## A GALERKIN METHOD OF $O(h^2)$ FOR SINGULAR BOUNDARY VALUE PROBLEMS

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Received 8 May 2000 and in revised form 2 August 2000

We describe a Galerkin method with special basis functions for a class of singular twopoint boundary value problems. The convergence is shown which is of  $O(h^2)$  for a certain subclass of the problems.

2000 Mathematics Subject Classification: 65L10.

**1. Introduction.** We consider the class of singular two-point boundary value problems:

$$-\frac{1}{p}(pu')' + f(x,u) = 0, \quad 0 < x < 1,$$
  
(pu')(0<sup>+</sup>) = 0,  $u(1) = 0.$  (1.1)

We assume that the real-valued function p satisfies

$$p \ge 0, \quad p^{-1} \in L^1_{\text{loc}}(0,1], \qquad p^{-1} \notin L^1_{\text{loc}}([0,\alpha)) \quad \text{for any } \alpha > 0,$$
 (1.2)

$$\int_{x}^{1} p^{-1} \in L_{p}^{1}(0,1), \text{ that is, } \int_{0}^{1} \left( \int_{x}^{1} \frac{1}{p(s)} ds \right) p(x) dx < \infty.$$
(1.3)

Note that (1.3) is clearly satisfied when p is an increasing function on (0,1). We also assume that f(x, u) is continuous in u such that for any real  $u, f(\cdot, u) \in L_p^{\infty}(0, 1)$ ,

$$q(u,v,x) \equiv \frac{f(x,u) - f(x,v)}{u - v} \ge 0 \quad \text{for } -\infty < u, \ v < \infty, \ u \neq v.$$
(1.4)

The singular two-point boundary value problems of the form (1.1) occur frequently in many applied problems, for example, in the study of electrohydrodynamics [9], in the theory of thermal explosions [4], in the separation of variables in partial differential equations [11]; see also [1]. There is a considerable literature on the numerical methods for the singular boundary value problems. Special finite difference methods were considered in Chawla et al. [5]. The Galerkin method for singular problems was considered in Ciarlet et al. [6], Eriksson et al. [7], Jesperson [8]. Ciarlet et al. [6] assumed that p(x) > 0 on (0,1),  $p \in C^1(0,1)$ , and  $p^{-1} \in L^1(0,1)$ . In this paper, we address the problem with  $p^{-1} \notin L^1(0,1)$ , and we assume that  $p \ge 0$ ,  $p^{-1} \in L^1_{loc}(0,1)$ ; see (1.2) and (1.3). We investigate a Galerkin method with the same special patch functions considered by Ciarlet et al. [6] and we show that the method is of  $O(h^2)$  when *p* is an increasing function on (0,1). The linear case with more general settings was considered in [2] and a nonlinear case was considered in [3]. The special case considered here requires a different approach to establish its order of convergence and to obtain the optimal order of convergence  $h^2$  under an easily checked condition on *p*; namely that *p* is increasing on [0,1].

**2. Preliminaries.** Let I = (0,1) and  $H = L_p^2(I)$  denote the weighted Hilbert space with the inner product

$$\langle u, v \rangle_H = \int_I u(x) v(x) p(x) dx.$$
(2.1)

Also let *V* be the Hilbert space consisting of functions  $u \in L_p^2(I)$  which are locally absolutely continuous on *I*, u(1) = 0, and  $u' \in L_p^2(I)$ . The inner product on the space *V* is defined by

$$\langle u, v \rangle_V = \int_I u'(x) v'(x) p(x) dx.$$
(2.2)

The variational formulation of the problem (1.1) now follows:

Find  $u \in V$  such that

$$a(u,v) = 0 \quad \forall v \in V, \tag{2.3}$$

where

$$a(u,v) \equiv \langle u,v \rangle_V + \int_0^1 f(x,u(x))v(x)p(x)dx.$$
(2.4)

It can be shown [3] that (1.1) and (2.3) have unique absolutely continuous (in [0,1]) solutions and that the weak solution of (2.3) coincides with the strong solution of (1.1).

