Research Article

# A Classification of a Totally Umbilical Slant Submanifold of Cosymplectic Manifolds 

Siraj Uddin, ${ }^{1}$ Cenap Ozel, ${ }^{2}$ and Viqar Azam Khan ${ }^{3}$<br>${ }^{1}$ Institute of Mathematical Sciences, Faculty of Science, University of Malaya, 50603 Kuala Lumpur, Malaysia<br>${ }^{2}$ Department of Mathematics, Abant Izzet Baysal University, 14268 Bolu, Turkey<br>${ }^{3}$ Department of Mathematics, Aligarh Muslim University, Aligarh 202002, India<br>Correspondence should be addressed to Siraj Uddin, siraj.ch@gmail.com

Received 27 September 2011; Revised 26 December 2011; Accepted 26 December 2011
Academic Editor: Natig Atakishiyev
Copyright © 2012 Siraj Uddin et al. This is an open access article distributed under the Creative Commons Attribution License, which permits unrestricted use, distribution, and reproduction in any medium, provided the original work is properly cited.

We study slant submanifolds of a cosymplectic manifold. It is shown that a totally umbilical slant submanifold $M$ of a cosymplectic manifold $\bar{M}$ is either an anti-invariant submanifold or a 1 -dimensional submanifold. We show that every totally umbilical proper slant submanifold of a cosymplectic manifold is totally geodesic.

## 1. Introduction

The study of slant submanifolds in complex spaces was initiated by Chen as a natural generalization of both holomorphic and totally real submanifolds [1,2]. Since then, many research papers have appeared concerning the existence of these submanifolds as well as on the geometry of the existent slant submanifolds in different known spaces (cf. [3, 4]). The slant submanifolds of an almost contact metric manifold were defined and studied by Lotta [4]. Later on, these submanifolds were studied by Cabrerizo et al. in the setting of Sasakian manifolds [3].

Recently, Şahin proved that a totally umbilical proper slant submanifold of a Kaehler manifold is totally geodesic [5]. Our aim in the present paper is to investigate slant submanifolds in contact manifolds. Thus, we study slant submanifolds of a cosymplectic manifold. We have shown that a totally umbilical slant submanifold $M$ of a cosymplectic manifold $\bar{M}$ is either an anti-invariant submanifold or the $\operatorname{dim} M=1$ or the mean curvature vector $H \in \Gamma(\mu)$, and then we have obtained an interesting result for a totally umbilical proper slant submanifold of a cosymplectic manifold.

## 2. Preliminaries

Let $\bar{M}$ be a $(2 n+1)$-dimensional manifold with $(1,1)$ tensor field $\phi$ satisfying [6]:

$$
\begin{equation*}
\phi^{2}=-I+\eta \otimes \xi \tag{2.1}
\end{equation*}
$$

where $I$ is the identity transformation, $\xi$ a vector field, and $\eta$ a 1-form on $\bar{M}$ satisfying $\phi \xi=$ $\eta \circ \phi=0$ and $\eta(\xi)=1$. Then $\bar{M}$ is said to have an almost contact structure. There always exists a Riemannian metric $g$ on $\bar{M}$ such that

$$
\begin{equation*}
g(\phi X, \phi Y)=g(X, Y)-\eta(X) \eta(Y) \tag{2.2}
\end{equation*}
$$

for all vector fields $X, Y$, on $\bar{M}$. From (2.2), it is easy to observe that

$$
\begin{equation*}
g(\phi X, Y)+g(X, \phi Y)=0 \tag{2.3}
\end{equation*}
$$

The fundamental 2-form $\Phi$ is defined as: $\Phi(X, Y)=g(X, \phi Y)$. If $[\phi, \phi]+d \eta \otimes \xi=0$, then the almost contact structure is said to be normal, where $[\phi, \phi](X, Y)=\phi^{2}[X, Y]+[\phi X, \phi Y]-$ $\phi[\phi X, Y]-\phi[X, \phi Y]$. If $\Phi=d \eta$, the almost contact structure is a contact structure. A normal almost contact structure such that $\Phi$ is closed and $d \eta=0$ is called cosymplectic structure. It is well known [7] that the cosymplectic structure is characterized by

$$
\begin{equation*}
\left(\bar{\nabla}_{X} \phi\right) Y=0, \quad\left(\bar{\nabla}_{X} \eta\right) Y=0 \tag{2.4}
\end{equation*}
$$

for all vector fields $X, Y$, on $\bar{M}$, where $\bar{\nabla}$ is the Levi-Civita connection of $g$. From the formula $\bar{\nabla}_{X} \phi=0$, it follows that $\bar{\nabla}_{X} \xi=0$.

