot)$ is H -continuous with $P.1$, t -a.e.,
- 2') $\Gamma(t, \cdot, x)$ is \mathcal{F}_t -adapted for every $t \in I$, $x \in E$,
- 3') $\Gamma(\cdot, \cdot, x)$ is measurable for every $x \in E$,
- 4') $\forall A \subset S_r(U): \mathcal{N}(\Gamma(t, A)) \leq k(t, \mathcal{N}(A))$ $P.1$, $t \in I$,

where $S_r(U) = U + rB(0, 1)$ and $B(0, 1)$ is a closed unit ball in Banach space E , centered at zero.

Theorem 3: *Suppose that Γ satisfies conditions 1'-4'. If a multivalued stochastic process $X = (X_t)_{t \in I}$ is a solution of equation (II) with $F = \overline{\text{co}}\Gamma$ then there exists stochastic process $x = (x_t)$ being both a solution to stochastic inclusion (II') and the selection of X .*

Proof: Similarly, as above, let $\xi_t = \int_0^t \sigma_s dw_s$, $\widehat{\Gamma}(t, \omega, x) := \Gamma(t, \omega, x + \xi_t(\omega))$ and $\widehat{F}(t, \omega, A) := F(t, \omega, A + \xi_t(\omega))$. Then $\widehat{F} = \overline{\text{co}}\widehat{\Gamma}$. Let us notice than \widehat{F} also satisfies 1'-4'. Hence, by Corollary 1 [11], there exists at least one solution of equation

$$X_t^\wedge = U + \int_0^t \widehat{F}(s, X_s^\wedge) ds \text{ } P.1, t \in I.$$

Taking $X = X^\wedge + \xi$ we get a solution of equation (II), where $F = \overline{\text{co}}\Gamma$. Moreover, by Theorem 4 [11] there exists stochastic process, say $\widehat{x} = (\widehat{x}_t)$, being a selection of X^\wedge such that: $\widehat{x}_t - \widehat{x}_s \in \int_s^t \widehat{\Gamma}(u, \widehat{x}_u) du$ with $P.1$, $0 \leq s \leq t \leq T$, and $\widehat{x}_0 \in U$ $P.1$.

Consequently, there exists stochastic process $x = (x_t)$, as a selection of X , such that: $\widehat{x}_t = x_t - \xi_t$ with $P.1$. It remains to observe that x is a desired solution of inclusion (II').

3. Continuity Properties of Solutions

By $S(I \times \Omega)$ we denote the class of "simple" multivalued processes that can be expressed by: $X = \sum_{i=1}^n I_{D_i} C_i$, where the sets D_i , $i = 1, 2, \dots, n$ form a measurable partition of $I \times \Omega$ and $C_i \in K_c(E)$, $i = 1, 2, \dots, n$.

Lemma 1: *If $X = (X_t)_{t \in T}$ is a multivalued stochastic process with continuous*

“paths” then there exists a sequence $\{X_n\} \subseteq S(I \times \Omega)$ such that $\forall (t, \omega) \in I \times \Omega$: $\lim_{n \rightarrow \infty} H(X(t, \omega), X_n(t, \omega)) = 0$.

Proof: It follows directly from the fact that $K_c(E)$ is a separable metric space and Proposition 1.9 [15].

Let Λ be a metric space. Let us consider the multivalued mapping $F: I \times \Omega \times K_c(E) \times \Lambda \rightarrow K_c(E)$ such that:

- A1. For every fixed $A \in K_c(E)$ and $\lambda \in \Lambda$, $F(\cdot, \cdot, A, \lambda)$ is a measurable and integrably bounded multifunction.
- A2. The mapping $F(t, \omega, \cdot, \lambda)$ is with P.1 uniformly continuous with respect to $t \in I$ and $\lambda \in \Lambda$.

Definition 2: A multifunction F (with properties A1 and A2) is said to be *integrably continuous in probability (icp) at $\lambda_0 \in \Lambda$ with respect to a family $\mathcal{C} \subset K_c(E)$ ($\mathcal{C} \neq \emptyset$)* if

$$\forall C \in \mathcal{C}, \forall t \in I: \int_0^t F(s, C, \lambda) ds \xrightarrow{P} \int_0^t F(s, C, \lambda_0) ds$$

for $\lambda \rightarrow \lambda_0$.

The results presented below give characterizations of icp multifunctions. We use them to obtain the main theorem.

