



*Gen. Math. Notes, Vol. 16, No. 2, June, 2013, pp.66-82*

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## On a Class of $\gamma$ -b-Open Sets in a Topological Space

Hariwan Z. Ibrahim

Department of Mathematics, Faculty of Science  
University of Zakho, Kurdistan-Region, Iraq  
E-mail: hariwan\_math@yahoo.com

(Received: 4-3-13 / Accepted: 7-4-13)

### Abstract

*In this paper, we introduce some weak separation axioms by utilizing the notions of  $\gamma$ -b-open sets and the  $\gamma$ -b-closure operator.*

**Keywords:**  $\gamma$ -b-open,  $\gamma$ -b-closure,  $\gamma D_b$ -set,  $\gamma$ -b- $T_0$ ,  $\gamma$ -b- $T_1$ ,  $\gamma$ -b- $T_2$ ,  $\gamma$ -b- $R_0$ ,  $\gamma$ -b- $R_1$ ,  $\gamma$ -b-continuous.

## 1 Introduction

In [1] Andrijevi introduced b-open sets, Kasahara [3] defined an operation  $\alpha$  on a topological space to introduce  $\alpha$ -closed graphs. Following the same technique, Ogata [6] defined an operation  $\gamma$  on a topological space and introduced  $\gamma$ -open sets.

In this paper, we introduce the notion of  $\gamma$ -b-open sets, and  $\gamma$ -b-irresolute in topological spaces. By utilizing these notions we introduce some weak separation axioms. Also we show that some basic properties of  $\gamma$ -b- $T_i$ ,  $\gamma$ -b- $D_i$  for  $i = 0, 1, 2$  spaces and we offer a new class of functions called  $\gamma$ -b-continuous functions and a new notion of the graph of a function called a  $\gamma$ -b-closed graph and investigate some of their fundamental properties.

## 2 Preliminaries

Let  $(X, \tau)$  be a topological space and  $A$  a subset of  $X$ . The closure of  $A$  and the interior of  $A$  are denoted by  $cl(A)$  and  $int(A)$ , respectively. A subset  $A$  is said to be b-open [1] if  $A \subseteq int(cl(A)) \cup cl(int(A))$ . The complement of a b-open set is said to be b-closed.

An operation  $\gamma$  [3] on a topology  $\tau$  is a mapping from  $\tau$  in to power set  $P(X)$  of  $X$  such that  $V \subset \gamma(V)$  for each  $V \in \tau$ , where  $\gamma(V)$  denotes the value of  $\gamma$  at  $V$ . A subset  $A$  of  $X$  with an operation  $\gamma$  on  $\tau$  is called  $\gamma$ -open [6] if for each  $x \in A$ , there exists an open set  $U$  such that  $x \in U$  and  $\gamma(U) \subset A$ . Then,  $\tau_\gamma$  denotes the set of all  $\gamma$ -open set in  $X$ . Clearly  $\tau_\gamma \subset \tau$ . Complements of  $\gamma$ -open sets are called  $\gamma$ -closed. The  $\gamma$ -closure [6] of a subset  $A$  of  $X$  with an operation  $\gamma$  on  $\tau$  is denoted by  $\tau_\gamma-cl(A)$  and is defined to be the intersection of all  $\gamma$ -closed sets containing  $A$ , and the  $\tau_\gamma$ -interior [4] of  $A$  is denoted by  $\tau_\gamma-int(A)$  and defined to be the union of all  $\gamma$ -open sets of  $X$  contained in  $A$ . A subset  $A$  of  $X$  with an operation  $\gamma$  on  $\tau$  is called be  $\gamma$ -preopen set [5] if and only if  $A \subseteq \tau_\gamma-int(\tau_\gamma-cl(A))$ . A subset  $A$  of  $X$  with an operation  $\gamma$  on  $\tau$  is called be  $\gamma$ - $\beta$ -open set [2] if  $A \subseteq \tau_\gamma-cl(\tau_\gamma-int(\tau_\gamma-cl(A)))$ . A topological  $X$  with an operation  $\gamma$  on  $\tau$  is said to be  $\gamma$ -regular [6] if for each  $x \in X$  and for each open neighborhood  $V$  of  $x$ , there exists an open neighborhood  $U$  of  $x$  such that  $\gamma(U)$  contained in  $V$ . It is also to be noted that  $\tau = \tau_\gamma$  if and only if  $X$  is a  $\gamma$ -regular space [6].

## 3 $\gamma$ -b-Open Sets

**Definition 3.1** A subset  $A$  of a topological space  $(X, \tau)$  is said to be  $\gamma$ -b-open if  $A \subset \tau_\gamma-int(\tau_\gamma-cl(A)) \cup \tau_\gamma-cl(\tau_\gamma-int(A))$ .

The complement of a  $\gamma$ -b-open set is said to be  $\gamma$ -b-closed. The family of all  $\gamma$ -b-open (resp.  $\gamma$ -b-closed) sets in a topological space  $(X, \tau)$  is denoted by  $\gamma bO(X, \tau)$  (resp.  $\gamma bC(X, \tau)$ ).

**Definition 3.2** Let  $A$  be a subset of a topological space  $(X, \tau)$ . The intersection of all  $\gamma$ -b-closed sets containing  $A$  is called the  $\gamma$ -b-closure of  $A$  and is denoted by  $\gamma cl_b(A)$ .

**Definition 3.3** Let  $(X, \tau)$  be a topological space. A subset  $U$  of  $X$  is called a  $\gamma$ -b-neighbourhood of a point  $x \in X$  if there exists a  $\gamma$ -b-open set  $V$  such that  $x \in V \subset U$ .

**Theorem 3.4** For the  $\gamma$ -b-closure of subsets  $A, B$  in a topological space  $(X, \tau)$ , the following properties hold:

1.  $A$  is  $\gamma$ - $b$ -closed in  $(X, \tau)$  if and only if  $A = \gamma cl_b(A)$ .
2. If  $A \subset B$  then  $\gamma cl_b(A) \subset \gamma cl_b(B)$ .
3.  $\gamma cl_b(A)$  is  $\gamma$ - $b$ -closed, that is  $\gamma cl_b(A) = \gamma cl_b(\gamma cl_b(A))$ .
4.  $x \in \gamma cl_b(A)$  if and only if  $A \cap V \neq \phi$  for every  $\gamma$ - $b$ -open set  $V$  of  $X$  containing  $x$ .

**Proof.** It is obvious.

**Theorem 3.5** For a family  $\{A_\alpha : \alpha \in \Delta\}$  of subsets a topological space  $(X, \tau)$ , the following properties hold:

1.  $\gamma cl_b(\bigcap_{\alpha \in \Delta} A_\alpha) \subset \bigcap_{\alpha \in \Delta} \gamma cl_b(A_\alpha)$ .
2.  $\gamma cl_b(\bigcup_{\alpha \in \Delta} A_\alpha) \supset \bigcup_{\alpha \in \Delta} \gamma cl_b(A_\alpha)$ .

**Proof.**

1. Since  $\bigcap_{\alpha \in \Delta} A_\alpha \subset A_\alpha$  for each  $\alpha \in \Delta$ , by Theorem 3.4 we have  $\gamma cl_b(\bigcap_{\alpha \in \Delta} A_\alpha) \subset \gamma cl_b(A_\alpha)$  for each  $\alpha \in \Delta$  and hence  $\gamma cl_b(\bigcap_{\alpha \in \Delta} A_\alpha) \subset \bigcap_{\alpha \in \Delta} \gamma cl_b(A_\alpha)$ .
2. Since  $A_\alpha \subset \bigcup_{\alpha \in \Delta} A_\alpha$  for each  $\alpha \in \Delta$ , by Theorem 3.4 we have  $\gamma cl_b(A_\alpha) \subset \gamma cl_b(\bigcup_{\alpha \in \Delta} A_\alpha)$  for each  $\alpha \in \Delta$  and hence  $\bigcup_{\alpha \in \Delta} \gamma cl_b(A_\alpha) \subset \gamma cl_b(\bigcup_{\alpha \in \Delta} A_\alpha)$ .

