Research Article

Positive Solutions to a Second-Order Discrete Boundary Value Problem

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We are concerned with second-order discrete boundary value problems and obtain some sufficient conditions for the existence of at least one positive solution by using the fixed point theorem due to Krasnosel'skii on a cone.

1. Introduction

Boundary value problems for difference equations have been studied extensively by many authors, for example, [1–10] to name a few. Many techniques arose in the studies of this kind of problem. For example, Agarwal et al. [1] employed the critical point theory to establish the existence of multiple solutions of some regular as well as singular discrete boundary value problems. Cai and Yu [2] applied the Linking Theorem and the Mountain Pass Lemma in the critical point theory to study second-order discrete boundary value problems and obtained some new results for the existence of solutions. Li and Sun [3, 4] were concerned with discrete system boundary value problems and gave some sufficient conditions for the existence of one or two positive solutions by using a nonlinear alternative of Leray-Schauder type and Krasnosel'skii's fixed point theorem in a cone. Pang et al. [5] provided sufficient conditions for the existence of at least three positive solutions for quasilinear boundary value problems for finite difference equations by using a generalization of the Leggett-Williams fixed point theorem due to Avery and Peterson. Du [6], Lin and Liu [7] discussed triple positive solutions of some second-order discrete boundary value problems by making use of the Leggett-Williams fixed-point theorem, respectively.

This paper deals with the following three-point boundary value problem for secondorder difference equation of the form

$$\begin{aligned} \Delta^2 y(k-1) + h(k) f(y(k)) &= 0, \quad k \in \{1, \dots, T\}, \\ y(0) - \alpha \Delta y(0) &= 0, \qquad y(T+1) = \beta y(n), \end{aligned} \tag{1.1}$$

where $\Delta y(k-1) = y(k) - y(k-1), \Delta^2 y(k-1) = y(k+1) - 2y(k) + y(k-1), k \in \{1, \dots, T\}.$

Throughout this paper, we will assume that the following conditions are satisfied:

- (A1) $T \ge 3$ is a fixed positive integer, $n \in \{2, ..., T-1\}$, constant $\alpha, \beta > 0$ such that $H := T + 1 \beta n + \alpha(1 \beta) > 0$ and $T + 1 \beta n > 0$;
- (A2) $f \in C([0, +\infty), [0, +\infty))$, f is either superlinear or sublinear, that is, either $f_0 = 0$, $f_{\infty} = \infty$ or $f_0 = \infty$, $f_{\infty} = 0$, where

$$f_0 = \lim_{u \to 0^+} \frac{f(u)}{u}, \qquad f_\infty = \lim_{u \to \infty} \frac{f(u)}{u}; \tag{1.2}$$

(A3) h(k) is nonnegative on $\{1, \ldots, T\}$ and $h(k) \equiv 0$ does not hold on $\{n, \ldots, T\}$.

In the paper, we show the existence of positive solutions of (1.1) under some assumptions. We also establish the associate Green's function. Readers may find that it is useful to define a cone on which a positive operator was defined, and a fixed point theorem due to Krasnosel'skii [11] will be applied to yield the existence of at least one positive solution.

2. Preliminary and Green's Function

Let **N** be the nonnegative integers; we let $N_{i,j} = \{k \in \mathbb{N} : i \leq k \leq j\}$ and $N_p = N_{0,p}$.

By a *positive solution* y of problem (1.1), we mean $y : \mathbf{N}_{T+1} \to R$, y satisfies the first equation of (1.1) on $\mathbf{N}_{1,T}$, y fulfills $y(0) - \alpha \Delta y(0) = 0$, $y(T + 1) = \beta y(n)$, and y is nonnegative on \mathbf{N}_{T+1} and positive on $\mathbf{N}_{1,T}$.

We shall need the following fixed point theorem due to Krasnosel'skii [8, 11].