Lemma 2: *If F is an icp multifunction at λ_0 with respect to \mathcal{C} then for every $C \in \mathcal{C}$ one has: $\int_0^t F(s, C, \lambda_n) ds \rightarrow \int_0^t F(s, C, \lambda_0) ds$ P.1 uniformly in $t \in I$, for some sequence (λ_n) convergent to λ_0 .*

Proof: Let D be a set of rationals in I , $D = \{t_1, t_2, \dots\}$ and let (λ_n) be an arbitrary sequence of elements of Λ that converges to λ_0 . Fix $C \in \mathcal{C}$. Then for $t_1 \in D$, there exist a sequence $(\lambda_n(t_1))_n$, convergent to λ_0 and set $\Omega(t_1) \subset \Omega$, $P(\Omega(t_1)) = 1$, such that

$$\forall \omega \in \Omega(t_1): H\left(\int_0^{t_1} F(s, \omega, C, \lambda_n(t_1)) ds, \int_0^{t_1} F(s, \omega, C, \lambda_0) ds\right) \rightarrow 0, \text{ for } n \rightarrow \infty.$$

Similarly, for $t_2 \in D$ we can find a sequence $(\lambda_n(t_2))_n$ being a subsequence of $(\lambda_n(t_1))_n$ and $\Omega(t_2) \subset \Omega$, $P(\Omega(t_2)) = 1$ for which a similar convergence holds. Continuing this selection process we obtain the infinite table

$$\begin{matrix} \lambda_1(t_1) & \lambda_2(t_1) & \dots & \lambda_n(t_1) & \dots \\ \lambda_1(t_2) & \lambda_2(t_2) & \dots & \lambda_n(t_2) & \dots \\ \vdots & \vdots & & \vdots & \\ \lambda_1(t_n) & \lambda_2(t_n) & \dots & \lambda_n(t_n) & \dots \\ \vdots & \vdots & & \dots & \end{matrix} \tag{1}$$

By diagonal selection we can find a sequence $(\lambda_n)_n$ being a subsequence of each row of table (1) that converges to λ_0 . Let $\Omega_0 = \bigcap \{\Omega(t_n); n \geq 1\}$. Then $P(\Omega_0) = 1$. Moreover,

$$\forall \omega \in \Omega_0, \forall t \in D: H\left(\int_0^t F(s, \omega, C, \lambda_n) ds, \int_0^t F(s, \omega, C, \lambda_0) ds\right) \rightarrow 0, n \rightarrow \infty.$$

Since the set-valued process $J_t = \int_0^t F(s, C, \lambda) ds$, $t \in I$ has with P.1 uniformly continuous “paths”, we can find Ω'_0 , $P(\Omega'_0) = 1$ such that

$$\forall \omega \in \Omega'_0: \sup_{t \in I} H\left(\int_0^t F(s, \omega, C, \lambda_n) ds, \int_0^t F(s, \omega, C, \lambda_0) ds\right) \rightarrow 0, \text{ if } n \rightarrow \infty.$$

This completes the proof.

By \mathbb{B}_I we denote the σ -field of Borel subsets of I .

Lemma 3: *A multifunction F is icp at λ_0 with respect to family \mathcal{C} if and only if: $\forall C \in \mathcal{C}, \forall (\lambda_n) \subset \Lambda: \lambda_n \rightarrow \lambda_0, \exists (\lambda'_n) \subset (\lambda_n)$:*

$$H\left(\int_B F(s, C, \lambda'_n) ds, \int_B F(s, C, \lambda_0) ds\right) \rightarrow 0 \text{ P.1} \tag{2}$$

as $n \rightarrow \infty$, for every $B \in \mathbb{B}_I$.

Proof: Fix $C \in \mathcal{C}$ and let (λ_n) be an arbitrary sequence convergent to λ_0 . Then by Lemma 2, we can find its subsequence (λ'_n) and $\Omega_0: P(\Omega_0) = 1$ such that for every $\omega \in \Omega_0$ and $0 \leq s < t \leq T$,

$$\int_s^t F(u, \omega, C, \lambda'_n) du \rightarrow \int_s^t F(u, \omega, C, \lambda_0) du, \text{ as } n \rightarrow \infty. \tag{3}$$

Let $\mathcal{F} = \{[s, t]: 0 \leq s < t \leq T\}$ and

$$\mathcal{A} = \left\{ \bigcup_{i=1}^n R_i : R_i \in \mathcal{F}, R_i \cap R_j = \emptyset, i \neq j, i, j = 1, 2, \dots, n, n \geq 1 \right\}.$$