Let $M$ be submanifold of an almost contact metric manifold $\bar{M}$ with induced metric $g$ and let $\nabla$ and $\nabla^{\perp}$ be the induced connections on the tangent bundle $T M$ and the normal bundle $T^{\perp} M$ of $M$, respectively. Denote by $\mathcal{F}(M)$ the algebra of smooth functions on $M$ and by $\Gamma(T M)$ the $\mathcal{F}(M)$-module of smooth sections of a vector bundle $T M$ over $M$, then Gauss and Weingarten formulae are given by

$$
\begin{align*}
& \bar{\nabla}_{X} Y=\nabla_{X} Y+h(X, Y),  \tag{2.5}\\
& \bar{\nabla}_{X} N=-A_{N} X+\nabla_{X}^{\perp} N \tag{2.6}
\end{align*}
$$

for each $X, Y \in \Gamma(T M)$ and $N \in \Gamma\left(T^{\perp} M\right)$, where $h$ and $A_{N}$ are the second fundamental form and the shape operator (corresponding to the normal vector field $N$ ), respectively for the immersion of $M$ into $\bar{M}$. They are related as

$$
\begin{equation*}
g(h(X, Y), N)=g\left(A_{N} X, Y\right) \tag{2.7}
\end{equation*}
$$

where $g$ denotes the Riemannian metric on $\bar{M}$ as well as the one induced on $M$ [8].

For any $X \in \Gamma(T M)$, we write

$$
\begin{equation*}
\phi X=P X+F X \tag{2.8}
\end{equation*}
$$

where $P X$ is the tangential component and $F X$ is the normal component of $\phi X$. Similarly for any $N \in \Gamma\left(T^{\perp} M\right)$, we write

$$
\begin{equation*}
\phi N=t N+f N, \tag{2.9}
\end{equation*}
$$

where $t N$ is the tangential component and $t N$ is the normal component of $\phi N$. If we denote the orthogonal complementary distribution of $F(T M)$ in $T^{\perp} M$ by $\mu$, then we have the direct sum

$$
\begin{equation*}
T^{\perp} M=F(T M) \oplus \mu . \tag{2.10}
\end{equation*}
$$

We can see that $\mu$ is an invariant subbundle with respect to $\phi$. Furthermore, the covariant derivatives of the tensor fields $P$ and $F$ are defined as

$$
\begin{align*}
& \left(\bar{\nabla}_{X} P\right) Y=\nabla_{X} P Y-P \nabla_{X} Y  \tag{2.11}\\
& \left(\bar{\nabla}_{X} F\right) Y=\nabla_{X}^{\perp} F Y-F \nabla_{X} Y
\end{align*}
$$

for any $X, Y \in \Gamma(T M)$.
A submanifold $M$ is said to be invariant if $F$ is identically zero, that is, $\phi X \in \Gamma(T M)$ for any $X \in \Gamma(T M)$. On the other hand, $M$ is said to be anti-invariant if $P$ is identically zero, that is, $\phi X \in \Gamma\left(T^{\perp} M\right)$, for any $X \in \Gamma(T M)$.

A submanifold $M$ of an almost contact metric manifold $\bar{M}$ is called totally umbilical if

$$
\begin{equation*}
h(X, Y)=g(X, Y) H \tag{2.12}
\end{equation*}
$$

for any $X, Y \in \Gamma(T M)$. The mean curvature vector $H$ is given by

$$
\begin{equation*}
H=\sum_{i=1}^{m} h\left(e_{i}, e_{i}\right) \tag{2.13}
\end{equation*}
$$

where $m$ is the dimension of $M$ and $\left\{e_{1}, e_{2}, \ldots, e_{m}\right\}$ is the local orthonormal frame on $M$. A submanifold $M$ is said to be totally geodesic if $h(X, Y)=0$ for each $X, Y \in \Gamma(T M)$ and is minimal if $H=0$ on $M$.

## 3. Slant Submanifolds

Throughout the section, we assume that $M$ is a slant submanifold of a cosymplectic manifold $\bar{M}$. We always consider such submanifold tangent to the structure vector field $\xi$. For each
nonzero vector $X$ tangent to $M$ at $x$, we denote by $0 \leq \theta(X) \leq \pi / 2$, the angle between $\phi X$ and $T_{x} M$, known as the Wirtinger angle of $X$. If the Wirtinger angle $\theta(X)$ is constant, that is, independent of the choice of $x \in M$ and $X \in T_{x} M-\{\xi\}$, then $M$ is said to be a slant submanifold [4]. In this case the constant angle $\theta$ is called slant angle of the slant submanifold. Obviously if $\theta=0, M$ is invariant and if $\theta=\pi / 2, M$ is an anti-invariant submanifold. A slant submanifold is said to be proper slant if it is neither invariant nor anti-invariant submanifold. If $M$ is a slant submanifold of an almost contact metric manifold, then the tangent bundle $T M$ is decomposed as

$$
\begin{equation*}
T M=\Phi \oplus\langle\xi\rangle, \tag{3.1}
\end{equation*}
$$

where $\langle\xi\rangle$ denotes the distribution spanned by the structure vector field $\xi$ and $\Phi$ is the complementary distribution of $\langle\xi\rangle$ in $T M$, known as the slant distribution.