Theorem A. Let *E* be a Banach space, and let $K \,\subset E$ be a cone in *E*. Assume that Ω_1 and Ω_2 are open subsets of *E* with $0 \in \Omega_1$, $\overline{\Omega_1} \subset \Omega_2$, and let $A : K \cap (\overline{\Omega_2} \setminus \Omega_1) \to K$ be a completely continuous operator such that either

- (1) $||Au|| \le ||u||, u \in K \cap \partial\Omega_1$ and $||Au|| \ge ||u||, u \in K \cap \partial\Omega_2$ or
- (2) $||Au|| \ge ||u||, u \in K \cap \partial \Omega_1$ and $||Au|| \le ||u||, u \in K \cap \partial \Omega_2$.

Then A has a fixed point in $K \cap (\overline{\Omega_2} \setminus \Omega_1)$ *.*

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Lemma 2.1 (see [7]). The function

$$G(k,l) = \frac{1}{H} \begin{cases} (l+\alpha) [T+1-k-\beta(n-k)], & l \in \mathbf{N}_{1,k-1} \cap \mathbf{N}_{1,n-1}, \\ (l+\alpha)(T+1-k) + \beta(n+\alpha)(k-l), & l \in \mathbf{N}_{n,k-1}, \\ (k+\alpha) [T+1-l-\beta(n-l)], & l \in \mathbf{N}_{k,n-1}, \\ (k+\alpha)(T+1-l), & l \in \mathbf{N}_{k,T} \cap \mathbf{N}_{n,T}, \end{cases}$$
(2.1)

is the Green's function of the problem

$$-\Delta^2 y(k-1) = 0, \quad k \in \mathbf{N}_{1,T}, y(0) - \alpha \Delta y(0) = 0, \qquad y(T+1) = \beta y(n).$$
(2.2)

Remark 2.2. We observe that the condition H > 0 and $T + 1 - \beta n > 0$ implies G(k, l) is positive on $N_{T+1} \times N_{1,T}$, which means that the finite set

$$\left\{\frac{G(k,l)}{G(k,k)}: k \in \mathbf{N}_{T+1}, \ l \in \mathbf{N}_{1,T}\right\}$$
(2.3)

takes positive values. Then we let

$$M_{1} = \min\left\{\frac{G(k,l)}{G(k,k)} : k \in \mathbf{N}_{T+1}, \ l \in \mathbf{N}_{1,T}\right\},$$
(2.4)

$$M_{2} = \max\left\{\frac{G(k,l)}{G(k,k)} : k \in \mathbf{N}_{T+1}, \ l \in \mathbf{N}_{1,T}\right\}.$$
(2.5)

3. Main Results

Theorem 3.1. *Assume that* (*A*1)–(*A*3) *hold, then problem* (1.1) *has at least one positive solution. Proof.* In the following, we denote

$$m = \min_{k \in \mathbf{N}_{n,T}} G(k,k), \qquad M = \max_{k \in \mathbf{N}_{T+1}} G(k,k).$$
(3.1)

Then 0 < *m* < *M*.

Let *E* be the Banach space defined by $E = \{y : N_{T+1} \rightarrow R\}$. Define

$$K = \left\{ y \in E : y(k) \ge 0, \text{ for } k \in \mathbf{N}_{T+1} \text{ and } \min_{k \in \mathbf{N}_{n,T}} y(k) \ge \sigma \|y\| \right\},$$
(3.2)

where $\sigma = M_1 m / M_2 M \in (0, 1), ||y|| = \max_{k \in \mathbb{N}_{T+1}} |y(k)|$. It is clear that *K* is a cone in *E*.

We define the operator $S: K \to E$ by

$$(Sy)(k) = \sum_{l=1}^{T} G(k,l)h(l)f(y(l)), \quad k \in \mathbf{N}_{T+1}.$$
 (3.3)

It is clear that problem (1.1) has a solution y if and only if $y \in E$ is a solution of the operator equation y(k) = (Sy)(k). We shall now show that the operator S maps K into itself. For this, let $y \in K$; from (A2), (A3), we find

$$(Sy)(k) = \sum_{l=1}^{T} G(k,l)h(l)f(y(l)) \ge 0, \text{ for } k \in \mathbf{N}_{T+1}.$$
 (3.4)