Since $\sigma(\mathcal{F}) = \sigma(\mathcal{A}) = \mathbb{B}_I$ and \mathcal{A} is a ring of subsets of I , then for every $\epsilon > 0$ and $B \in \mathbb{B}_I$, there exists $A \in \mathcal{A}$ such that $|B \Delta A| < \epsilon$ (c.f. e.g., Th. 11.4 [2]), where $| \cdot |$ is Lebesgue measure and $B \Delta A = (B \setminus A) \cup (A \setminus B)$. By integrably boundness of F we get:

$$\begin{aligned} H\left(\int_B F(s, C, \lambda'_n) ds, \int_B F(s, C, \lambda_0) ds\right) &\leq H\left(\int_A F(s, C, \lambda'_n) ds, \int_A F(s, C, \lambda_0) ds\right) \\ &+ \int_{B \Delta A} m(s, \omega) ds, \text{ for every } A \in \mathcal{A}. \end{aligned}$$

Then by (3), $\limsup_{n \rightarrow \infty} H\left(\int_B F(s, C, \lambda'_n) ds, \int_B F(s, C, \lambda_0) ds\right) \leq \int_{B \Delta A} m(s, \omega) ds$.

Taking A sufficiently close to B we claim (2). The converse is obvious.

Lemma 4: *A multifunction F is icp at λ_0 with respect to $K_c(E)$ if and only if F is icp at λ_0 with respect to $S(I \times \Omega)$.*

Proof: Let us assume that F is icp with respect to $K_c(E)$. Let $X \in S(I \times \Omega)$. Then there exist $C_1, C_2, \dots, C_r \in K_c(E)$ and a measurable partition $\{D_1, D_2, \dots, D_r\}$ of space $I \times \Omega$ such that $X = \sum_{i=1}^r I_{D_i} C_i$. Take C_1 and (λ_n) to be an arbitrary sequence convergent to λ_0 . Next let (λ_{n_k}) be any subsequence of (λ_n) . By Lemma 3 there exists a sequence $(\lambda'_{n,1})$ being a subsequence of (λ_{n_k}) and a subset $\Omega_{0,1} \subseteq \Omega$;

$P(\Omega_{0,1}) = 1$ such that:

$$\forall \omega \in \Omega_{0,1}, \forall B \in \mathbb{B}_I: \lim_{n \rightarrow \infty} H\left(\int_B F(s, \omega, C_1, \lambda'_{n,1}) ds, \int_B F(s, \omega, C_1, \lambda_0) ds\right) = 0.$$

Similarly, for C_2 we can extract a subsequence $(\lambda'_{n,2})$ from $(\lambda'_{n,1})$ and $\Omega_{0,2} \subseteq \Omega$ $P(\Omega_{0,2}) = 1$, with the desired property, and so on. Thus we obtain a sequence $(\lambda'_{n,r})$ which is a subsequence of $(\lambda'_{n,i}), i = 1, 2, \dots, r - 1$ and $\Omega_{0,r}, P(\Omega_{0,r}) = 1$, such that

$$\forall \omega \in \Omega_{0,r}, \forall B \in \mathbb{B}_I: \lim_{n \rightarrow \infty} \left(\int_B F(s, \omega, C_r, \lambda'_{n,r}) ds, \int_B F(s, \omega, C_r, \lambda_0) ds\right) = 0.$$

Let $\Omega_0 = \bigcap_{1 \leq i \leq r} \Omega_{0,i}$. For any $A \in \mathbb{B}_I \otimes \mathcal{F}$ and $\omega \in \Omega$, we define the set $(A)_\omega := \{t \in I: (t, \omega) \in A\}$. Then $(A)_\omega \in \mathbb{B}_I$. Let $\omega \in \Omega_0$. Then $X(\cdot, \omega) = \sum_{i=1}^r I_{(D_i)_\omega}(\cdot) C_i$ and $\{(D_i)_\omega: i = 1, 2, \dots, r\}$ is measurable partition of I . Hence, the following inequality holds:

$$\begin{aligned} & H\left(\int_0^t F(s, \omega, X_s, \lambda'_{n,r}) ds, \int_0^t F(s, \omega, X_s, \lambda_0) ds\right) \\ & \leq \sum_{i=1}^r H\left(\int_{(D_i)_\omega \cap [0,t]} F(s, \omega, C_i, \lambda'_{n,r}) ds, \int_{(D_i)_\omega \cap [0,t]} F(s, \omega, C_i, \lambda_0) ds\right). \end{aligned}$$

It remains to observe that each term of the above sum converges to zero as n tends to infinity.