**3.** The Galerkin approximation and convergence results. Let  $\pi : 0 = x_0 < x_1 < \cdots < x_{N+1} = 1$  be a mesh on the interval [0,1] and, for  $i = 1, 2, \dots, N$ , define the patch functions

$$\gamma_{i}(x) = \begin{cases}
\gamma_{i}^{-}(x) & \text{if } x_{i-1} \leq x \leq x_{i}, \\
\gamma_{i}^{+}(x) & \text{if } x_{i} \leq x \leq x_{i+1}, \\
0 & \text{otherwise,} 
\end{cases}$$
(3.1)

where

$$r_{i}^{-}(x) = 1,$$

$$r_{i}^{-}(x) = \frac{\int_{x_{i-1}}^{x} (1/p(s)) ds}{\int_{x_{i-1}}^{x_{i}} (1/p(s)) ds}, \quad i = 2, 3, \dots, N,$$

$$r_{i}^{+}(x) = \frac{\int_{x}^{x_{i+1}} (1/p(s)) ds}{\int_{x_{i}}^{x_{i+1}} (1/p(s)) ds}, \quad i = 1, 2, \dots, N.$$
(3.2)

Define the discrete subspace  $V_N$  of V by

$$V_N = \text{span} \{ r_i \}_{i=1}^N.$$
(3.3)

The discrete version of the weak problem (2.3) reads:

Find  $u^G \in V_N$  such that

$$a(u^G, v_N) = 0 \quad \forall v_N \in V_N. \tag{3.4}$$

Note that (3.4) has a unique solution  $u^G \in AC[0,1]$ . It follows from (2.3) and (3.4) that

$$\langle u - u^G, v_N \rangle_V + \int_0^1 \frac{f(x, u) - f(x, u^G)}{u - u^G} (u - u^G) v_N p = 0.$$
 (3.5)

Let  $\tilde{q}(x)$  be the unique function (because *u* and  $u^G$  are unique) defined by

$$\widetilde{q}(x) \equiv \begin{cases} \frac{f(x, u(x)) - f(x, u^{G}(x))}{u(x) - u^{G}(x)}, & u(x) \neq u^{G}(x) \\ 0, & u(x) = u^{G}(x). \end{cases}$$
(3.6)

We assume that f is such that

$$C_{\widetilde{q}} := \int_0^1 \widetilde{q}(x) \int_x^1 \frac{ds}{p(s)} p(x) dx < \infty.$$
(3.7)

This is the case for example if f satisfies a Lipschitz condition in its second argument (see (1.3)). We can now state our results on the convergence of the Galerkin solution  $u^G$  to the weak solution u of (2.3).

**THEOREM 3.1.** The following relation holds:

$$||u^{G} - u||_{\infty} \le (1 + 4C_{\widetilde{q}})||f(\cdot, u(\cdot))||_{\infty}\ell(\pi_{N}),$$
(3.8)

where  $\ell(\pi_N)$  is given by

$$\ell(\pi_N) = \max_{0 \le i \le N} \int_{x_i}^{x_{i+1}} \left( \int_s^{x_{i+1}} \frac{1}{p(t)} dt \right) p(s) ds.$$
(3.9)

**COROLLARY 3.2.** If *p* is increasing then the method is  $O(h^2)$  where

$$h = \max_{0 \le i \le N} (x_{i+1} - x_i).$$
(3.10)

**REMARK 3.3.** The absolute continuity of the solution u and the continuity of f imply that  $||f(\cdot, u(\cdot))||_{\infty} < \infty$  in the above expression for the error.