**Theorem 3.6** Every  $\gamma$ -preopen set is  $\gamma$ - $b$ -open.

**Proof.** It follows from the Definitions.

The converse of the above Theorem need not be true by the following Example.

**Example 3.7** Let  $X = \{a, b, c\}$ ,  $\tau = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$  and  $\gamma(A) = A$  for all  $A \in \tau$ . Here  $\{a, b\}$  is not  $\gamma$ -preopen however it is  $\gamma$ - $b$ -open.

**Corollary 3.8** Every  $\gamma$ -open set is  $\gamma$ - $b$ -open.

**Proof.** It follows from Theorem 3.6.

**Theorem 3.9** Every  $\gamma$ - $b$ -open set is  $\gamma$ - $\beta$ -open.

**Proof.** It follows from the Definitions.

**Remark 3.10** The concepts of  $b$ -open and  $\gamma$ - $b$ -open sets are independent, while in a  $\gamma$ -regular space these concepts are equivalent.

**Example 3.11** Let  $X = \{a, b, c\}$  and  $\tau = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$ . Define an operation  $\gamma$  on  $\tau$  by

$$\gamma(A) = \begin{cases} \{a\} & \text{if } A = \{a\} \\ A \cup \{c\} & \text{if } A \neq \{a\} \end{cases}$$

Clearly,  $\tau_\gamma = \{\phi, \{a\}, X\}$ . Then  $\{b\}$  is  $b$ -open but not  $\gamma$ - $b$ -open. Again, if we define  $\gamma$  on  $\tau$  by  $\gamma(A) = X$ , then  $\{c\}$  is  $\gamma$ - $b$ -open but not  $b$ -open.

**Theorem 3.12** An arbitrary union of  $\gamma$ - $b$ -open sets is  $\gamma$ - $b$ -open.

**Proof.** Let  $\{A_k : k \in \Delta\}$  be a family of  $\gamma$ - $b$ -open sets. Then for each  $k$ ,  $A_k \subseteq \tau_\gamma\text{-int}(\tau_\gamma\text{-cl}(A_k)) \cup \tau_\gamma\text{-cl}(\tau_\gamma\text{-int}(A_k))$  and so

$$\begin{aligned} \bigcup_{k \in \Delta} A_k &\subseteq \bigcup_{k \in \Delta} [\tau_\gamma\text{-int}(\tau_\gamma\text{-cl}(A_k)) \cup \tau_\gamma\text{-cl}(\tau_\gamma\text{-int}(A_k))] \\ &\subseteq [\bigcup_{k \in \Delta} \tau_\gamma\text{-int}(\tau_\gamma\text{-cl}(A_k))] \cup [\bigcup_{k \in \Delta} \tau_\gamma\text{-cl}(\tau_\gamma\text{-int}(A_k))] \\ &\subseteq [\tau_\gamma\text{-int}(\bigcup_{k \in \Delta} \tau_\gamma\text{-cl}(A_k))] \cup [\tau_\gamma\text{-cl}(\bigcup_{k \in \Delta} \tau_\gamma\text{-int}(A_k))] \\ &\subseteq [\tau_\gamma\text{-int}(\tau_\gamma\text{-cl}(\bigcup_{k \in \Delta} A_k))] \cup [\tau_\gamma\text{-cl}(\tau_\gamma\text{-int}(\bigcup_{k \in \Delta} A_k))]. \end{aligned}$$

Therefore,  $\bigcup_{k \in \Delta} A_k$  is  $\gamma$ - $b$ -open.

**Remark 3.13**

1. An arbitrary intersection of  $\gamma$ - $b$ -closed sets is  $\gamma$ - $b$ -closed.
2. The intersection of even two  $\gamma$ - $b$ -open sets may not be  $\gamma$ - $b$ -open.

**Example 3.14** Let  $X = \{a, b, c\}$  and  $\tau = \{\phi, \{a\}, \{a, b\}, X\}$ . Define an operation  $\gamma$  on  $\tau$  by

$$\gamma(A) = \begin{cases} A & \text{if } A = \{a, b\} \\ X & \text{otherwise} \end{cases}$$

Clearly,  $\tau_\gamma = \{\phi, \{a, b\}, X\}$ , take  $A = \{a, c\}$  and  $B = \{b, c\}$  are  $\gamma$ - $b$ -open. Then  $A \cap B = \{c\}$ , which is not a  $\gamma$ - $b$ -open set.

**Definition 3.15** A subset  $A$  of a topological space  $(X, \tau)$  is called a  $\gamma D_b$ -set if there are two  $U, V \in \gamma bO(X, \tau)$  such that  $U \neq X$  and  $A = U \setminus V$ .

It is true that every  $\gamma$ - $b$ -open set  $U$  different from  $X$  is a  $\gamma D_b$ -set if  $A = U$  and  $V = \phi$ . So, we can observe the following.

**Remark 3.16** Every proper  $\gamma$ - $b$ -open set is a  $\gamma D_b$ -set.

**Definition 3.17** A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is said to be

1.  $\gamma$ -b- $D_0$  if for any pair of distinct points  $x$  and  $y$  of  $X$  there exists a  $\gamma D_b$ -set of  $X$  containing  $x$  but not  $y$  or a  $\gamma D_b$ -set of  $X$  containing  $y$  but not  $x$ .
2.  $\gamma$ -b- $D_1$  if for any pair of distinct points  $x$  and  $y$  of  $X$  there exists a  $\gamma D_b$ -set of  $X$  containing  $x$  but not  $y$  and a  $\gamma D_b$ -set of  $X$  containing  $y$  but not  $x$ .
3.  $\gamma$ -b- $D_2$  if for any pair of distinct points  $x$  and  $y$  of  $X$  there exist disjoint  $\gamma D_b$ -set  $G$  and  $E$  of  $X$  containing  $x$  and  $y$ , respectively.

**Definition 3.18** A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is said to be

1.  $\gamma$ -b- $T_0$  (resp.  $\gamma$ -pre  $T_0$  [5] and  $\gamma$ - $\beta$   $T_0$  [2]) if for any pair of distinct points  $x$  and  $y$  of  $X$  there exists a  $\gamma$ -b-open (resp.  $\gamma$ -preopen and  $\gamma$ - $\beta$ -open) set  $U$  in  $X$  containing  $x$  but not  $y$  or a  $\gamma$ -b-open (resp.  $\gamma$ -preopen and  $\gamma$ - $\beta$ -open) set  $V$  in  $X$  containing  $y$  but not  $x$ .
2.  $\gamma$ -b- $T_1$  (resp.  $\gamma$ -pre  $T_1$  [5] and  $\gamma$ - $\beta$   $T_1$  [2]) if for any pair of distinct points  $x$  and  $y$  of  $X$  there exists a  $\gamma$ -b-open (resp.  $\gamma$ -preopen and  $\gamma$ - $\beta$ -open) set  $U$  in  $X$  containing  $x$  but not  $y$  and a  $\gamma$ -b-open (resp.  $\gamma$ -preopen and  $\gamma$ - $\beta$ -open) set  $V$  in  $X$  containing  $y$  but not  $x$ .
3.  $\gamma$ -b- $T_2$  (resp.  $\gamma$ -pre  $T_2$  [5] and  $\gamma$ - $\beta$   $T_2$  [2]) if for any pair of distinct points  $x$  and  $y$  of  $X$  there exist disjoint  $\gamma$ -b-open (resp.  $\gamma$ -preopen and  $\gamma$ - $\beta$ -open) sets  $U$  and  $V$  in  $X$  containing  $x$  and  $y$ , respectively.

**Remark 3.19** For a topological space  $(X, \tau)$ , the following properties hold:

1. If  $(X, \tau)$  is  $\gamma$ -b- $T_i$ , then it is  $\gamma$ -b- $T_{i-1}$ , for  $i = 1, 2$ .
2. If  $(X, \tau)$  is  $\gamma$ -b- $T_i$ , then it is  $\gamma$ -b- $D_i$ , for  $i = 0, 1, 2$ .
3. If  $(X, \tau)$  is  $\gamma$ -b- $D_i$ , then it is  $\gamma$ -b- $D_{i-1}$ , for  $i = 1, 2$ .
4. If  $(X, \tau)$  is  $\gamma$ -pre  $T_i$ , then it is  $\gamma$ -b- $T_i$ , for  $i = 0, 1, 2$ .
5. If  $(X, \tau)$  is  $\gamma$ -b- $T_i$ , then it is  $\gamma$ - $\beta$   $T_i$ , for  $i = 0, 1, 2$ .

