

## COMMON FIXED POINTS OF COMPATIBLE MAPPINGS

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**ABSTRACT.** In this paper, we present a common fixed point theorem for compatible mappings, which extends the results of Ding, Diviccaro-Sessa and the third author.

**KEY WORDS AND PHRASES.** Common fixed points, commuting mappings, weakly commuting mappings and compatible mappings.

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### 1. INTRODUCTION.

In [1], the concept of compatible mappings was introduced as a generalization of commuting mappings. The utility of compatibility in the context of fixed point theory was demonstrated by extending a theorem of Park-Bae [2]. In [3], the third author extended a result of Singh-Singh [4] by employing compatible mappings in lieu of commuting mappings and by using four functions as opposed to three. On the other hand, Diviccaro-Sessa [5] proved a common fixed point theorem for four mappings, using a well known contractive condition of Meade-Singh [6] and the concept of weak commutativity of Sessa [7]. Their theorems generalize results of Chang [8], Imdad Khan [9], Meade-Singh [6], Sessa-Fisher [10] and Singh-Singh [4].

In this paper, we extend the results of Ding [11], Diviccaro-Sessa [5] and the third author [3].

The following Definition 1.1 is given in [1].

**DEFINITION 1.1.** Let  $A$  and  $B$  be mappings from a metric space  $(X, d)$  into itself. Then  $A$  and  $B$  are said to be compatible if  $\lim_{n \rightarrow \infty} d(ABx_n, BAx_n) = 0$  whenever  $\{x_n\}$  is a sequence in  $X$  such that  $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Bx_n = z$  for some  $z$  in  $X$ .

Thus, if  $d(ABx_n, BAx_n) \rightarrow 0$  as  $d(Ax_n, Bx_n) \rightarrow 0$ , then  $A$  and  $B$  are compatible.

Mappings which commute are clearly compatible, but the converse is false. S. Sessa [7] generalized commuting mappings by calling mappings A and B from a metric space  $(X,d)$  into itself a weakly commuting pair if  $d(ABx, BAx) < d(Ax, Bx)$  for all  $x$  in  $X$ . Any weakly commuting pair are obviously compatible, but the converse is false [3]. See [1] for other examples of the compatible pairs which are not weakly commutative and hence not commuting pairs.

LEMMA 1.1 ([1]). Let A and B be compatible mappings from a metric space  $(X,d)$  into itself. Suppose that  $\lim_{n \rightarrow \infty} Ax_n = \lim_{n \rightarrow \infty} Bx_n = z$  for some  $z$  in  $X$ . Then  $\lim_{n \rightarrow \infty} BAx_n = Az$  if A is continuous.

## 2. A FIXED POINT THEOREM.

Throughout this paper, suppose that the function  $\phi: [0, \infty)^5 \rightarrow [0, \infty)$  satisfies the following conditions:

(1)  $\phi$  is nondecreasing and upper semicontinuous in each coordinate variable,

(2) For each  $t > 0$ ,  $\psi(t) = \max \{ \phi(0,0,t,t,t), \phi(t,t,t,2t,0), \phi(t,t,t,0,2t) \} < t$ . (2.1)

LEMMA 2.1 ([12]). Suppose that  $\Psi: [0, \infty) \rightarrow [0, \infty)$  is nondecreasing and upper semicontinuous from the right. If  $\Psi(t) < t$  for every  $t > 0$ , then  $\lim_{n \rightarrow \infty} \Psi^n(t) = 0$ , where  $\Psi^n(t)$  denotes the composition of  $\Psi(t)$  with itself  $n$ -times.

Now, we are ready to state our main Theorem.

THEOREM 2.2. Let A, B, S, and T be mappings from a complete metric space  $(X,d)$  into itself. Suppose that one of A, B, S and T is continuous, the pairs A, S and B, T are compatible and that  $A(X) \subset T(X)$  and  $B(X) \subset S(X)$ . If the inequality

$$d(Ax, By) < \phi(d(Ax, Sx), d(By, Ty), d(Sx, Ty), d(Ax, Ty), d(By, Sx)) \quad (2.2)$$

holds for all  $x$  and  $y$  in  $X$ , where  $\phi$  satisfies (1) and (2), then A, B, S and T have a unique common fixed point in  $X$ .

