# ON THE FRESNEL SINE INTEGRAL AND THE CONVOLUTION 

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The Fresnel sine integral $S(x)$, the Fresnel cosine integral $C(x)$, and the associated functions $S_{+}(x), S_{-}(x), C_{+}(x)$, and $C_{-}(x)$ are defined as locally summable functions on the real line. Some convolutions and neutrix convolutions of the Fresnel sine integral and its associated functions with $x_{+}^{r}, x^{r}$ are evaluated.

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1. Introduction. The Fresnel integrals occur in the diffraction theory and they are of two kinds: the Fresnel integral $S(x)$ with a sine in the integral and the Fresnel integral $C(x)$ with a cosine in the integral.

The Fresnel sine integral $S(x)$ is defined by

$$
\begin{equation*}
S(x)=\sqrt{\frac{2}{\pi}} \int_{0}^{x} \sin u^{2} d u \tag{1.1}
\end{equation*}
$$

(see [5]) and the associated functions $S_{+}(x)$ and $S_{-}(x)$ are defined by

$$
\begin{equation*}
S_{+}(x)=H(x) S(x), \quad S_{-}(x)=H(-x) S(x) . \tag{1.2}
\end{equation*}
$$

The Fresnel cosine integral $C(x)$ is defined by

$$
\begin{equation*}
C(x)=\sqrt{\frac{2}{\pi}} \int_{0}^{x} \cos u^{2} d u \tag{1.3}
\end{equation*}
$$

(see [5]) and the associated functions $C_{+}(x)$ and $C_{-}(x)$ are defined by

$$
\begin{equation*}
C_{+}(x)=H(x) C(x), \quad C_{-}(x)=H(-x) C(x), \tag{1.4}
\end{equation*}
$$

where $H$ denotes Heaviside's function.
We define the function $L_{r}(x)$ by

$$
\begin{equation*}
L_{r}(x)=\int_{0}^{x} u^{r} \sin u^{2} d u \tag{1.5}
\end{equation*}
$$

for $r=0,1,2, \ldots$ In particular, we have

$$
\begin{align*}
& L_{0}(x)=\sqrt{\frac{\pi}{2}} S(x) \\
& L_{1}(x)=\frac{1}{2}-\frac{1}{2} \cos x^{2}  \tag{1.6}\\
& L_{2}(x)=\frac{1}{4} \sqrt{2} \sqrt{\pi} C(x)-\frac{1}{2}\left(\cos x^{2}\right) x
\end{align*}
$$

We define the functions $\sin _{+} x, \sin _{-} x, \cos _{+} x$, and $\cos _{-} x$ by

$$
\begin{align*}
\sin _{+} x & =H(x) \sin x, & & \sin -x=H(-x) \sin x, \\
\cos _{+} x & =H(x) \cos x, & & \cos -x=H(-x) \cos x . \tag{1.7}
\end{align*}
$$

2. Convolution products. The classical definition for the convolution product of two functions $f$ and $g$ is as follows.

Definition 2.1. Let $f$ and $g$ be functions. Then the convolution $f * g$ is defined by

$$
\begin{equation*}
(f * g)(x)=\int_{-\infty}^{\infty} f(t) g(x-t) d t \tag{2.1}
\end{equation*}
$$

for all points $x$ for which the integral exists.
If the classical convolution $f * g$ of two functions $f$ and $g$ exists, then $g * f$ exists and

$$
\begin{equation*}
f * g=g * f \tag{2.2}
\end{equation*}
$$

Further, if $(f * g)^{\prime}$ and $f * g^{\prime}\left(\right.$ or $\left.f^{\prime} * g\right)$ exist, then

$$
\begin{equation*}
(f * g)^{\prime}=f * g^{\prime} \quad\left(\text { or } f^{\prime} * g\right) \tag{2.3}
\end{equation*}
$$

The classical definition of the convolution can be extended to define the convolution $f * g$ of two distributions $f$ and $g$ in $\mathscr{D}^{\prime}$ with the following definition, see [4].