By Remark 3.19 we have the following diagram.

$$\begin{array}{ccccc}
 \gamma\text{-pre } T_2 & \longrightarrow & \gamma\text{-pre } T_1 & \longrightarrow & \gamma\text{-pre } T_0 \\
 \downarrow & & \downarrow & & \downarrow \\
 \gamma\text{-b-}T_2 & \longrightarrow & \gamma\text{-b-}T_1 & \longrightarrow & \gamma\text{-b-}T_0 \\
 \downarrow & & \downarrow & & \downarrow \\
 \gamma\text{-}\beta T_2 & \longrightarrow & \gamma\text{-}\beta T_1 & \longrightarrow & \gamma\text{-}\beta T_0
 \end{array}$$

**Theorem 3.20** *A topological space  $(X, \tau)$  is  $\gamma$ - $b$ - $D_1$  if and only if it is  $\gamma$ - $b$ - $D_2$ .*

**Proof.** sufficiency. Follows from Remark 3.19.

Necessity. Let  $x, y \in X$ ,  $x \neq y$ . Then there exist  $\gamma D_b$ -sets  $G_1, G_2$  in  $X$  such that  $x \in G_1$ ,  $y \notin G_1$  and  $y \in G_2$ ,  $x \notin G_2$ . Let  $G_1 = U_1 \setminus U_2$  and  $G_2 = U_3 \setminus U_4$ , where  $U_1, U_2, U_3$  and  $U_4$  are  $\gamma$ - $b$ -open sets in  $X$ . From  $x \notin G_2$ , it follows that either  $x \notin U_3$  or  $x \in U_3$  and  $x \in U_4$ . We discuss the two cases separately.

(i)  $x \notin U_3$ . By  $y \notin G_1$  we have two subcases:

(a)  $y \notin U_1$ . From  $x \in U_1 \setminus U_2$ , it follows that  $x \in U_1 \setminus (U_2 \cup U_3)$ , and by  $y \in U_3 \setminus U_4$  we have  $y \in U_3 \setminus (U_1 \cup U_4)$ . Therefore  $(U_1 \setminus (U_2 \cup U_3)) \cap (U_3 \setminus (U_1 \cup U_4)) = \phi$ .

(b)  $y \in U_1$  and  $y \in U_2$ . We have  $x \in U_1 \setminus U_2$ , and  $y \in U_2$ . Therefore  $(U_1 \setminus U_2) \cap U_2 = \phi$ .

(ii)  $x \in U_3$  and  $x \in U_4$ . We have  $y \in U_3 \setminus U_4$  and  $x \in U_4$ . Hence  $(U_3 \setminus U_4) \cap U_4 = \phi$ . Therefore  $X$  is  $\gamma$ - $b$ - $D_2$ .

**Definition 3.21** *A point  $x \in X$  which has only  $X$  as the  $\gamma$ - $b$ -neighborhood is called a  $\gamma$ - $b$ -neat point.*

**Theorem 3.22** *If a topological space  $(X, \tau)$  is  $\gamma$ - $b$ - $D_1$ , then it has no  $\gamma$ - $b$ -neat point.*

**Proof.** Since  $(X, \tau)$  is  $\gamma$ - $b$ - $D_1$ , so each point  $x$  of  $X$  is contained in a  $\gamma D_b$ -set  $A = U \setminus V$  and thus in  $U$ . By definition  $U \neq X$ . This implies that  $x$  is not a  $\gamma$ - $b$ -neat point.

**Theorem 3.23** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ - $b$ - $T_0$  if and only if for each pair of distinct points  $x, y$  of  $X$ ,  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ .*

**Theorem 3.24** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ - $b$ - $T_1$  if and only if the singletons are  $\gamma$ - $b$ -closed sets.*

**Proof.** Let  $(X, \tau)$  be  $\gamma$ -b- $T_1$  and  $x$  any point of  $X$ . Suppose  $y \in X \setminus \{x\}$ , then  $x \neq y$  and so there exists a  $\gamma$ -b-open set  $U$  such that  $y \in U$  but  $x \notin U$ . Consequently  $y \in U \subset X \setminus \{x\}$  i.e.,  $X \setminus \{x\} = \cup\{U : y \in X \setminus \{x\}\}$  which is  $\gamma$ -b-open.

Conversely, suppose  $\{p\}$  is  $\gamma$ -b-closed for every  $p \in X$ . Let  $x, y \in X$  with  $x \neq y$ . Now  $x \neq y$  implies  $y \in X \setminus \{x\}$ . Hence  $X \setminus \{x\}$  is a  $\gamma$ -b-open set contains  $y$  but not  $x$ . Similarly  $X \setminus \{y\}$  is a  $\gamma$ -b-open set contains  $x$  but not  $y$ . Accordingly  $X$  is a  $\gamma$ -b- $T_1$  space.

**Definition 3.25** A topological space  $(X, \tau)$  is  $\gamma$ -b-symmetric if for  $x$  and  $y$  in  $X$ ,  $x \in \gamma cl_b(\{y\})$  implies  $y \in \gamma cl_b(\{x\})$ .

**Theorem 3.26** If a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is a  $\gamma$ -b- $T_1$  space, then it is  $\gamma$ -b-symmetric.

**Proof.** Suppose that  $y \notin \gamma cl_b(\{x\})$ . Then, since  $x \neq y$ , there exists a  $\gamma$ -b-open set  $U$  containing  $x$  such that  $y \notin U$  and hence  $x \notin \gamma cl_b(\{y\})$ . This shows that  $x \in \gamma cl_b(\{y\})$  implies  $y \in \gamma cl_b(\{x\})$ . Therefore,  $(X, \tau)$  is  $\gamma$ -b-symmetric.

**Definition 3.27** Let  $(X, \tau)$  and  $(Y, \sigma)$  be two topological spaces and  $\gamma, \beta$  operations on  $\tau, \sigma$ , respectively. A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\gamma$ -b-irresolute if for each  $x \in X$  and each  $\beta$ -b-open set  $V$  containing  $f(x)$ , there is a  $\gamma$ -b-open set  $U$  in  $X$  containing  $x$  such that  $f(U) \subset V$ .

**Theorem 3.28** If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is a  $\gamma$ -b-irresolute surjective function and  $E$  is a  $\beta D_b$ -set in  $Y$ , then the inverse image of  $E$  is a  $\gamma D_b$ -set in  $X$ .

**Proof.** Let  $E$  be a  $\beta D_b$ -set in  $Y$ . Then there are  $\beta$ -b-open sets  $U_1$  and  $U_2$  in  $Y$  such that  $E = U_1 \setminus U_2$  and  $U_1 \neq Y$ . By the  $\gamma$ -b-irresolute of  $f$ ,  $f^{-1}(U_1)$  and  $f^{-1}(U_2)$  are  $\gamma$ -b-open in  $X$ . Since  $U_1 \neq Y$  and  $f$  is surjective, we have  $f^{-1}(U_1) \neq X$ . Hence,  $f^{-1}(E) = f^{-1}(U_1) \setminus f^{-1}(U_2)$  is a  $\gamma D_b$ -set.

**Theorem 3.29** If  $(Y, \sigma)$  is  $\beta$ -b- $D_1$  and  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\gamma$ -b-irresolute bijective, then  $(X, \tau)$  is  $\gamma$ -b- $D_1$ .