From (2.5), we obtain

$$(Sy)(k) = \sum_{l=1}^{T} G(k,l)h(l)f(y(l)) \le M_2 \sum_{l=1}^{T} G(k,k)h(l)f(y(l))$$

$$\le M_2 M \sum_{l=1}^{T} h(l)f(y(l)), \text{ for } k \in \mathbf{N}_{T+1}.$$
(3.5)

Therefore

$$||Sy|| \le M_2 M \sum_{l=1}^{T} h(l) f(y(l)).$$
 (3.6)

Now from (A2), (A3), (2.4), and (3.6), for $k \in N_{n,T}$, we have

$$(Sy)(k) \ge M_1 \sum_{l=1}^{T} G(k, k) h(l) f(y(l)) \ge M_1 m \sum_{l=1}^{T} h(l) f(y(l))$$

$$\ge \frac{M_1 m}{M_2 M} ||Sy|| = \sigma ||y||.$$
(3.7)

Then

$$\min_{k \in \mathbf{N}_{n,T}} (Sy)(k) \ge \sigma \|Sy\|.$$
(3.8)

From (3.4) and (3.6), we obtain $Sy \in K$. Hence $S(K) \subseteq K$. Also standard arguments yield that $S: K \to K$ is completely continuous.

Case 1. Suppose *f* is superlinear. Now since $f_0 = 0$, we may choose $C_1 > 0$ such that $f(u) \le \delta_1 u$, for $0 < u \le C_1$, where δ_1 satisfies

$$\delta_1 M_2 M \sum_{l=1}^T h(l) \le 1.$$
 (3.9)

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Let $y \in K$ be such that $||y|| = C_1$; by using (2.5) and (3.9), we have

$$(Sy)(k) \leq M_{2} \sum_{l=1}^{T} G(k,k) h(l) f(y(l)) \leq \delta_{1} M_{2} M \sum_{l=1}^{T} h(l) y(l)$$

$$\leq \delta_{1} M_{2} M \sum_{l=1}^{T} h(l) \|y\| \leq \|y\|.$$
(3.10)

Now if we let

$$\Omega_1 = \{ y \in E : ||y|| < C_1 \}, \tag{3.11}$$

then

$$\|Sy\| \le \|y\|, \quad \text{for } y \in K \cap \partial\Omega_1.$$
(3.12)

Next since $f_{\infty} = \infty$, there exists $\overline{C_2} > 0$, such that $f(u) \ge \delta_2 u$, for $u \ge \overline{C_2}$, where $\delta_2 > 0$ satisfying

$$\delta_2 M_1 \sigma \sum_{l=n}^T G(n, n) h(l) \ge 1.$$
(3.13)

Let $C_2 = \max\{2C_1, \overline{C_2}/\sigma\}$ and $\Omega_2 = \{y \in E : ||y|| < C_2\}$, and let $y \in K$ and $||y|| = C_2$, then

$$\min_{k \in \mathbf{N}_{n,T}} \boldsymbol{y}(k) \ge \sigma \|\boldsymbol{y}\| \ge \overline{C_2}.$$
(3.14)

Applying (2.4) and (3.13), one has

$$(Sy)(n) = M_{1} \sum_{l=1}^{T} G(n, l) h(l) f(y(l)) \ge M_{1} \sum_{l=n}^{T} G(n, n) h(l) f(y(l))$$

$$\ge \delta_{2} M_{1} \sum_{l=n}^{T} G(n, n) h(l) y(l) \ge \delta_{2} M_{1} \sigma \sum_{l=n}^{T} G(n, n) h(l) ||y||$$

$$\ge ||y||.$$
(3.15)

Thus

$$\|Sy\| \ge \|y\|, \quad y \in K \cap \partial\Omega_2. \tag{3.16}$$

In view of (3.12) and (3.16), it follows from Theorem A that *S* has a fixed point $y \in K \cap (\overline{\Omega_2} \setminus \Omega_1)$ such that $C_1 \leq ||y|| \leq C_2$.