4. Proof of the results. Let

$$u^G(x) = \sum_{i=1}^N \alpha_i r_i(x) \tag{4.1}$$

be the Galerkin approximation and  $u^I$  be the  $V_N$ -interpolant of the solution u given by

$$u^{I}(x) = \sum_{i=1}^{N} u_{i} r_{i}(x), \qquad (4.2)$$

where  $u_i = u(x_i)$  and  $r_i$  is given by (3.1), i = 1,...,N. We note here that  $u^I$  is the orthogonal projection of u with respect to the inner product  $\langle \cdot, \cdot \rangle_V$ :

$$\langle u - u^I, v_N \rangle_V = 0 \tag{4.3}$$

for all  $v_N \in V_N$ . The following relation is also easily checked (using (3.5) and (4.3))

$$\langle u^G - u^I, v_N \rangle_V = \langle \widetilde{q}(u - u^G), v_N \rangle_p, \qquad (4.4)$$

for all  $v_N \in V_N$ . We have the following lemma.

**LEMMA 4.1.** The following relation holds:

$$\|\boldsymbol{u} - \boldsymbol{u}^{I}\|_{\infty} \le \|f(\cdot, \boldsymbol{u}(\cdot))\|_{\infty} \boldsymbol{\ell}(\boldsymbol{\pi}_{N}).$$

$$(4.5)$$

**PROOF.** For any  $x \in [x_i, x_{i+1}], i = 0, 1, ..., N$ 

$$u(x) - u^{I}(x) \le \int_{x_{i}}^{x_{i+1}} |g(s)| \left( \int_{s}^{x_{i+1}} \frac{dt}{p(t)} \right) p(s) ds,$$
(4.6)

where g(s) = -f(s, u(s)). To see this we consider two cases: i = 0 and  $i \ge 1$ .

For i = 0, that is, for  $x \in [0, x_1]$  we have

$$u(x) - u^{I}(x) = u(x) - u(x_{1})$$

$$= \int_{x}^{x_{1}} \frac{1}{p(s)} \int_{0}^{s} g(t)p(t)dt$$

$$= \int_{x}^{x_{1}} \frac{ds}{p(s)} \int_{0}^{x} g(s)p(s)ds + \int_{x}^{x_{1}} g(s)p(s) \int_{s}^{x_{1}} \frac{dt}{p(t)}ds$$

$$\leq \int_{0}^{x} |g(s)|p(s) \int_{s}^{x_{1}} \frac{dt}{p(t)}ds + \int_{x}^{x_{1}} |g(s)|p(s) \int_{s}^{x_{1}} \frac{dt}{p(t)}ds$$

$$= \int_{0}^{x_{1}} |g(s)| \int_{s}^{x_{1}} \frac{dt}{p(t)}p(s)ds.$$
(4.7)

364

It can be shown, using the fact  $\sum_{i=1}^{N} r_i(x) = 1$  and integrating by parts, that for  $x \in [x_i, x_{i+1}]$ , i = 1, ..., N,

$$\begin{split} u(x) - u^{I}(x) \\ &= r_{i}^{+}(x) \int_{x_{i}}^{x} \left( \int_{x_{i}}^{s} \frac{dt}{p(t)} \right) g(s) p(s) ds + r_{i+1}^{-}(x) \int_{x}^{x_{i+1}} \left( \int_{s}^{x_{i+1}} \frac{dt}{p(t)} \right) g(s) p(s) ds \\ &= \frac{\int_{x}^{x_{i+1}} ds / p(s)}{\int_{x_{i}}^{x_{i+1}} ds / p(s)} \int_{x_{i}}^{x} \left( \int_{x_{i}}^{s} dt / p(t) \right) g(s) p(s) ds \\ &+ \frac{\int_{x_{i}}^{x} ds / p(s)}{\int_{x_{i}}^{x_{i+1}} ds / p(s)} \int_{x}^{x_{i+1}} \int_{s}^{x_{i+1}} \frac{dt}{p(t)} g(s) p(s) ds \\ &\leq \left( \int_{x}^{x_{i+1}} \frac{ds}{p(s)} \right) \int_{x_{i}}^{x} |g(s)| p(s) ds + \int_{x}^{x_{i+1}} \int_{s}^{x_{i+1}} \frac{dt}{p(t)} |g(s)| p(s) ds \\ &\leq \int_{x_{i}}^{x} |g(s)| p(s) \int_{s}^{x_{i+1}} \frac{dt}{p(t)} ds + \int_{x}^{x_{i+1}} \int_{s}^{x_{i+1}} \frac{dt}{p(t)} |g(s)| p(s) ds \\ &= \int_{x_{i}}^{x_{i+1}} |g(s)| \int_{s}^{x_{i+1}} \frac{dt}{p(t)} p(s) ds \end{split}$$

$$(4.8)$$

The result thus follows.