**Proof.** Suppose that  $Y$  is a  $\beta$ -b- $D_1$  space. Let  $x$  and  $y$  be any pair of distinct points in  $X$ . Since  $f$  is injective and  $Y$  is  $\beta$ -b- $D_1$ , there exist  $\beta D_b$ -set  $G_x$  and  $G_y$  of  $Y$  containing  $f(x)$  and  $f(y)$  respectively, such that  $f(x) \notin G_y$  and  $f(y) \notin G_x$ . By Theorem 3.28,  $f^{-1}(G_x)$  and  $f^{-1}(G_y)$  are  $\gamma D_b$ -set in  $X$  containing  $x$  and  $y$ , respectively, such that  $x \notin f^{-1}(G_y)$  and  $y \notin f^{-1}(G_x)$ . This implies that  $X$  is a  $\gamma$ -b- $D_1$  space.

**Theorem 3.30** A topological space  $(X, \tau)$  is  $\gamma$ -b- $D_1$  if for each pair of distinct points  $x, y \in X$ , there exists a  $\gamma$ -b-irresolute surjective function  $f : (X, \tau) \rightarrow (Y, \sigma)$ , where  $Y$  is a  $\beta$ -b- $D_1$  space such that  $f(x)$  and  $f(y)$  are distinct.

**Proof.** Let  $x$  and  $y$  be any pair of distinct points in  $X$ . By hypothesis, there exists a  $\gamma$ -b-irresolute, surjective function  $f$  of a space  $X$  onto a  $\beta$ -b- $D_1$  space  $Y$  such that  $f(x) \neq f(y)$ . By Theorem 3.20, there exist disjoint  $\beta D_b$ -set  $G_x$  and  $G_y$  in  $Y$  such that  $f(x) \in G_x$  and  $f(y) \in G_y$ . Since  $f$  is  $\gamma$ -b-irresolute and surjective, by Theorem 3.28,  $f^{-1}(G_x)$  and  $f^{-1}(G_y)$  are disjoint  $\gamma D_b$ -sets in  $X$  containing  $x$  and  $y$ , respectively. hence by Theorem 3.20,  $X$  is  $\gamma$ -b- $D_1$  space.

## 4 $\gamma$ -b- $R_0$ and $\gamma$ -b- $R_1$ Spaces

**Definition 4.1** Let  $A$  be a subset of a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ . The  $\gamma$ -b-kernel of  $A$ , denoted by  $\gamma ker_b(A)$  is defined to be the set

$$\gamma ker_b(A) = \cap \{U \in \gamma bO(X) : A \subset U\}.$$

**Theorem 4.2** Let  $(X, \tau)$  be a topological space with an operation  $\gamma$  on  $\tau$  and  $x \in X$ . Then  $y \in \gamma ker_b(\{x\})$  if and only if  $x \in \gamma cl_b(\{y\})$ .

**Proof.** Suppose that  $y \notin \gamma ker_b(\{x\})$ . Then there exists a  $\gamma$ -b-open set  $V$  containing  $x$  such that  $y \notin V$ . Therefore, we have  $x \notin \gamma cl_b(\{y\})$ . The proof of the converse case can be done similarly.

**Lemma 4.3** Let  $(X, \tau)$  be a topological space and  $A$  be a subset of  $X$ . Then,  $\gamma ker_b(A) = \{x \in X : \gamma cl_b(\{x\}) \cap A \neq \phi\}$ .

**Proof.** Let  $x \in \gamma ker_b(A)$  and suppose  $\gamma cl_b(\{x\}) \cap A = \phi$ . Hence  $x \notin X \setminus \gamma cl_b(\{x\})$  which is a  $\gamma$ -b-open set containing  $A$ . This is impossible, since  $x \in \gamma ker_b(A)$ . Consequently,  $\gamma cl_b(\{x\}) \cap A \neq \phi$ . Next, let  $x \in X$  such that  $\gamma cl_b(\{x\}) \cap A \neq \phi$  and suppose that  $x \notin \gamma ker_b(A)$ . Then, there exists a  $\gamma$ -b-open set  $V$  containing  $A$  and  $x \notin V$ . Let  $y \in \gamma cl_b(\{x\}) \cap A$ . Hence,  $V$  is a  $\gamma$ -b-neighborhood of  $y$  which does not contain  $x$ . By this contradiction  $x \in \gamma ker_b(A)$  and the claim.

**Remark 4.4** The following properties hold for the subsets  $A, B$  of a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ :

1.  $A \subset \gamma ker_b(A)$ , if  $A$  is  $\gamma$ -b-open in  $(X, \tau)$ , then  $A = \gamma ker_b(A)$ .
2. If  $A \subset B$ , then  $\gamma ker_b(A) \subset \gamma ker_b(B)$ .

**Definition 4.5** A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is said to be  $\gamma$ -b- $R_0$  if every  $\gamma$ -b-open set  $U$  and  $x \in U$  implies  $\gamma cl_b(\{x\}) \subset U$ .

**Theorem 4.6** For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following properties are equivalent:



1.  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .
2. For any  $F \in \gamma bC(X)$ ,  $x \notin F$  implies  $F \subset U$  and  $x \notin U$  for some  $U \in \gamma bO(X)$ .
3. For any  $F \in \gamma bC(X)$ ,  $x \notin F$  implies  $F \cap \gamma cl_b(\{x\}) = \phi$ .
4. For any distinct points  $x$  and  $y$  of  $X$ , either  $\gamma cl_b(\{x\}) = \gamma cl_b(\{y\})$  or  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ .

**Proof.** (1)  $\Rightarrow$  (2). Let  $F \in \gamma bC(X)$  and  $x \notin F$ . Then by (1)  $\gamma cl_b(\{x\}) \subset X \setminus F$ . Set  $U = X \setminus \gamma cl_b(\{x\})$ , then  $U$  is  $\gamma$ -b-open set such that  $F \subset U$  and  $x \notin U$ .

(2)  $\Rightarrow$  (3). Let  $F \in \gamma bC(X)$  and  $x \notin F$ . There exists  $U \in \gamma bO(X)$  such that  $F \subset U$  and  $x \notin U$ . Since  $U \in \gamma bO(X)$ ,  $U \cap \gamma cl_b(\{x\}) = \phi$  and  $F \cap \gamma cl_b(\{x\}) = \phi$ .

(3)  $\Rightarrow$  (4). Suppose that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$  for distinct points  $x, y \in X$ . There exists  $z \in \gamma cl_b(\{x\})$  such that  $z \notin \gamma cl_b(\{y\})$  (or  $z \in \gamma cl_b(\{y\})$  such that  $z \notin \gamma cl_b(\{x\})$ ). There exists  $V \in \gamma bO(X)$  such that  $y \notin V$  and  $z \in V$ ; hence  $x \in V$ . Therefore, we have  $x \notin \gamma cl_b(\{y\})$ . By (3), we obtain  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ . The proof for otherwise is similar.

(4)  $\Rightarrow$  (1). let  $V \in \gamma bO(X)$  and  $x \in V$ . For each  $y \notin V$ ,  $x \neq y$  and  $x \notin \gamma cl_b(\{y\})$ . This shows that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . By (4),  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$  for each  $y \in X \setminus V$  and hence  $\gamma cl_b(\{x\}) \cap (\bigcup_{y \in X \setminus V} \gamma cl_b(\{y\})) = \phi$ . On other hand, since  $V \in \gamma bO(X)$  and  $y \in X \setminus V$ , we have  $\gamma cl_b(\{y\}) \subset X \setminus V$  and hence  $X \setminus V = \bigcup_{y \in X \setminus V} \gamma cl_b(\{y\})$ . Therefore, we obtain  $(X \setminus V) \cap \gamma cl_b(\{x\}) = \phi$  and  $\gamma cl_b(\{x\}) \subset V$ . This shows that  $(X, \tau)$  is a  $\gamma$ -b- $R_0$  space.

**Theorem 4.7** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ -b- $T_1$  if and only if  $(X, \tau)$  is  $\gamma$ -b- $T_0$  and  $\gamma$ -b- $R_0$  space.*

**Proof.** Necessity. Let  $U$  be any  $\gamma$ -b-open set of  $(X, \tau)$  and  $x \in U$ . Then by Theorem 3.24, we have  $\gamma cl_b(\{x\}) \subset U$  and so by Remark 3.19, it is clear that  $X$  is  $\gamma$ -b- $T_0$  and  $\gamma$ -b- $R_0$  space.