Case 2. Suppose *f* is sublinear case. Since $f_0 = \infty$, we may choose $C_3 > 0$ such that $f(u) \ge \delta_3 u$ for $0 < u \le C_3$, where $\delta_3 > 0$ satisfying

$$\delta_3 M_1 \sigma \sum_{l=n}^T G(n, n) h(l) \ge 1,$$
 (3.17)

 $\Omega_3 = \{y \in E : ||y|| < C_3\}; \text{ let } y \in K \text{ and } ||y|| = C_3. \text{ Using (2.4) and (3.17), one has }$

$$(Sy)(n) \ge M_1 \sum_{l=n}^{T} G(n,n)h(l)f(y(l)) \ge \delta_3 M_1 \sum_{l=n}^{T} G(n,n)h(l)y(l)$$

$$\ge \delta_3 M_1 \sigma \sum_{l=n}^{T} G(n,n)h(l) ||y|| \ge ||y||.$$
(3.18)

Then $||Sy|| \ge ||y||$, $y \in K \cap \partial \Omega_3$.

In view of $f_{\infty} = 0$, there exists $\overline{C_4} > 0$ such that $f(u) \le \delta_4 u$ for $u \ge \overline{C_4}$, where $\delta_4 > 0$ satisfying

$$\delta_4 M_2 M \sum_{l=n}^{T} h(l) \le 1.$$
 (3.19)

There are two subcases to consider, that is, f is bounded and f is unbounded.

Subcase 2.1. Suppose f is bounded, that is, $f(y) \leq L$ for all $y \in [0, \infty)$ for some L > 0. Let

$$C_4 = \max\left\{2C_3, LM_2M\sum_{l=1}^T h(l)\right\}.$$
(3.20)

Then, for $y \in K$ and $||y|| = C_4$, one has

$$(Sy)(k) \le M_2 \sum_{l=1}^{T} G(k, k) h(l) f(y(l)) \le L M_2 M \sum_{l=1}^{T} h(l)$$

$$\le C_4 = ||y||.$$
(3.21)

Hence $||Sy|| \leq ||y||$.

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Subcase 2.2. Suppose f is unbounded, that is, there exists $C_4 > \max\{2C_3, \overline{C_4}/\sigma\}$ such that $f(u) \le f(C_4)$ for all $0 < u \le C_4$. Then, for $y \in K$ with $||y|| = C_4$, from (2.5) and (3.19), we have

$$(Sy)(k) \leq M_2 \sum_{l=1}^{T} G(k,k)h(l)f(y(l)) \leq M_2 M \sum_{l=1}^{T} h(l)f(C_4)$$

$$\leq \delta_4 M_2 M \sum_{l=1}^{T} h(l)C_4 \leq C_4 = ||y||.$$
(3.22)

Thus in both Subcases 2.1 and 2.2, we may put $\Omega_4 = \{y \in E : ||y|| < C_4\}$. Then

$$\|Sy\| \le \|y\|, \quad y \in K \cap \partial\Omega_4. \tag{3.23}$$

By using the fixed point Theorem A, it follows that problem (1.1) has at least one positive solution, such that $C_3 \le ||y|| \le C_4$. The proof is finished.

Finally, we give an example to demonstrate our main result.

Example 3.2. Consider the following three-point boundary value problem:

$$\Delta^{2} y(k-1) + \frac{2}{\left(-k^{2} + 10k + 33\right)^{1.5}} \left(y + 20\right)^{1.5} = 0, \quad k \in \mathbf{N}_{1,8},$$

$$y(0) - \frac{13}{9} \Delta y(0) = 0, \qquad y(9) = \frac{22}{37} y(4),$$
(3.24)

where T = 8, n = 4, $\alpha = 13/9$, $\beta = 22/37$, $T+1-\beta n+\alpha(1-\beta) = 800/111 > 0$, $T+1-\beta n = 245/37 > 0$, $h(k) = 2/(-k^2 + 10k + 33)^{1.5}$, $k \in \mathbb{N}_{1,8}$, $f(y) = (y+20)^{1.5}$, then *f* is superlinear. Conditions of Theorem 3.1 are all satisfied. Then problem (3.24) has at least one positive solution *y*. Indeed $y = -k^2 + 10k + 13$ is one such positive solution.

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