DEFINITION 2.2. Let $f$ and $g$ be distributions in $\mathscr{D}^{\prime}$. Then the convolution $f * g$ is defined by the equation

$$
\begin{equation*}
\langle(f * g)(x), \varphi(x)\rangle=\langle f(y),\langle g(x), \varphi(x+y)\rangle\rangle \tag{2.4}
\end{equation*}
$$

for arbitrary $\varphi$ in $\mathscr{D}^{\prime}$, provided that $f$ and $g$ satisfy either of the following conditions:
(a) either $f$ or $g$ has bounded support,
(b) the supports of $f$ and $g$ are bounded on the same side.

It follows that if the convolution $f * g$ exists by this definition, then (2.2) and (2.3) are satisfied.

Theorem 2.3. The convolution $\left(\sin _{+} x^{2}\right) * x_{+}^{r}$ exists and

$$
\begin{equation*}
\left(\sin _{+} x^{2}\right) * x_{+}^{r}=\sum_{i=0}^{r}\binom{r}{i}(-1)^{r-i} L_{r-i}(x) x_{+}^{i} \tag{2.5}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. It is obvious that $\left(\sin _{+} x^{2}\right) * x_{+}^{r}=0$ if $x<0$. When $x>0$, we have

$$
\begin{align*}
\left(\sin _{+} x^{2}\right) * x_{+}^{r} & =\int_{0}^{x} \sin t^{2}(x-t)^{r} d t \\
& =\sum_{i=0}^{r}\binom{r}{i}(-1)^{r-i} L_{r-i}(x) x^{i}, \tag{2.6}
\end{align*}
$$

thus proving (2.5).
Corollary 2.4. The convolution $\left(\sin _{-} x^{2}\right) * x_{-}^{r}$ exists and

$$
\begin{equation*}
\left(\sin _{-} x^{2}\right) * x_{-}^{r}=\sum_{i=0}^{r}\binom{r}{i} L_{r-i}(x) x_{-}^{i} \tag{2.7}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. Equation (2.7) follows on replacing $x$ by $-x$ in (2.5) and noting that

$$
\begin{equation*}
L_{r}(-x)=(-1)^{r+1} L_{r}(x) \tag{2.8}
\end{equation*}
$$

Theorem 2.5. The convolution $S_{+}(x) * x_{+}^{r}$ exists and

$$
\begin{equation*}
S_{+}(x) * x_{+}^{r}=\frac{\sqrt{2}}{\sqrt{\pi}(r+1)} \sum_{i=0}^{r+1}\binom{r+1}{i}(-1)^{r-i+1} L_{r-i+1}(x) x_{+}^{i} \tag{2.9}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. It is obvious that $S_{+}(x) * x_{+}^{r}=0$ if $x<0$. When $x>0$, we have

$$
\begin{align*}
\sqrt{\frac{\pi}{2}} S_{+}(x) * x_{+}^{r} & =\int_{0}^{x}(x-t)^{r} \int_{0}^{t} \sin u^{2} d u d t \\
& =\frac{1}{r+1} \sum_{i=0}^{r+1}\binom{r+1}{i}(-1)^{r-i+1} L_{r-i+1}(x) x_{+}^{i} \tag{2.10}
\end{align*}
$$

Thus equation (2.9) follows.

Corollary 2.6. The convolution $S_{-}(x) * x_{-}^{r}$ exists and

$$
\begin{equation*}
S_{-}(x) * x_{-}^{r}=\frac{\sqrt{2}}{\sqrt{\pi}(r+1)} \sum_{i=0}^{r+1}\binom{r+1}{i} L_{r-i+1}(x) x_{-}^{i} \tag{2.11}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. Equation (2.11) follows on replacing $x$ by $-x$ in (2.9).
3. Existence of neutrix convolution product. In order to extend the convolution product to a larger class of distributions, the neutrix convolution product was introduced in [1] and was later extended in [2, 3]. For the further extension, first of all, we let $\tau$ be a function in $\mathscr{D}$ having the following properties:
(i) $\tau(x)=\tau(-x)$,
(ii) $0 \leq \tau(x) \leq 1$,
(iii) $\tau(x)=1$ for $|x| \leq 1 / 2$,
(iv) $\tau(x)=0$ for $|x| \geq 1$.