Sufficiency. Let  $x$  and  $y$  be any distinct points of  $X$ . Since  $X$  is  $\gamma$ -b- $T_0$ , there exists a  $\gamma$ -b-open set  $U$  such that  $x \in U$  and  $y \notin U$ . As  $x \in U$  implies that  $\gamma cl_b(\{x\}) \subset U$ . Since  $y \notin U$ , so  $y \notin \gamma cl_b(\{x\})$ . Hence  $y \in V = X \setminus \gamma cl_b(\{x\})$  and it is clear that  $x \notin V$ . Hence it follows that there exist  $\gamma$ -b-open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively, such that  $y \notin U$  and  $x \notin V$ . This implies that  $X$  is  $\gamma$ -b- $T_1$ .

**Theorem 4.8** *For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following properties are equivalent:*

1.  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .

2.  $x \in \gamma cl_b(\{y\})$  if and only if  $y \in \gamma cl_b(\{x\})$ , for any points  $x$  and  $y$  in  $X$ .

**Proof.** (1)  $\Rightarrow$  (2). Assume that  $X$  is  $\gamma$ -b- $R_0$ . Let  $x \in \gamma cl_b(\{y\})$  and  $V$  be any  $\gamma$ -b-open set such that  $y \in V$ . Now by hypothesis,  $x \in V$ . Therefore, every  $\gamma$ -b-open set which contain  $y$  contains  $x$ . Hence  $y \in \gamma cl_b(\{x\})$ .

(2)  $\Rightarrow$  (1). Let  $U$  be a  $\gamma$ -b-open set and  $x \in U$ . If  $y \notin U$ , then  $x \notin \gamma cl_b(\{y\})$  and hence  $y \notin \gamma cl_b(\{x\})$ . This implies that  $\gamma cl_b(\{x\}) \subset U$ . Hence  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .

We observed that by Definition 3.25 and Theorem 4.8 the notions of  $\gamma$ -b-symmetric and  $\gamma$ -b- $R_0$  are equivalent.

**Theorem 4.9** *The following statements are equivalent for any points  $x$  and  $y$  in a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ :*

1.  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$ .
2.  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ .

**Proof.** (1)  $\Rightarrow$  (2). Suppose that  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$ , then there exists a point  $z$  in  $X$  such that  $z \in \gamma ker_b(\{x\})$  and  $z \notin \gamma ker_b(\{y\})$ . From  $z \in \gamma ker_b(\{x\})$  it follows that  $\{x\} \cap \gamma cl_b(\{z\}) \neq \phi$  which implies  $x \in \gamma cl_b(\{z\})$ . By  $z \notin \gamma ker_b(\{y\})$ , we have  $\{y\} \cap \gamma cl_b(\{z\}) = \phi$ . Since  $x \in \gamma cl_b(\{z\})$ ,  $\gamma cl_b(\{x\}) \subset \gamma cl_b(\{z\})$  and  $\{y\} \cap \gamma cl_b(\{x\}) = \phi$ . Therefore, it follows that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . Now  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$  implies that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ .

(2)  $\Rightarrow$  (1). Suppose that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . Then there exists a point  $z$  in  $X$  such that  $z \in \gamma cl_b(\{x\})$  and  $z \notin \gamma cl_b(\{y\})$ . Then, there exists a  $\gamma$ -b-open set containing  $z$  and therefore  $x$  but not  $y$ , namely,  $y \notin \gamma ker_b(\{x\})$  and thus  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$ .

**Theorem 4.10** *Let  $(X, \tau)$  be a topological space and  $\gamma$  be an operation on  $\tau$ . Then  $\cap\{\gamma cl_b(\{x\}) : x \in X\} = \phi$  if and only if  $\gamma ker_b(\{x\}) \neq X$  for every  $x \in X$ .*

**Proof.** Necessity. Suppose that  $\cap\{\gamma cl_b(\{x\}) : x \in X\} = \phi$ . Assume that there is a point  $y$  in  $X$  such that  $\gamma ker_b(\{y\}) = X$ . Let  $x$  be any point of  $X$ . Then  $x \in V$  for every  $\gamma$ -b-open set  $V$  containing  $y$  and hence  $y \in \gamma cl_b(\{x\})$  for any  $x \in X$ . This implies that  $y \in \cap\{\gamma cl_b(\{x\}) : x \in X\}$ . But this is a contradiction.

Sufficiency. Assume that  $\gamma ker_b(\{x\}) \neq X$  for every  $x \in X$ . If there exists a point  $y$  in  $X$  such that  $y \in \cap\{\gamma cl_b(\{x\}) : x \in X\}$ , then every  $\gamma$ -b-open set containing  $y$  must contain every point of  $X$ . This implies that the space  $X$  is the unique  $\gamma$ -b-open set containing  $y$ . Hence  $\gamma ker_b(\{y\}) = X$  which is a contradiction. Therefore,  $\cap\{\gamma cl_b(\{x\}) : x \in X\} = \phi$ .

**Theorem 4.11** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ - $b$ - $R_0$  if and only if for every  $x$  and  $y$  in  $X$ ,  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$  implies  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ .*

**Proof.** Necessity. Suppose that  $(X, \tau)$  is  $\gamma$ - $b$ - $R_0$  and  $x, y \in X$  such that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . Then, there exists  $z \in \gamma cl_b(\{x\})$  such that  $z \notin \gamma cl_b(\{y\})$  (or  $z \in \gamma cl_b(\{y\})$  such that  $z \notin \gamma cl_b(\{x\})$ ). There exists  $V \in \gamma bO(X)$  such that  $y \notin V$  and  $z \in V$ , hence  $x \in V$ . Therefore, we have  $x \notin \gamma cl_b(\{y\})$ . Thus  $x \in [X \setminus \gamma cl_b(\{y\})] \in \gamma bO(X)$ , which implies  $\gamma cl_b(\{x\}) \subset [X \setminus \gamma cl_b(\{y\})]$  and  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ . The proof for otherwise is similar.

Sufficiency. Let  $V \in \gamma bO(X)$  and let  $x \in V$ . We still show that  $\gamma cl_b(\{x\}) \subset V$ . Let  $y \notin V$ , i.e.,  $y \in X \setminus V$ . Then  $x \neq y$  and  $x \notin \gamma cl_b(\{y\})$ . This shows that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . By assumption,  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ . Hence  $y \notin \gamma cl_b(\{x\})$  and therefore  $\gamma cl_b(\{x\}) \subset V$ .

**Theorem 4.12** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ - $b$ - $R_0$  if and only if for any points  $x$  and  $y$  in  $X$ ,  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$  implies  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\}) = \phi$ .*

**Proof.** Suppose that  $(X, \tau)$  is a  $\gamma$ - $b$ - $R_0$  space. Thus by Theorem 4.9, for any points  $x$  and  $y$  in  $X$  if  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$  then  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . Now we prove that  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\}) = \phi$ . Assume that  $z \in \gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\})$ . By  $z \in \gamma ker_b(\{x\})$  and Theorem 4.2, it follows that  $x \in \gamma cl_b(\{z\})$ . Since  $x \in \gamma cl_b(\{x\})$ , by Theorem 4.6,  $\gamma cl_b(\{x\}) = \gamma cl_b(\{z\})$ . Similarly, we have  $\gamma cl_b(\{y\}) = \gamma cl_b(\{z\}) = \gamma cl_b(\{x\})$ . This is a contradiction. Therefore, we have  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\}) = \phi$ .