The converse statement is obvious. It is enough to take $X := I_{I \times \Omega} C$, for $C \in K_c(E)$. This completes the proof.

By X^λ we denote a multivalued process being the solution of the equation

$$X_t = U + \int_0^t F(s, X_s, \lambda) ds + \int_0^t \sigma_s dw_s \quad P.1, t \in I, \lambda \in A. \tag{III}$$

Theorem 3: *Let us assume that F is an icp set-valued mapping at $\lambda_0 \in A$ with respect to $K_c(E)$. Then,*

- i) *if $X^\lambda \xrightarrow{P} X^{\lambda_0}$ then $\forall t \in I: \int_0^t F(s, X_s^\lambda, \lambda) ds \xrightarrow{P} \int_0^t F(s, X_s^{\lambda_0}, \lambda_0) ds, \lambda \rightarrow \lambda_0$,*
- ii) *if for every $A_1, A_2, \dots \in K_c(E)$ and $(\lambda_n); \lambda_n \rightarrow \lambda_0$ we have*

$$\mathcal{N}\left\{\bigcup_{n \geq 1} F(t, A_n, \lambda_n)\right\} \leq k\left(t, \mathcal{N}\left\{\bigcup_{n \geq 1} A_n\right\}\right) \text{ with } P.1 \ t \in I \text{ a.e., then } X^\lambda \xrightarrow{P} X^{\lambda_0}.$$

Proof: (i) Let (λ_n) be an arbitrary sequence convergent to λ_0 . Then its every subsequence contains a further subsequence, say, (λ'_n) , such that $X^{\lambda'_n} \xrightarrow{P} X^{\lambda_0}$ with P.1 in C_I . Take ω from an appropriate set (for which this convergence holds). By condition A2, for any $\epsilon > 0$, there exists $\delta > 0$ such that $H(F(t, C, \lambda'_n), F(t, D, \lambda'_n)) < \epsilon/4T$, for $n \in N, C, D \in K_c(E)$ whenever $H(C, D) < \delta$.

Let V_0 be an open neighborhood for λ_0 such that

$$\text{if } \lambda'_n \in V_0 \text{ then } \sup_{t \in I} H(X_t^{\lambda'_n}, X^{\lambda_0}) < \delta. \tag{4}$$

Let $(X_k^{\lambda_0})_k$ be a sequence of simple multifunctions (Lemma 1) convergent to X^{λ_0} for every $t \in I$ and $\omega \in \Omega$. Then for every $t \in I$ and $\lambda \in \Lambda$, we have:

$$\lim_k H(F(t, \omega, X_k^{\lambda_0}(t, \omega), \lambda), F(t, \omega, X_t^{\lambda_0}(\omega), \lambda)) = 0 \text{ P.1.}$$

Next by the Lebesgue Dominated Convergence Theorem (via integrably boundedness of F) we obtain that

$$\int_0^T H(F(s, X_k^{\lambda_0}(s), \lambda), F(s, X_s^{\lambda_0}(\omega), \lambda)) ds \rightarrow 0 \text{ P.1}$$

for every $\lambda \in \Lambda$. Hence by (4), after standard calculation we see that

$$\begin{aligned} & H\left(\int_0^t F(s, \omega, X_s^{\lambda_n}(\omega), \lambda'_n) ds, \int_0^t F(s, \omega, X_s^{\lambda_0}(\omega), \lambda_0) ds\right) \leq (3/4)\epsilon \\ & + H\left(\int_0^t F(s, \omega, X_k^{\lambda_0}(s, \omega), \lambda'_n) ds, \int_0^t F(s, \omega, X_k^{\lambda_0}(s, \omega), \lambda_0) ds\right), \end{aligned}$$

for $t \in I$, k sufficiently large and ω taken from an appropriate set of probability one.