The function $\tau_{v}$ is now defined for $v>0$ by

$$
\tau_{v}(x)= \begin{cases}1, & |x| \leq v  \tag{3.1}\\ \tau\left(v^{v} x-v^{v+1}\right), & x>v \\ \tau\left(v^{v} x+v^{v+1}\right), & x<-v\end{cases}
$$

Definition 3.1. Let $f$ and $g$ be distributions in $\mathscr{D}^{\prime}$ and let $f_{v}=f \tau_{v}$ for $v>0$. The neutrix convolution product $f \circledast g$ is defined as the neutrix limit of the sequence $\left\{f_{v} * g\right\}$, provided that the limit $h$ exists in the sense that

$$
\begin{equation*}
N-\lim _{v \rightarrow \infty}\left\langle f_{v} * g, \varphi\right\rangle=\langle h, \varphi\rangle, \tag{3.2}
\end{equation*}
$$

for all $\varphi$ in $\mathscr{D}$, where $N$ is the neutrix, see van der Corput [7], having domain $N^{\prime}$, the positive real numbers, with negligible functions finite linear sums of the functions $v^{\lambda} \ln ^{r-1} v, \ln ^{r} v, v^{r} \sin \nu^{2}$, and $v^{r} \sin v^{2}(\lambda \neq 0, r=1,2, \ldots)$ and all functions which converge to zero in the normal sense as $v$ tends to infinity.

Note that in this definition the convolution product $f_{v} * g$ is defined in Gel'fand and Shilov's sense, with the distribution $f_{v}$ having bounded support.

It was proved in [1] that if $f * g$ exists in the classical sense or by Definition 2.1, then $f \circledast g$ exists and

$$
\begin{equation*}
f \circledast g=f * g . \tag{3.3}
\end{equation*}
$$

The following theorem was also proved in [1].
Theorem 3.2. Let $f$ and $g$ be distributions in $\mathscr{D}^{\prime}$ and suppose that the neutrix convolution product $f \circledast g$ exists. Then the neutrix convolution product $f \circledast g^{\prime}$
exists and

$$
\begin{equation*}
(f \circledast g)^{\prime}=f \circledast g^{\prime} . \tag{3.4}
\end{equation*}
$$

Now if we let $L_{r}=N-\lim _{v \rightarrow \infty} L_{r}(v)$ and note that

$$
\begin{equation*}
S(\infty)=C(\infty)=\frac{1}{2} \tag{3.5}
\end{equation*}
$$

see Olver [6], then we have the following theorem.
Theorem 3.3. The neutrix convolution $\left(\sin _{+} x^{2}\right) * x^{r}$ exists and

$$
\begin{equation*}
\left(\sin _{+} x^{2}\right) \circledast x^{r}=\sum_{i=0}^{r}\binom{r}{i}(-1)^{r-i} L_{r-i} x^{i} \tag{3.6}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. We set

$$
\begin{equation*}
\left(\sin _{+} x^{2}\right)_{v}=\left(\sin _{+} x^{2}\right) \tau_{v}(x) \tag{3.7}
\end{equation*}
$$

Then the convolution $\left(\sin _{+} x^{2}\right)_{v} * x^{r}$ exists and

$$
\begin{equation*}
\left(\sin _{+} x^{2}\right)_{v} * x^{r}=\int_{0}^{v} \sin t^{2}(x-t)^{r} d t+\int_{v}^{v+v^{-v}} \tau_{v}(t) \sin t^{2}(x-t)^{r} d t \tag{3.8}
\end{equation*}
$$