**PROOF OF THEOREM 3.1.** In (4.4) taking  $v_N = r_i$  for i = 1, ..., N, we obtain

$$\langle u^G - u^I, r_i \rangle_V = \langle \tilde{q}(u - u^G), r_i \rangle_p, \qquad (4.9)$$

which can be written as

$$\sum_{j=1}^{N} \left[ \langle r_j, r_i \rangle_V + \langle \widetilde{q}r_j, r_i \rangle_p \right] (\alpha_j - u_j) = \langle \widetilde{q}(u - u^I), r_i \rangle_p.$$
(4.10)

This gives the system

$$(\mathbf{A} + \mathbf{Q})\mathbf{e} = \mathbf{d},\tag{4.11}$$

where  $\mathbf{A} = (a_{ij}) = (\langle \mathbf{r}_i, \mathbf{r}_j \rangle_V)$  is a symmetric and tridiagonal matrix given by

$$a_{11} = \frac{1}{\int_{x_1}^{x_2} (1/p(s)) ds},$$
  

$$a_{ii} = \frac{1}{\int_{x_{i-1}}^{x_i} (1/p(s)) ds} + \frac{1}{\int_{x_i}^{x_{i+1}} (1/p(s)) ds}, \quad i = 2, \dots, N,$$
  

$$a_{i,i+1} = -\frac{1}{\int_{x_i}^{x_{i+1}} (1/p(s)) ds}, \quad i = 1, \dots, N-1,$$
  
(4.12)

$$\mathbf{Q} = (q_{ij}) = (\langle \tilde{q}r_j, r_i \rangle_p), \, \mathbf{e} = (e_i) = (\alpha_i - u_i), \, \text{and} \, \mathbf{d} = (d_i) \text{ is given by} 
d_1 = \int_{x_0}^{x_1} h(s)p(s)ds + \frac{\int_{x_1}^{x_2} h(s)p(s)\int_s^{x_2} (dt/p(t))ds}{\int_{x_1}^{x_2} dt/p(t)} 
d_i = \frac{\int_{x_{i-1}}^{x_i} h(s)p(s)\int_{x_{i-1}}^{s} (dt/p(t))ds}{\int_{x_{i-1}}^{x_i} dt/p(t)} + \frac{\int_{x_i}^{x_{i+1}} h(s)p(s)\int_s^{x_{i+1}} (dt/p(t))ds}{\int_{x_i}^{x_i} dt/p(t)}, \quad i > 1,$$
(4.13)

where h(s) stands for  $\tilde{q}(s)(u(s) - u^{I}(s))$ . Now **A** is an **M**-matrix,  $q_{ij} \ge 0$  (see (1.4)),  $q_{ij} < -a_{ij}(i \ne j)$  for sufficiently small mesh size and therefore,  $\mathbf{A} + \mathbf{Q}$  is an **M**-matrix with  $(\mathbf{A} + \mathbf{Q})^{-1} \le \mathbf{A}^{-1}$  (see Ortega [10]). Thus  $|\mathbf{e}| \le \mathbf{A}^{-1} |\mathbf{d}|$ . The inverse of the matrix **A**, denoted by  $\mathbf{B} = (b_{ij})$ , can be explicitly written as

$$b_{ij} = \begin{cases} \int_{x_j}^1 \frac{ds}{p(s)} & \text{if } i \le j, \\ \int_{x_i}^1 \frac{ds}{p(s)} & \text{if } i \ge j. \end{cases}$$