By Lemma 4, multifunction F is icp at λ_0 with respect to $S(I \times \Omega)$. Hence there exists a sequence (λ''_n) being a subsequence of (λ'_n) , a subset of Ω of measure one such that for every $\epsilon > 0$ and appropriate ω we can find an open neighborhood V_1 of λ_0 with

$$H\left(\int_0^t F(s, \omega, X_k^{\lambda_0}(s, \omega), \lambda''_n) ds, \int_0^t F(s, \omega, X_k^{\lambda_0}(s, \omega), \lambda_0) ds\right) < \epsilon/4,$$

for $t \in I$ and $\lambda''_n \in V_1$. Therefore, taking n'' sufficiently large and $\lambda''_n \in V_0 \cap V_1$ we have:

$$H\left(\int_0^t F(s, \omega, X_s^{\lambda''_n}(\omega), \lambda''_n) ds, \int_0^t F(s, \omega, X_s^{\lambda_0}(\omega), \lambda_0) ds\right) < \epsilon$$

for $t \in I$. This completes the proof of part (i).

Proof of part (ii).

Let (λ_n) be a sequence convergent to λ_0 . Consider its arbitrary subsequence, denoted for simplicity by the same symbol. We define the multivalued mapping $\Pi: \Omega \rightarrow 2^{C_I}$ by

$$\Pi(\omega) = \{X \in C_I: X^{\lambda_n} \rightarrow X \text{ in } C_I \text{ for some sequence } (\lambda'_n), (\lambda'_n) \subseteq (\lambda_n)\}.$$

By the assumption of the integrably boundness of F it follows that

$$\forall n \in N, \forall 0 \leq s \leq t \leq T: H(X_t^{\lambda_n}, X_s^{\lambda_n}) \leq \int_s^t m(u) du \text{ with P.1.}$$

Thus the sequence (X^{λ_n}) is equicontinuous in C_I with $P.1$. Similarly, (compare [14]) by assumption (iii), it can be proved that $\bigcup_{n \geq 1} \{X_t^{\lambda_n}\}$ is a relatively compact subset of E , for every $t \in I$ with $P.1$. Thus, by Ascoli Theorem we claim that the sequence (X^{λ_n}) is relatively compact (with $P.1$). Hence the multifunction $\Pi \neq \emptyset$ $P.1$ and has closed values. Moreover, we claim that Π is measurable. To see this, let $\Omega_0 := \{\omega: \Pi(\omega) \text{ is closed subset of } C_I\}$. For $X \in C_I$ we consider a mapping $\Omega_0 \ni \omega \rightarrow \text{Dist}(X, \Pi(\omega))$, where $\text{Dist}(X, \Pi(\omega)) = \inf_{Y \in \Pi(\omega)} \rho(X, Y)$. Fix $r > 0$.

Then $\{\omega: \text{Dist}(X, \Pi(\omega)) < r\} = \{\omega: \exists Y \in \Pi(\omega): Y \in B_r(X)\}$, where $B_r(X) := \{Y \in C_I: \rho(X, Y) < r\}$. Let $\{t_k\}$ be a sequence of rationals in I . Then we get:

$$\begin{aligned} \{\omega: \text{dist}(X, \Pi(\omega)) < r\} &= \{\omega: \Pi(\omega) \cap B_r(X) \neq \emptyset\} \\ &= \bigcup_{m \geq 1} \bigcap_{l \geq 1} \bigcup_{j \geq l} \bigcap_{k \geq 1} \{\omega: X_{t_k}^{\lambda_{nj}}(\omega) \cap B_{r-1/m}(X) \neq \emptyset\}. \end{aligned}$$

Since $X_{t_k}^{\lambda_{nj}}$ is an \mathfrak{F}_{t_k} -measurable multifunction then the last set above belongs to σ -field \mathfrak{F} , which yields the \mathfrak{F} -measurability of Π (see, e.g. [4]). Thus, by Kuratowski and Ryll-Nardzewski Selection Theorem [10], there exists a measurable selection \hat{X} of Π ; $\hat{X} \in \Pi$ $P.1$. The definition of Π implies then that $X^{\lambda'_n} \rightarrow \hat{X}$ $P.1$ in C_I , for some sequence (λ'_n) tending to λ_0 and this yields convergence in probability in C_I . Finally, we claim that \hat{X} is a solution of (III). Indeed, let us notice that

$$\begin{aligned} &H(X_t, U + \int_0^t F(s, X_s, \lambda_0) ds + \int \sigma_s dw_s) \\ &\leq H(X_t, X_t^{\lambda'_n}) + H(\int_0^t F(s, X_s^{\lambda'_n}, \lambda'_n) ds, \int_0^t F(s, X_s, \lambda_0) ds), \end{aligned}$$

with $P.1$ and for $t \in I$.

Since the first term above converges to zero then by (i) the second term converges to zero as well. This completes the proof.

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