We recall the following result for a slant submanifold.
Theorem 3.1 (see [3]). Let $M$ be a submanifold of an almost contact metric manifold $\bar{M}$, such that $\xi \in T M$. Then, $M$ is slant if and only if there exists a constant $\lambda \in[0,1]$ such that

$$
\begin{equation*}
P^{2}=\lambda(-I+\eta \otimes \xi) \tag{3.2}
\end{equation*}
$$

Furthermore, if $\theta$ is slant angle, then $\lambda=\cos ^{2} \theta$.
The following relations are straightforward consequence of (3.2):

$$
\begin{align*}
& g(P X, P Y)=\cos ^{2} \theta[g(X, Y)-\eta(X) \eta(Y)]  \tag{3.3}\\
& g(F X, F Y)=\sin ^{2} \theta[g(X, Y)-\eta(X) \eta(Y)] \tag{3.4}
\end{align*}
$$

for any $X, Y$ tangent to $M$.
Now, we prove the following.
Theorem 3.2. Let $M$ be a totally umbilical slant submanifold of a cosymplectic manifold $\bar{M}$. Then at least one of the following statements is ture:
(i) $M$ is an anti-invariant submanifold;
(ii) $M$ is a 1-dimensional submanifold;
(iii) If $M$ is a proper slant submanifold, then $H \in \Gamma(\mu)$,
where $H$ is the mean curvature vector of the submanifold $M$.
Proof. Let $M$ be a totally umbilical slant submanifold of a cosymplectic manifold $\bar{M}$, then for any $X, Y \in \Gamma(T M)$, we have

$$
\begin{equation*}
h(P X, P Y)=g(P X, P Y) H . \tag{3.5}
\end{equation*}
$$

From (2.5) and (3.3), we deduce that

$$
\begin{equation*}
\bar{\nabla}_{P X} P X-\nabla_{P X} P X=\cos ^{2} \theta\{g(X, X)-\eta(X) \eta(X)\} H \tag{3.6}
\end{equation*}
$$

Using (2.8) and the fact that $\bar{M}$ is cosymplectic we obtain that

$$
\begin{equation*}
\phi \bar{\nabla}_{P X} X-\bar{\nabla}_{P X} F X-\nabla_{P X} P X=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} H . \tag{3.7}
\end{equation*}
$$

Then from (2.5) and (2.6), we get

$$
\begin{equation*}
\phi \nabla_{P X} X+\phi h(X, P X)+A_{F X} P X-\nabla_{P X}^{\perp} F X-\nabla_{P X} P X=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} H \tag{3.8}
\end{equation*}
$$

Thus by (2.8) and (2.12), we obtain

$$
\begin{equation*}
P \nabla_{P X} X+F \nabla_{P X} X+g(P X, X) \phi H+A_{F X} P X-\nabla_{P X}^{\perp} F X-\nabla_{P X} P X=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} H \tag{3.9}
\end{equation*}
$$

Equating the normal components, we get

$$
\begin{equation*}
F \nabla_{P X} X-\nabla_{P X}^{\perp} F X=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} H \tag{3.10}
\end{equation*}
$$

On the other hand, from (3.4), we have

$$
\begin{equation*}
g(F X, F X)=\sin ^{2} \theta\{g(X, X)-\eta(X) \eta(X)\} \tag{3.11}
\end{equation*}
$$

for any $X \in \Gamma(T M)$. Taking the covariant derivative of the above equation with respect to $P X$, we obtain

$$
\begin{equation*}
2 g\left(\bar{\nabla}_{P X} F X, F X\right)=2 \sin ^{2} \theta g\left(\bar{\nabla}_{P X} X, X\right)-2 \sin ^{2} \theta \eta(X) g\left(\bar{\nabla}_{P X} X, \xi\right)-2 \sin ^{2} \theta \eta(X) g\left(X, \bar{\nabla}_{P X} \xi\right) \tag{3.12}
\end{equation*}
$$