Conversely, let  $(X, \tau)$  be a topological space such that for any points  $x$  and  $y$  in  $X$ ,  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$  implies  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\}) = \phi$ . If  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ , then by Theorem 4.9,  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$ . Hence,  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{y\}) = \phi$  which implies  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$ . Because  $z \in \gamma cl_b(\{x\})$  implies that  $x \in \gamma ker_b(\{z\})$  and therefore  $\gamma ker_b(\{x\}) \cap \gamma ker_b(\{z\}) \neq \phi$ . By hypothesis, we have  $\gamma ker_b(\{x\}) = \gamma ker_b(\{z\})$ . Then  $z \in \gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\})$  implies that  $\gamma ker_b(\{x\}) = \gamma ker_b(\{z\}) = \gamma ker_b(\{y\})$ . This is a contradiction. Therefore,  $\gamma cl_b(\{x\}) \cap \gamma cl_b(\{y\}) = \phi$  and by Theorem 4.6  $(X, \tau)$  is a  $\gamma$ - $b$ - $R_0$  space.

**Theorem 4.13** *For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following properties are equivalent:*

1.  $(X, \tau)$  is a  $\gamma$ - $b$ - $R_0$  space.
2. For any nonempty set  $A$  and  $G \in \gamma bO(X)$  such that  $A \cap G \neq \phi$ , there exists  $F \in \gamma bC(X)$  such that  $A \cap F \neq \phi$  and  $F \subset G$ .

3. Any  $G \in \gamma bO(X)$ ,  $G = \cup\{F \in \gamma bC(X): F \subset G\}$ .
4. Any  $F \in \gamma bC(X)$ ,  $F = \cap\{G \in \gamma bO(X): F \subset G\}$ .
5. For every  $x \in X$ ,  $\gamma cl_b(\{x\}) \subset \gamma ker_b(\{x\})$ .

**Proof.** (1)  $\Rightarrow$  (2). Let  $A$  be a nonempty subset of  $X$  and  $G \in \gamma bO(X)$  such that  $A \cap G \neq \phi$ . There exists  $x \in A \cap G$ . Since  $x \in G \in \gamma bO(X)$ ,  $\gamma cl_b(\{x\}) \subset G$ . Set  $F = \gamma cl_b(\{x\})$ , then  $F \in \gamma bC(X)$ ,  $F \subset G$  and  $A \cap F \neq \phi$ . (2)  $\Rightarrow$  (3). Let  $G \in \gamma bO(X)$ , then  $G \supseteq \cup\{F \in \gamma bC(X): F \subset G\}$ . Let  $x$  be any point of  $G$ . There exists  $F \in \gamma bC(X)$  such that  $x \in F$  and  $F \subset G$ . Therefore, we have  $x \in F \subset \cup\{F \in \gamma bC(X): F \subset G\}$  and hence  $G = \cup\{F \in \gamma bC(X): F \subset G\}$ .

(3)  $\Rightarrow$  (4). This is obvious.

(4)  $\Rightarrow$  (5). Let  $x$  be any point of  $X$  and  $y \notin \gamma ker_b(\{x\})$ . There exists  $V \in \gamma bO(X)$  such that  $x \in V$  and  $y \notin V$ , hence  $\gamma cl_b(\{y\}) \cap V = \phi$ . By (4)  $(\cap\{G \in \gamma bO(X): \gamma cl_b(\{y\}) \subset G\}) \cap V = \phi$  and there exists  $G \in \gamma bO(X)$  such that  $x \notin G$  and  $\gamma cl_b(\{y\}) \subset G$ . Therefore  $\gamma cl_b(\{x\}) \cap G = \phi$  and  $y \notin \gamma cl_b(\{x\})$ . Consequently, we obtain  $\gamma cl_b(\{x\}) \subset \gamma ker_b(\{x\})$ .

(5)  $\Rightarrow$  (1). Let  $G \in \gamma bO(X)$  and  $x \in G$ . Let  $y \in \gamma ker_b(\{x\})$ , then  $x \in \gamma cl_b(\{y\})$  and  $y \in G$ . This implies that  $\gamma ker_b(\{x\}) \subset G$ . Therefore, we obtain  $x \in \gamma cl_b(\{x\}) \subset \gamma ker_b(\{x\}) \subset G$ . This shows that  $(X, \tau)$  is a  $\gamma$ -b- $R_0$  space.

**Corollary 4.14** For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following properties are equivalent:

1.  $(X, \tau)$  is a  $\gamma$ -b- $R_0$  space.
2.  $\gamma cl_b(\{x\}) = \gamma ker_b(\{x\})$  for all  $x \in X$ .

**Proof.** (1)  $\Rightarrow$  (2). Suppose that  $(X, \tau)$  is a  $\gamma$ -b- $R_0$  space. By Theorem 4.13,  $\gamma cl_b(\{x\}) \subset \gamma ker_b(\{x\})$  for each  $x \in X$ . Let  $y \in \gamma ker_b(\{x\})$ , then  $x \in \gamma cl_b(\{y\})$  and by Theorem 4.6  $\gamma cl_b(\{x\}) = \gamma cl_b(\{y\})$ . Therefore,  $y \in \gamma cl_b(\{x\})$  and hence  $\gamma ker_b(\{x\}) \subset \gamma cl_b(\{x\})$ . This shows that  $\gamma cl_b(\{x\}) = \gamma ker_b(\{x\})$ .

(2)  $\Rightarrow$  (1). This is obvious by Theorem 4.13.

**Theorem 4.15** For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following properties are equivalent:

1.  $(X, \tau)$  is a  $\gamma$ -b- $R_0$  space.
2. If  $F$  is  $\gamma$ -b-closed, then  $F = \gamma ker_b(F)$ .
3. If  $F$  is  $\gamma$ -b-closed and  $x \in F$ , then  $\gamma ker_b(\{x\}) \subset F$ .
4. If  $x \in X$ , then  $\gamma ker_b(\{x\}) \subset \gamma cl_b(\{x\})$ .

**Proof.** (1)  $\Rightarrow$  (2). Let  $F$  be a  $\gamma$ -b-closed and  $x \notin F$ . Thus  $(X \setminus F)$  is a  $\gamma$ -b-open set containing  $x$ . Since  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .  $\gamma cl_b(\{x\}) \subset (X \setminus F)$ . Thus  $\gamma cl_b(\{x\}) \cap F = \phi$  and by Lemma 4.3  $x \notin \gamma ker_b(F)$ . Therefore  $\gamma ker_b(F) = F$ . (2)  $\Rightarrow$  (3). In general,  $A \subset B$  implies  $\gamma ker_b(A) \subset \gamma ker_b(B)$ . Therefore, it follows from (2) that  $\gamma ker_b(\{x\}) \subset \gamma ker_b(F) = F$ .

(3)  $\Rightarrow$  (4). Since  $x \in \gamma cl_b(\{x\})$  and  $\gamma cl_b(\{x\})$  is  $\gamma$ -b-closed, by (3),  $\gamma ker_b(\{x\}) \subset \gamma cl_b(\{x\})$ .

(4)  $\Rightarrow$  (1). We show the implication by using Theorem 4.8. Let  $x \in \gamma cl_b(\{y\})$ . Then by Theorem 4.2,  $y \in \gamma ker_b(\{x\})$ . Since  $x \in \gamma cl_b(\{x\})$  and  $\gamma cl_b(\{x\})$  is  $\gamma$ -b-closed, by (4) we obtain  $y \in \gamma ker_b(\{x\}) \subset \gamma cl_b(\{x\})$ . Therefore  $x \in \gamma cl_b(\{y\})$  implies  $y \in \gamma cl_b(\{x\})$ . The converse is obvious and  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .

**Definition 4.16** A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , is said to be  $\gamma$ -b- $R_1$  if for  $x, y$  in  $X$  with  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ , there exist disjoint  $\gamma$ -b-open sets  $U$  and  $V$  such that  $\gamma cl_b(\{x\}) \subset U$  and  $\gamma cl_b(\{y\}) \subset V$ .

**Theorem 4.17** A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ -b- $R_1$  if it is  $\gamma$ -b- $T_2$ .

**Proof.** Let  $x$  and  $y$  be any points of  $X$  such that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . By Remark 3.19, every  $\gamma$ -b- $T_2$  space is  $\gamma$ -b- $T_1$ . Therefore, by Theorem 3.24,  $\gamma cl_b(\{x\}) = \{x\}$ ,  $\gamma cl_b(\{y\}) = \{y\}$  and hence  $\{x\} \neq \{y\}$ . Since  $(X, \tau)$  is  $\gamma$ -b- $T_2$ , there exist disjoint  $\gamma$ -b-open sets  $U$  and  $V$  such that  $\gamma cl_b(\{x\}) = \{x\} \subset U$  and  $\gamma cl_b(\{y\}) = \{y\} \subset V$ . This shows that  $(X, \tau)$  is  $\gamma$ -b- $R_1$ .