$$(4.14)$$

Therefore,

$$|e_{i}| \leq \sum_{j=1}^{N} b_{ij} |d_{j}|$$

$$= \sum_{j=1}^{i} \int_{x_{i}}^{1} \frac{ds}{p(s)} |d_{j}| + \sum_{j=i+1}^{N} \int_{x_{j}}^{1} \frac{ds}{p(s)} |d_{j}| \qquad (4.15)$$

$$\leq \sum_{j=1}^{N} \int_{x_{j}}^{1} \frac{ds}{p(s)} |d_{j}|.$$

We see that

$$\begin{split} \int_{x_1}^1 \frac{ds}{p(s)} \left| d_1 \right| &\leq \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} \left| h(s) \right| p(s) ds + \int_{x_1}^1 \frac{ds}{p(s)} \frac{\int_{x_1}^{x_2} \left| h(s) \right| p(s) \int_{s}^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &= \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} \left| h(s) \right| p(s) ds + \int_{x_1}^{x_2} \frac{ds}{p(s)} \frac{\int_{x_1}^{x_2} \left| h(s) \right| p(s) \int_{s}^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &+ \int_{x_2}^1 \frac{ds}{p(s)} \frac{\int_{x_1}^{x_1} \left| h(s) \right| p(s) \int_{s}^{x_2} (dt/p(t)) ds}{\int_{x_1}^{x_2} dt/p(t)} \\ &\leq \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} \left| h(s) \right| p(s) ds + \int_{x_1}^{x_2} \left| h(s) \right| p(s) \int_{s}^{x_2} \frac{dt}{p(t)} ds \\ &+ \int_{x_2}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} \left| h(s) \right| p(s) ds \\ &= \int_{x_1}^1 \frac{ds}{p(s)} \int_{x_0}^{x_1} \left| h(s) \right| p(s) ds + \int_{x_1}^{x_2} \left| h(s) \right| p(s) \int_{s}^1 \frac{dt}{p(t)} ds \\ &\leq \int_{x_0}^{x_1} \left| h(s) \right| p(s) \int_{s}^1 \frac{dt}{p(t)} ds + \int_{x_1}^{x_2} \left| h(s) \right| p(s) \int_{s}^1 \frac{dt}{p(t)} ds. \end{split}$$

$$(4.16)$$

Also for j = 2, ..., N, by a similar approach, we have

$$\int_{x_{j}}^{1} \frac{ds}{p(s)} \left| d_{j} \right| \leq \int_{x_{j}}^{1} \frac{ds}{p(s)} \int_{x_{j-1}}^{x_{j}} \left| h(s) \right| p(s) ds 
+ \int_{x_{j}}^{1} \frac{ds}{p(s)} \frac{\int_{x_{i}}^{x_{i+1}} \left| h(s) \right| p(s) \int_{s}^{x_{i+1}} \left( dt/p(t) \right) ds}{\int_{x_{i}}^{x_{i+1}} dt/p(t)} 
\leq \int_{x_{j-1}}^{x_{j}} \left| h(s) \right| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds + \int_{x_{j}}^{x_{j+1}} \left| h(s) \right| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds.$$
(4.17)

Substituting these two inequalities in (4.15) we obtain

$$\begin{aligned} |e_{i}| &\leq \int_{x_{0}}^{x_{N}} |h(s)| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds + \int_{x_{1}}^{x_{N+1}} |h(s)| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds \\ &\leq 2 \int_{0}^{1} |h(s)| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds \\ &= 2 \int_{0}^{1} |\widetilde{q}(s) (u(s) - u^{I}(s))| p(s) \int_{s}^{1} \frac{dt}{p(t)} ds. \end{aligned}$$

$$(4.18)$$

Thus using (3.7), we have

$$\max_{1 \le i \le N} |\alpha_i - u_i| \le 2C_{\widetilde{q}} ||u - u^I||_{\infty}.$$

$$(4.19)$$

It can be shown that

$$||u^{G} - u^{I}||_{\infty} \le 2 \max_{1 \le i \le N} |\alpha_{i} - u_{i}|.$$
(4.20)