PROOF. Let  $x_0 \in X$  be given. Since  $A(X) \subset T(X)$  and  $B(X) \subset S(X)$ , we can choose  $x_1$  in  $X$  such that  $y_1 = Tx_1 = Ax_0$  and, for this point  $x_1$ , there exists a point  $x_2$  in  $X$  such that  $y_2 = Sx_2 = Bx_1$  and so on. Inductively, we can define a sequence  $\{y_n\}$  in  $X$  such that

$$y_{2n+1} = Tx_{2n+1} = Ax_{2n} \text{ and } y_{2n} = Sx_{2n} = Bx_{2n-1}. \quad (2.3)$$

By (2.2) and (2.3), we have

$$\begin{aligned} d(y_{2n+1}, y_{2n+2}) &= d(Ax_{2n}, Bx_{2n+1}) \\ &< \phi(d(Ax_{2n}, Sx_{2n}), d(Bx_{2n+1}, Tx_{2n+1}), d(Sx_{2n}, Tx_{2n+1}), \\ &\quad d(Ax_{2n}, Tx_{2n+1}), d(Bx_{2n+1}, Sx_{2n})) \\ &< \phi(d(y_{2n+1}, y_{2n}), d(y_{2n+2}, y_{2n+1}), d(y_{2n}, y_{2n+1}), \\ &\quad 0, d(y_{2n+2}, y_{2n})) \\ &< \phi(d(y_{2n}, y_{2n+1}), d(y_{2n+1}, y_{2n+2}), d(y_{2n}, y_{2n+1}), \\ &\quad 0, d(y_{2n}, y_{2n+1}) + d(y_{2n+1}, y_{2n+2})). \end{aligned}$$

If  $d(y_{2n+1}, y_{2n+2}) > d(y_{2n}, y_{2n+1})$  in the above inequality, then we have

$$\begin{aligned} d(y_{2n+1}, y_{2n+2}) &\leq \Phi(d(y_{2n+1}, y_{2n+2}), d(y_{2n+1}, y_{2n+2}), \\ &\quad d(y_{2n+1}), y_{2n+2}), 0, 2d(y_{2n+1}, y_{2n+2})) \\ &\leq \Psi(d(y_{2n+1}, y_{2n+2})) < d(y_{2n+1}, y_{2n+2}), \end{aligned}$$

which is a contradiction. Thus,

$$\begin{aligned} d(y_{2n+1}, y_{2n+2}) &\leq \Phi(d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1}), d(y_{2n}, y_{2n+1}), \\ &\quad 0, 2d(y_{2n}, y_{2n+1})) \\ &\leq \Psi(d(y_{2n}, y_{2n+1})). \end{aligned} \quad (2.4)$$

Similarly, we have

$$d(y_{2n+2}, y_{2n+3}) \leq \Psi(d(y_{2n+1}, y_{2n+2})). \quad (2.5)$$

It follows from (2.4) and (2.5) that

$$d_n = d(y_n, y_{n+1}) \leq \Psi(d(y_{n-1}, y_n)) \leq \dots \leq \Psi^{n-1}(d(y_1, y_2)). \quad (2.6)$$

By (2.6) and Lemma 2.1, we obtain

$$\lim_{n \rightarrow \infty} d_n = 0. \quad (2.7)$$

In order to show that  $\{y_n\}$  is a Cauchy sequence, it is sufficient to show that  $\{y_{2n}\}$  is a Cauchy sequence. Suppose that  $\{y_{2n}\}$  is not a Cauchy sequence. Then there is an  $\varepsilon > 0$  such that, for each even integer  $2k$ , there exist even integers  $2m(k)$  and  $2n(k)$  such that

$$d(y_{2m(k)}, y_{2n(k)}) > \varepsilon \text{ for } 2m(k) > 2n(k) > 2k. \quad (2.8)$$

For each even integer  $2k$ , let  $2m(k)$  be the least even integer exceeding  $2n(k)$  satisfying (2.8), that is,

$$d(y_{2n(k)}, y_{2m(k)-2}) \leq \varepsilon \text{ and } d(y_{2n(k)}, y_{2m(k)}) > \varepsilon. \quad (2.9)$$

Then, for each even integer  $2k$ ,

$$\varepsilon < d(y_{2n(k)}, y_{2m(k)}) \leq d(y_{2n(k)}, y_{2m(k)-2}) + d_{2m(k)-2} + d_{2m(k)-1}.$$

It follows from (2.7) and (2.9) that

$$\lim_{k \rightarrow \infty} d(y_{2n(k)}, y_{2m(k)}) = \varepsilon. \quad (2.10)$$