**Theorem 4.18** For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following are equivalent:

1.  $(X, \tau)$  is  $\gamma$ -b- $T_2$ .
2.  $(X, \tau)$  is  $\gamma$ -b- $R_1$  and  $\gamma$ -b- $T_1$ .
3.  $(X, \tau)$  is  $\gamma$ -b- $R_1$  and  $\gamma$ -b- $T_0$ .

**Proof.** Proof is easy and hence omitted.

**Theorem 4.19** For a topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$ , the following statements are equivalent:

1.  $(X, \tau)$  is  $\gamma$ -b- $R_1$ .
2. If  $x, y \in X$  such that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ , then there exist  $\gamma$ -b-closed sets  $F_1$  and  $F_2$  such that  $x \in F_1$ ,  $y \notin F_1$ ,  $y \in F_2$ ,  $x \notin F_2$  and  $X = F_1 \cup F_2$ .

**Proof.** Proof is easy and hence omitted.

**Theorem 4.20** *If  $(X, \tau)$  is  $\gamma$ -b- $R_1$ , then  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .*

**Proof.** Let  $U$  be  $\gamma$ -b-open such that  $x \in U$ . If  $y \notin U$ , since  $x \notin \gamma cl_b(\{y\})$ , we have  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . So, there exists a  $\gamma$ -b-open set  $V$  such that  $\gamma cl_b(\{y\}) \subset V$  and  $x \notin V$ , which implies  $y \notin \gamma cl_b(\{x\})$ . Hence  $\gamma cl_b(\{x\}) \subset U$ . Therefore,  $(X, \tau)$  is  $\gamma$ -b- $R_0$ .

The converse of the above Theorem need not be true as shown in the following example.

**Example 4.21** *Consider  $X = \{a, b, c\}$  with the discrete topology on  $X$ . Define an operation  $\gamma$  on  $\tau$  by*

$$\gamma(A) = \begin{cases} A & \text{if } A = \{a, b\} \text{ or } \{a, c\} \text{ or } \{b, c\} \\ X & \text{otherwise} \end{cases}$$

*Then  $X$  is a  $\gamma$ -b- $R_0$  space but not a  $\gamma$ -b- $R_1$  space.*

**Theorem 4.22** *A topological space  $(X, \tau)$  with an operation  $\gamma$  on  $\tau$  is  $\gamma$ -b- $R_1$  if and only if for  $x, y \in X$ ,  $\gamma ker_b(\{x\}) \neq \gamma ker_b(\{y\})$ , there exist disjoint  $\gamma$ -b-open sets  $U$  and  $V$  such that  $\gamma cl_b(\{x\}) \subset U$  and  $\gamma cl_b(\{y\}) \subset V$ .*

**Proof.** It follows from Theorem 4.9.

**Theorem 4.23** *A topological space  $(X, \tau)$  is  $\gamma$ -b- $R_1$  if and only if the inclusion  $x \in X \setminus \gamma cl_b(\{y\})$  implies that  $x$  and  $y$  have disjoint  $\gamma$ -b-open neighborhoods.*

**Proof.** Necessity. Let  $x \in X \setminus \gamma cl_b(\{y\})$ . Then  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$  and  $x$  and  $y$  have disjoint  $\gamma$ -b-open neighborhoods.

Sufficiency. First, we show that  $(X, \tau)$  is  $\gamma$ -b- $R_0$ . Let  $U$  be a  $\gamma$ -b-open set and  $x \in U$ . Suppose that  $y \notin U$ . Then,  $\gamma cl_b(\{y\}) \cap U = \phi$  and  $x \notin \gamma cl_b(\{y\})$ . There exist  $\gamma$ -b-open sets  $U_x$  and  $U_y$  such that  $x \in U_x$ ,  $y \in U_y$  and  $U_x \cap U_y = \phi$ . Hence,  $\gamma cl_b(\{x\}) \subset \gamma cl_b(U_x)$  and  $\gamma cl_b(\{x\}) \cap U_y \subset \gamma cl_b(U_x) \cap U_y = \phi$ . Therefore,  $y \notin \gamma cl_b(\{x\})$ . Consequently,  $\gamma cl_b(\{x\}) \subset U$  and  $(X, \tau)$  is  $\gamma$ -b- $R_0$ . Next, we show that  $(X, \tau)$  is  $\gamma$ -b- $R_1$ . Suppose that  $\gamma cl_b(\{x\}) \neq \gamma cl_b(\{y\})$ . Then, we can assume that there exists  $z \in \gamma cl_b(\{x\})$  such that  $z \notin \gamma cl_b(\{y\})$ . There exist  $\gamma$ -b-open sets  $V_z$  and  $V_y$  such that  $z \in V_z$ ,  $y \in V_y$  and  $V_z \cap V_y = \phi$ . Since  $z \in \gamma cl_b(\{x\})$ ,  $x \in V_z$ . Since  $(X, \tau)$  is  $\gamma$ -b- $R_0$ , we obtain  $\gamma cl_b(\{x\}) \subset V_z$ ,  $\gamma cl_b(\{y\}) \subset V_y$  and  $V_z \cap V_y = \phi$ . This shows that  $(X, \tau)$  is  $\gamma$ -b- $R_1$ .

## 5 $\gamma$ -b-Continuous Functions and $\gamma$ -b-Closed Graphs

**Definition 5.1** *A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\gamma$ -b-continuous if for every open set  $V$  of  $Y$ ,  $f^{-1}(V)$  is  $\gamma$ -b-open in  $X$ .*

**Theorem 5.2** *The following are equivalent for a function  $f : (X, \tau) \rightarrow (Y, \sigma)$ :*

1.  $f$  is  $\gamma$ - $b$ -continuous.
2. The inverse image of every closed set in  $Y$  is  $\gamma$ - $b$ -closed in  $X$ .
3. For each subset  $A$  of  $X$ ,  $f(\gamma cl_b(A)) \subset cl(f(A))$ .
4. For each subset  $B$  of  $Y$ ,  $\gamma cl_b(f^{-1}(B)) \subset f^{-1}(cl(B))$ .

**Proof.** (1)  $\Leftrightarrow$  (2). Obvious.

(3)  $\Leftrightarrow$  (4). Let  $B$  be any subset of  $Y$ . Then by (3), we have  $f(\gamma cl_b(f^{-1}(B))) \subset cl(f(f^{-1}(B))) \subset cl(B)$ . This implies  $\gamma cl_b(f^{-1}(B)) \subset f^{-1}(cl(B))$ .

Conversely, let  $B = f(A)$  where  $A$  is a subset of  $X$ . Then, by (4), we have,  $\gamma cl_b(A) \subset \gamma cl_b(f^{-1}(f(A))) \subset f^{-1}(cl(f(A)))$ . Thus,  $f(\gamma cl_b(A)) \subset cl(f(A))$ .

(2)  $\Rightarrow$  (4). Let  $B \subset Y$ . Since  $f^{-1}(cl(B))$  is  $\gamma$ - $b$ -closed and  $f^{-1}(B) \subset f^{-1}(cl(B))$ , then  $\gamma cl_b(f^{-1}(B)) \subset f^{-1}(cl(B))$ .

(4)  $\Rightarrow$  (2). Let  $K \subset Y$  be a closed set. By (4),  $\gamma cl_b(f^{-1}(K)) \subset f^{-1}(cl(K)) = f^{-1}(K)$ . Thus,  $f^{-1}(K)$  is  $\gamma$ - $b$ -closed.