Therefore,

$$\begin{aligned} ||u - u^{G}||_{\infty} &\leq ||u - u^{I}||_{\infty} + ||u^{G} - u^{I}||_{\infty} \\ &\leq ||u - u^{I}||_{\infty} + 2 \max_{1 \leq i \leq N} ||u_{i} - \alpha_{i}| \\ &\leq (1 + 4C_{\widetilde{q}}) ||u - u^{I}||_{\infty}. \end{aligned}$$
(4.21)

The result thus follows from Lemma 4.1.

**5. Example.** In this section we give examples which are solved by the Galerkin method just described above with equal mesh size h. We then compare the results with the actual solutions.

**EXAMPLE 5.1.** We consider the boundary value problem

$$-\frac{1}{x}(xu')' + e^u = 0, \quad 0 < x < 1, \qquad u'(0) = u(1) = 0.$$
(5.1)

The exact solution is known:  $u(x) = 2\ln((1+\beta)/(1+\beta x^2))$ ,  $\beta = -5+2\sqrt{6}$ . It is seen that  $||u^G - u||_{\infty} = 0.188845 \times 10^{-2}$  for h = 0.1 and  $||u^G - u||_{\infty} = 0.189 \times 10^{-4}$  for h = 0.01. According to the Corollary 3.2 the method is  $O(h^2)$  which is reflected in these results.

**EXAMPLE 5.2.** We consider the equation

$$-\frac{1}{x^{\alpha}}(x^{\alpha}u')' + \frac{\beta^2 x^{2\beta-2}}{5(4+x^{\beta})}e^u = \frac{\beta(\alpha+\beta-1)x^{\beta-2}}{4+x^{\beta}}$$

$$(x^{\alpha}u')(0^+) = 0, \qquad u(1) = 0.$$
(5.2)

The exact solution is  $u = \ln 5 - \ln(4 + x^{\beta})$ . The following results were obtained:

$\alpha$ $\beta$ $h$ $\ u^G - u\ _{\infty}$ 0.5         2         0.02         1.0299×10 <sup>-4</sup> 0.5         2         0.01         2.6147×10 <sup>-5</sup> 1.0         2         0.02         9.9647×10 <sup>-5</sup> 1.0         2         0.01         2.4913×10 <sup>-5</sup> 2.0         6         0.02         3.4133×10 <sup>-4</sup> 2.0         6         0.01         8.6170×10 <sup>-5</sup>				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	α	β	h	$\ u^G - u\ _{\infty}$
$1.0$ $2$ $0.02$ $9.9647 \times 10^{-5}$ $1.0$ $2$ $0.01$ $2.4913 \times 10^{-5}$ $2.0$ $6$ $0.02$ $3.4133 \times 10^{-4}$	0.5	2	0.02	$1.0299 \times 10^{-4}$
$1.0$ $2$ $0.01$ $2.4913 \times 10^{-5}$ $2.0$ $6$ $0.02$ $3.4133 \times 10^{-4}$	0.5	2	0.01	$2.6147 \times 10^{-5}$
2.0 6 0.02 $3.4133 \times 10^{-4}$	1.0	2	0.02	$9.9647 \times 10^{-5}$
	1.0	2	0.01	$2.4913 \times 10^{-5}$
2.0 6 0.01 $8.6170 \times 10^{-5}$	2.0	6	0.02	$3.4133 \times 10^{-4}$
	2.0	6	0.01	$8.6170 \times 10^{-5}$

TABLE 5.1

**REMARK 5.3.** Our method does not differentiate between  $0 < \alpha < 1$  and  $\alpha \ge 1$  as is the case in many articles in the literature.

**ACKNOWLEDGEMENT.** The authors acknowledge the excellent research facilities available at King Fahd University of Petroleum and Minerals, Saudi Arabia.

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