By the triangle inequality,

$$\begin{aligned} |d(y_{2n(k)}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| &\leq d_{2m(k)-1} \text{ and} \\ |d(y_{2n(k)+1}, y_{2m(k)-1}) - d(y_{2n(k)}, y_{2m(k)})| &\leq d_{2m(k)-1} + d_{2n(k)}. \end{aligned}$$

From (2.7) and (2.10), as  $k \rightarrow \infty$ ,

$$d(y_{2n(k)}, y_{2m(k)-1}) \rightarrow \varepsilon \text{ and } d(y_{2n(k)+1}, y_{2m(k)-1}) \rightarrow \varepsilon.$$

By (2.2) and (2.3), we have

$$\begin{aligned} d(y_{2n(k)}, y_{2m(k)}) &< d_{2n(k)} + d(Ax_{2n(k)}, Bx_{2m(k)-1}) \\ &< d_{2n(k)} + \psi(d_{2n(k)}, d_{2m(k)-1}, d(y_{2n(k)}, y_{2m(k)-1}), \\ &\quad d(y_{2n(k)+1}, y_{2m(k)-1}), d(y_{2m(k)}, y_{2n(k)})). \end{aligned}$$

Since  $\psi$  is upper semicontinuous,

$$\varepsilon < \psi(0, 0, \varepsilon, \varepsilon, \varepsilon) < \varepsilon \text{ as } k \rightarrow \infty,$$

which is a contradiction. Hence  $\{y_n\}$  is a Cauchy sequence and it converges to some point  $z$  in  $X$ . Consequently the subsequences  $\{Ax_{2n}\}$ ,  $\{Sx_{2n}\}$ ,  $\{Bx_{2n-1}\}$  and  $\{Tx_{2n-1}\}$  converge to  $z$ . Suppose that  $S$  is continuous. Since  $A$  and  $S$  are compatible, Lemma 1.2 implies that

$$SSx_{2n} \text{ and } ASx_{2n} \rightarrow Sz.$$

By (2.2), we obtain

$$\begin{aligned} d(ASx_{2n}, Bx_{2n-1}) &< \psi(d(ASx_{2n}, SSx_{2n}), d(Bx_{2n-1}, Tx_{2n-1}), \\ &\quad d(SSx_{2n}, Tx_{2n-1}), d(ASx_{2n}, Tx_{2n-1}), d(Bx_{2n-1}, SSx_{2n})). \end{aligned}$$

Letting  $n \rightarrow \infty$ , we have

$$d(Sz, z) < \psi(0, 0, d(Sz, z), d(Sz, z), d(z, Sz)),$$

so that  $z = Sz$ . By (2.2), we also obtain

$$\begin{aligned} d(Az, Bx_{2n-1}) &< \psi(d(Az, Sz), d(Bx_{2n-1}, Tx_{2n-1}), d(Sz, Tx_{2n-1}), \\ &\quad d(Az, Tx_{2n-1}), d(Bx_{2n-1}, Sz)). \end{aligned}$$

Letting  $n \rightarrow \infty$ , we have

$$d(Az, z) < \psi(d(Az, Sz), 0, d(Sz, z), d(Az, z), d(z, Sz)),$$

so that  $z = Az$ . Since  $A(X) \subset T(X)$ ,  $z \in T(X)$  and hence there exists a point  $w$  in  $X$  such that  $z = Az = Tw$ .

$$d(z, Bw) = d(Az, Bw) < \psi(0, d(Bw, Tw), d(Sz, Tw), d(Az, Tw), d(Bw, z)),$$

which implies that  $z = Bw$ . Since  $B$  and  $T$  are compatible and  $Tw = Bw = z$ ,  $d(TBw, BTw) = 0$  and hence  $Tz = TBw = BTw = Bz$ . Moreover, by (2.2),

$$d(z, Tz) = d(Az, Bz) < \psi(0, d(Bz, Tz), d(z, Tz), d(z, Tz), d(Bz, z)),$$

so that  $z = Tz$ . Therefore,  $z$  is a common fixed point of  $A, B, S$  and  $T$ . Similarly, we can complete the proof in the case of the continuity of  $T$ . Now, suppose that  $A$  is continuous. Since  $A$  and  $S$  are compatible, Lemma 1.2 implies that

$$AAx_{2n} \text{ and } SAx_{2n} \rightarrow Az.$$

By (2.2), we have

$$\begin{aligned} d(AAx_{2n}, Bx_{2n-1}) &< \psi(d(AAx_{2n}, SAx_{2n}), d(Bx_{2n-1}, Tx_{2n-1}), \\ &\quad d(SAx_{2n}, Tx_{2n-1}), d(AAx_{2n}, Tx_{2n-1}), d(Bx_{2n-1}, SAx_{2n})). \end{aligned}$$