Using the property of metric connection $\bar{\nabla}$, the last two terms of the right-hand side are cancelling each other, thus we have

$$
\begin{equation*}
g\left(\bar{\nabla}_{P X} F X, F X\right)=\sin ^{2} \theta g\left(\bar{\nabla}_{P X} X, X\right) \tag{3.13}
\end{equation*}
$$

Then by (2.5) and (2.6), we derive

$$
\begin{equation*}
g\left(\nabla_{P X}^{\perp} F X, F X\right)=\sin ^{2} \theta g\left(\nabla_{P X} X, X\right) \tag{3.14}
\end{equation*}
$$

Now, taking the inner product in (3.10) with $F X$, for any $X \in \Gamma(T M)$, then

$$
\begin{equation*}
g\left(F \nabla_{P X} X, F X\right)-g\left(\nabla_{P X}^{\perp} F X, F X\right)=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X) \tag{3.15}
\end{equation*}
$$

Then from (3.4) and (3.14), we obtain

$$
\begin{equation*}
-\sin ^{2} \theta \eta(X) \eta\left(\nabla_{P X} X\right)=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X) \tag{3.16}
\end{equation*}
$$

or

$$
\begin{equation*}
-\sin ^{2} \theta \eta(X) g\left(\nabla_{P X} X, \xi\right)=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X) \tag{3.17}
\end{equation*}
$$

Using (2.5), we derive

$$
\begin{equation*}
-\sin ^{2} \theta \eta(X) g\left(\bar{\nabla}_{P X} X, \xi\right)=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X) \tag{3.18}
\end{equation*}
$$

Since $\bar{\nabla}$ is the metric connection, then the above equation can be written as

$$
\begin{equation*}
\sin ^{2} \theta \eta(X) g\left(X, \bar{\nabla}_{P X} \xi\right)=\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X) \tag{3.19}
\end{equation*}
$$

As $\bar{M}$ is cosymplectic thus using the fact that $\bar{\nabla}_{P X} \xi=0$, the left hand side of the above equation vanishes identically, then

$$
\begin{equation*}
\cos ^{2} \theta\left\{\|X\|^{2}-\eta^{2}(X)\right\} g(H, F X)=0 \tag{3.20}
\end{equation*}
$$

Thus from (3.20), it follows that either $\theta=\pi / 2$ or $X=\xi$ or $H \in \Gamma(\mu)$, where $\mu$ is the invariant normal subbundle orthogonal to FTM. This completes the proof.

Theorem 3.3. Every totally umbilical proper slant submanifold $M$ of a cosymplectic manifold $\bar{M}$ is totally geodesic, provided $\nabla_{X}^{\perp} H \in \Gamma(\mu)$, for any $X \in T M$.

Proof. As $\bar{M}$ is cosymplectic, then we have

$$
\begin{equation*}
\bar{\nabla}_{U} \phi V=\phi \bar{\nabla}_{U} V \tag{3.21}
\end{equation*}
$$

for any $U, V \in \Gamma(T \bar{M})$. Using this fact and formulae (2.5) and (2.8) we obtain that

$$
\begin{equation*}
\bar{\nabla}_{X} P Y+\bar{\nabla}_{X} F Y=P \nabla_{X} Y+F \nabla_{X} Y+\phi h(X, Y) \tag{3.22}
\end{equation*}
$$

for any $X, Y \in \Gamma(T M)$. Then from (2.5), (2.6) and (2.12), we get

$$
\begin{equation*}
\nabla_{X} P Y+h(X, P Y)-A_{F Y} X+\nabla_{X}^{\perp} F Y=P \nabla_{X} Y+F \nabla_{X} Y+g(X, Y) \phi H \tag{3.23}
\end{equation*}
$$

Taking the inner product in (3.23) with $\phi H$ and using the fact that $H \in \Gamma(\mu)$ (by Theorem 3.2), we obtain

$$
\begin{equation*}
g(h(X, P Y), \phi H)+g\left(\nabla_{X}^{\perp} F Y, \phi H\right)=g(X, Y) g(\phi H, \phi H) \tag{3.24}
\end{equation*}
$$

Then from (2.2) and (2.12), we derive

$$
\begin{equation*}
g(X, P Y) g(H, \phi H)+g\left(\nabla_{X}^{\perp} F Y, \phi H\right)=g(X, Y) g(H, H) \tag{3.25}
\end{equation*}
$$

That is,

$$
\begin{equation*}
g\left(\nabla_{X}^{\perp} F Y, \phi H\right)=g(X, Y)\|H\|^{2} \tag{3.26}
\end{equation*}
$$