Now

$$
\begin{align*}
\int_{0}^{v} \sin t^{2}(x-t)^{r} d t & =\sum_{i=0}^{r}\binom{r}{i} \int_{0}^{v} x^{i}(-t)^{r-i} \sin t^{2} d t  \tag{3.9}\\
& =\sum_{i=0}^{r}\binom{r}{i}(-1)^{r-i} L_{r-i}(v) x^{i}
\end{align*}
$$

and it follows that

$$
\begin{equation*}
N-\lim \int_{v \rightarrow \infty}^{v} \sin t^{2}(x-t)^{r} d t=\sum_{i=0}^{r}\binom{r}{i}(-1)^{r-i} L_{r-i} x^{i} \tag{3.10}
\end{equation*}
$$

Further, it can easily be seen that for each fixed $x$,

$$
\begin{equation*}
\lim _{v \rightarrow \infty} \int_{v}^{v+v^{-v}} \tau_{v}(t) \sin t^{2}(x-t)^{r} d t=0 \tag{3.11}
\end{equation*}
$$

and (3.6) follows from (3.9), (3.10), and (3.11).
Theorem 3.4. The neutrix convolution $S_{+}(x) \circledast x^{r}$ exists and

$$
\begin{equation*}
S_{+}(x) \circledast x^{r}=\frac{\sqrt{2}}{\sqrt{\pi}(r+1)} \sum_{i=0}^{r}\binom{r+1}{i}(-1)^{r-i+1} L_{r-i+1} x^{i} \tag{3.12}
\end{equation*}
$$

for $r=0,1,2, \ldots$

Proof. We put $\left[S_{+}(x)\right]_{v}=S_{+}(x) \tau_{v}(x)$. Then the convolution product $\left[S_{+}(x)\right]_{v} * x^{r}$ exists and

$$
\begin{equation*}
\left[S_{+}(x)\right]_{v} * x^{r}=\int_{0}^{v} S(t)(x-t)^{r} d t+\int_{v}^{v+v^{-v}} \tau_{v}(t) S(t)(x-t)^{r} d t \tag{3.13}
\end{equation*}
$$

We have

$$
\begin{align*}
& \sqrt{\frac{\pi}{2}} \int_{0}^{v} S(t)(x-t)^{r} d t \\
& \quad=\int_{0}^{v}(x-t)^{r} \int_{0}^{t} \sin u^{2} d u d t  \tag{3.14}\\
& \quad=-\frac{1}{r+1} \int_{0}^{v} \sum_{i=0}^{r}\binom{r+1}{i} x^{i}\left[(-v)^{r-i+1}-(-u)^{r-i+1}\right] \sin u^{2} d u
\end{align*}
$$

and it follows that

$$
\begin{equation*}
N-\lim \int_{v \rightarrow \infty}^{v} S(t)(x-t)^{r} d t=\frac{\sqrt{2}}{\sqrt{\pi}(r+1)} \sum_{i=0}^{r}\binom{r+1}{i}(-1)^{r-i+1} L_{r-i+1} x^{i} \tag{3.15}
\end{equation*}
$$

Further, it is easily seen that for each fixed $x$,

$$
\begin{equation*}
\lim _{v \rightarrow \infty} \int_{v}^{v+v^{-v}} \tau_{v}(t) S(t)(x-t)^{r} d t=0 \tag{3.16}
\end{equation*}
$$

and (3.12) now follows immediately from (3.14), (3.15), and (3.16).
Corollary 3.5. The neutrix convolution $S_{-}(x) \oplus x^{r}$ exists and

$$
\begin{equation*}
S_{-}(x) \circledast x^{r}=\frac{\sqrt{2}}{\sqrt{\pi}(r+1)} \sum_{i=0}^{r}\binom{r+1}{i}(-1)^{r-i} L_{r-i+1} x^{i} \tag{3.17}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. Equation (3.17) follows on replacing $x$ by $-x$ and $L_{r}$ by $(-1)^{r+1} L_{r}$ in (3.12).

Corollary 3.6. The neutrix convolution $S(x) \circledast x^{r}$ exists and

$$
\begin{equation*}
S(x) \circledast x^{r}=0 \tag{3.18}
\end{equation*}
$$

for $r=0,1,2, \ldots$.
Proof. Equation (3.18) follows from (3.12) and (3.17) on noting that $S(x)=$ $S_{+}(x)+S_{-}(x)$.

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