Letting  $n \rightarrow \infty$ , we obtain

$$d(Az, z) < \psi(0, 0, d(Az, z), d(Az, z), d(z, Az)),$$

so that  $z = Az$ . Hence, there exists a point  $v$  in  $X$  such that  $z = Az = Tv$ .

$$d(AAx_{2n}, Bv) \leq \Phi(d(AAx_{2n}, SAx_{2n}), d(Bv, Tv), d(SAx_{2n}, Tv), \\ d(AAx_{2n}, Tv) d(Bv, SAx_{2n})),$$

Letting  $n \rightarrow \infty$ , we have

$$d(z, Bv) \leq \Phi(0, d(Bv, Tv), d(z, Tv), d(Az, Tv), d(Bv, z)),$$

which implies that  $z = Bv$ . Since  $B$  and  $T$  are compatible and  $Tv = Bv = z$ ,  $d(TBv, BTv) = 0$  and hence  $Tz = TBv = BTv = Bz$ . Moreover, by (2.2), we have

$$d(Ax_{2n}, Bz) \leq \Phi(d(Ax_{2n}, Sx_{2n}), d(Bz, Tz), d(Sx_{2n}, Tz), \\ d(Ax_{2n}, Tz), d(Bz, Sx_{2n})).$$

Letting  $n \rightarrow \infty$ ,  $d(z, Bz) \leq \Phi(0, d(Bz, Tz), d(z, Tz), d(z, Tz), d(Bz, z))$ , so that  $z = Bz$ . Since  $B(X) \subset S(X)$ , there exists a point  $w$  in  $X$  such that  $z = Bz = Sw$ .

$$d(Aw, z) = d(Aw, Bz) \leq \Phi(d(Aw, Sw), 0, d(Sw, z), d(Aw, z), d(z, Sw)),$$

so that  $Aw = z$ . Since  $A$  and  $S$  are compatible and  $Aw = Sw = z$ ,  $d(SBw, BSw) = 0$  and hence  $Sz = SAw = ASw = Az$ . Therefore  $z$  is a common fixed point of  $A, B, S$  and  $T$ . Similarly, we can complete the proof in the case of the continuity of  $B$ . It follows easily from (2.2) that  $z$  is a unique common fixed point of  $A, B, S$  and  $T$ .

**COROLLARY 2.3.** Let  $A, B, S$  and  $T$  be mappings from a complete metric space  $(X, d)$  into itself. Suppose that one of  $A, B, S$  and  $T$  is continuous, the pairs  $A, S$  and  $B, T$  are compatible and that  $A(X) \subset T(X)$  and  $B(X) \subset S(X)$ . If the inequality (2.2) holds for all  $x$  and  $y$  in  $X$ , where  $\Phi$  satisfies (1) and (2.11);

$$\psi(t) = \max\{\Phi(t, t, t, t, t), \Phi(t, t, t, 2t, 0), \Phi(t, t, t, 0, 2t)\} < t \quad (2.11)$$

for each  $t > 0$ , then  $A, B, S$  and  $T$  have a unique common fixed point in  $X$ .

**REMARK 2.4.** From Theorem 2.2 and Corollary 2.3, we extend the results of Ding [11] and Diviccaro-Sessa [5] by employing compatibility in lieu of commuting and weakly commuting mappings, respectively. Further our theorem extends also a result of Ding [11] by using one continuous function as opposed to two.

**REMARK 2.5.** From Theorem 2.2 defining  $\Phi: [0, \infty)^5 \rightarrow [0, \infty)$  by

$$\Phi(t_1, t_2, t_3, t_4, t_5) = h \max\{t_1, t_2, t_3, \frac{1}{2}(t_4 + t_5)\}$$

for all  $t_1, t_2, t_3, t_4, t_5 \in [0, \infty)$  and  $h \in [0, 1)$ , we obtain a result of the third author [3] even if one function is continuous as opposed to two.

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