Now, we consider

$$
\begin{equation*}
\bar{\nabla}_{X} \phi H=\phi \bar{\nabla}_{X} H \tag{3.27}
\end{equation*}
$$

for any $X \in \Gamma(T M)$. From (2.6), we obtain

$$
\begin{equation*}
-A_{\phi H} X+\nabla_{X}^{\perp} \phi H=\phi\left(-A_{H} X+\nabla_{X}^{\perp} H\right) \tag{3.28}
\end{equation*}
$$

Thus, on using (2.8), (2.9), we get

$$
\begin{equation*}
-A_{\phi H} X+\nabla_{X}^{\perp} \phi H=-P A_{H} X-F A_{H} X+t \nabla{ }_{X}^{\perp} H+f \nabla_{X}^{\perp} H \tag{3.29}
\end{equation*}
$$

Taking the inner product with $F Y$, for any $Y \in \Gamma(T M)$, then

$$
\begin{equation*}
g\left(\nabla_{X}^{\perp} \phi H, F Y\right)=-g\left(F A_{H} X, F Y\right)+g\left(f \nabla_{X}^{\perp} H, F Y\right) \tag{3.30}
\end{equation*}
$$

Since $f \nabla \stackrel{\perp}{X} H \in \Gamma(\mu)$, then by (3.4) the above equation takes the form

$$
\begin{equation*}
g\left(\nabla_{X}^{\perp} \phi H, F Y\right)=-\sin ^{2} \theta\left\{g\left(A_{H} X, Y\right)-\eta\left(A_{H} X\right) \eta(Y)\right\} \tag{3.31}
\end{equation*}
$$

Using (2.6), (2.7), and (2.12), we get

$$
\begin{equation*}
g\left(\bar{\nabla}_{X} \phi H, F Y\right)=-\sin ^{2} \theta\{g(X, Y)-\eta(X) \eta(Y)\}\|H\|^{2} \tag{3.32}
\end{equation*}
$$

The above equation can be written as

$$
\begin{equation*}
\mathrm{g}\left(\bar{\nabla}_{X} F Y, \phi H\right)=\sin ^{2} \theta\{g(X, Y)-\eta(X) \eta(Y)\}\|H\|^{2} \tag{3.33}
\end{equation*}
$$

Again using the fact that $H \in \Gamma(\mu)$, then by (2.6), we obtain

$$
\begin{equation*}
g\left(\nabla_{X}^{\perp} F Y, \phi H\right)=\sin ^{2} \theta\{g(X, Y)-\eta(X) \eta(Y)\}\|H\|^{2} \tag{3.34}
\end{equation*}
$$

From (3.26) and (3.34), we derive

$$
\begin{equation*}
\left\{\cos ^{2} \theta g(X, Y)+\sin ^{2} \theta \eta(X) \eta(Y)\right\}\|H\|^{2}=0 \tag{3.35}
\end{equation*}
$$

Thus, (3.35) implies either $H=0$ or $\theta=\tan ^{-1}(\sqrt{-g(X, Y) / \eta(X) \eta(Y)})$, which is not possible, because the slant angle $\theta \in(0, \pi / 2)$. Hence, $M$ is totally geodesic in $\bar{M}$.

## Acknowledgment

The authors are grateful to the anonymous referee for his valuable comments and the first author is supported by the research Grant RG117/10AFR (University of Malaya).

## References

[1] B. Y. Chen, "Slant immersions," Bulletin of the Australian Mathematical Society, vol. 41, no. 1, pp. 135-147, 1990.
[2] B.-Y. Chen, Geometry of Slant Submanifolds, Katholieke Universiteit Leuven, Leuven, Belgium, 1990.
[3] J. L. Cabrerizo, A. Carriazo, L. M. Fernández, and M. Fernández, "Slant submanifolds in Sasakian manifolds," Glasgow Mathematical Journal, vol. 42, no. 1, pp. 125-138, 2000.
[4] A. Lotta, "Slant submanifolds in contact geometry," Bulletin Mathematical Society Roumanie, vol. 39, pp. 183-198, 1996.
[5] B. Şahin, "Every totally umbilical proper slant submanifold of a Kahler manifold is totally geodesic," Results in Mathematics, vol. 54, no. 1-2, pp. 167-172, 2009.
[6] D. E. Blair, Contact Manifolds in Riemannian Geometry, Springer-Verlag, New York, NY, USA, 1976.
[7] G. D. Ludden, "Submanifolds of cosymplectic manifolds," Journal of Differential Geometry, vol. 4, pp. 237-244, 1970.
[8] K. Yano and M. Kon, Structures on Manifolds, Series in Pure Mathematics, World Scientific Publishing, Singapore, Singapore, 1984.