**Definition 5.3** *For a function  $f : (X, \tau) \rightarrow (Y, \sigma)$ , the graph  $G(f) = \{(x, f(x)) : x \in X\}$  is said to be  $\gamma$ - $b$ -closed if for each  $(x, y) \notin G(f)$ , there exist a  $\gamma$ - $b$ -open set  $U$  containing  $x$  and an open set  $V$  containing  $y$  such that  $(U \times V) \cap G(f) = \phi$ .*

**Lemma 5.4** *The function  $f : (X, \tau) \rightarrow (Y, \sigma)$  has an  $\gamma$ - $b$ -closed graph if and only if for each  $x \in X$  and  $y \in Y$  such that  $y \neq f(x)$ , there exist a  $\gamma$ - $b$ -open set  $U$  and an open set  $V$  containing  $x$  and  $y$  respectively, such that  $f(U) \cap V = \phi$ .*

**Proof.** It follows readily from the above definition.

**Theorem 5.5** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is an injective function with the  $\gamma$ - $b$ -closed graph, then  $X$  is  $\gamma$ - $b$ - $T_1$ .*

**Proof.** Let  $x$  and  $y$  be two distinct points of  $X$ . Then  $f(x) \neq f(y)$ . Thus there exist a  $\gamma$ - $b$ -open set  $U$  and an open set  $V$  containing  $x$  and  $f(y)$ , respectively, such that  $f(U) \cap V = \phi$ . Therefore  $y \notin U$  and it follows that  $X$  is  $\gamma$ - $b$ - $T_1$ .

**Theorem 5.6** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is an injective  $\gamma$ - $b$ -continuous with a  $\gamma$ - $b$ -closed graph  $G(f)$ , then  $X$  is  $\gamma$ - $b$ - $T_2$ .*

**Proof.** Let  $x_1$  and  $x_2$  be any distinct points of  $X$ . Then  $f(x_1) \neq f(x_2)$ , so  $(x_1, f(x_2)) \in (X \times Y) \setminus G(f)$ . Since the graph  $G(f)$  is  $\gamma$ -b-closed, there exist a  $\gamma$ -b-open set  $U$  containing  $x_1$  and open set  $V$  containing  $f(x_2)$  such that  $f(U) \cap V = \phi$ . Since  $f$  is  $\gamma$ -b-continuous,  $f^{-1}(V)$  is a  $\gamma$ -b-open set containing  $x_2$  such that  $U \cap f^{-1}(V) = \phi$ . Hence  $X$  is  $\gamma$ -b- $T_2$ .

Recall that a space  $X$  is said to be  $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist an open set  $U$  containing  $x$  but not  $y$  and an open set  $V$  containing  $y$  but not  $x$ .

**Theorem 5.7** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is an surjective function with the  $\gamma$ -b-closed graph, then  $Y$  is  $T_1$ .*

**Proof.** Let  $y_1$  and  $y_2$  be two distinct points of  $Y$ . Since  $f$  is surjective, there exists  $x$  in  $X$  such that  $f(x) = y_2$ . Therefore  $(x, y_1) \notin G(f)$ . By Lemma 5.4, there exist  $\gamma$ -b-open set  $U$  and an open set  $V$  containing  $x$  and  $y_1$  respectively, such that  $f(U) \cap V = \phi$ . We obtain an open set  $V$  containing  $y_1$  which does not contain  $y_2$ . It follows that  $y_2 \notin V$ . Hence,  $Y$  is  $T_1$ .

**Definition 5.8** *A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $\gamma$ -b- $W$ -continuous if for each  $x \in X$  and each open set  $V$  of  $Y$  containing  $f(x)$ , there exists a  $\gamma$ -b-open set  $U$  in  $X$  containing  $x$  such that  $f(U) \subset cl(V)$ .*

**Theorem 5.9** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is  $\gamma$ -b- $W$ -continuous and  $Y$  is Hausdorff, then  $G(f)$  is  $\gamma$ -b-closed.*

**Proof.** Suppose that  $(x, y) \notin G(f)$ , then  $f(x) \neq y$ . By the fact that  $Y$  is Hausdorff, there exist open sets  $W$  and  $V$  such that  $f(x) \in W$ ,  $y \in V$  and  $V \cap W = \phi$ . It follows that  $cl(W) \cap V = \phi$ . Since  $f$  is  $\gamma$ -b- $W$ -continuous, there exists a  $\gamma$ -b-open set  $U$  containing  $x$  such that  $f(U) \subset cl(W)$ . Hence, we have  $f(U) \cap V = \phi$ . This means that  $G(f)$  is  $\gamma$ -b-closed.

**Definition 5.10** *A subset  $A$  of a space  $X$  is said to be  $\gamma$ -b-compact relative to  $X$  if every cover of  $A$  by  $\gamma$ -b-open sets of  $X$  has a finite subcover.*

**Theorem 5.11** *Let  $f : (X, \tau) \rightarrow (Y, \sigma)$  have a  $\gamma$ -b-closed graph. If  $K$  is  $\gamma$ -b-compact relative to  $X$ , then  $f(K)$  is closed in  $Y$ .*

**Proof.** Suppose that  $y \notin f(K)$ . For each  $x \in K$ ,  $f(x) \neq y$ . By lemma 5.4, there exists a  $\gamma$ -b-open set  $U_x$  containing  $x$  and an open neighbourhood  $V_x$  of  $y$  such that  $f(U_x) \cap V_x = \phi$ . The family  $\{U_x : x \in K\}$  is a cover of  $K$  by  $\gamma$ -b-open sets of  $X$  and there exists a finite subset  $K_0$  of  $K$  such that  $K \subset \cup\{U_x : x \in K_0\}$ . Put  $V = \cap\{V_x : x \in K_0\}$ . Then  $V$  is an open neighbourhood of  $y$  and  $f(K) \cap V = \phi$ . This means that  $f(K)$  is closed in  $Y$ .



**Theorem 5.12** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  has a  $\gamma$ -b-closed graph  $G(f)$ , then for each  $x \in X$ .  $\{f(x)\} = \cap\{cl(f(A)) : A \text{ is } \gamma\text{-b-open set containing } x\}$ .*

**Proof.** Suppose that  $y \neq f(x)$  and  $y \in \cap\{cl(f(A)) : A \text{ is } \gamma\text{-b-open set containing } x\}$ . Then  $y \in cl(f(A))$  for each  $\gamma$ -b-open set  $A$  containing  $x$ . This implies that for each open set  $B$  containing  $y$ ,  $B \cap f(A) \neq \phi$ . Since  $(x, y) \notin G(f)$  and  $G(f)$  is a  $\gamma$ -b-closed graph, this is a contradiction.

**Definition 5.13** *A function  $f : (X, \tau) \rightarrow (Y, \sigma)$  is called a  $\gamma$ -b-open if the image of every  $\gamma$ -b-open set in  $X$  is open in  $Y$ .*

**Theorem 5.14** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is a surjective  $\gamma$ -b-open function with a  $\gamma$ -b-closed graph  $G(f)$ , then  $Y$  is  $T_2$ .*

**Proof.** Let  $y_1$  and  $y_2$  be any two distinct points of  $Y$ . Since  $f$  is surjective  $f(x) = y_1$  for some  $x \in X$  and  $(x, y_2) \in (X \times Y) \setminus G(f)$ . This implies that there exist a  $\gamma$ -b-open set  $A$  of  $X$  and an open set  $B$  of  $Y$  such that  $(x, y_2) \in (A \times B)$  and  $(A \times B) \cap G(f) = \phi$ . We have  $f(A) \cap B = \phi$ . Since  $f$  is  $\gamma$ -b-open, then  $f(A)$  is open such that  $f(x) = y_1 \in f(A)$ . Thus,  $Y$  is  $T_2$ .

**Theorem 5.15** *If  $f : (X, \tau) \rightarrow (Y, \sigma)$  is a  $\gamma$ -b-continuous injective function and  $Y$  is  $T_2$ , then  $X$  is  $\gamma$ -b- $T_2$ .*

**Proof.** Let  $x$  and  $y$  in  $X$  be any pair of distinct points, then there exist disjoint open sets  $A$  and  $B$  in  $Y$  such that  $f(x) \in A$  and  $f(y) \in B$ . Since  $f$  is  $\gamma$ -b-continuous,  $f^{-1}(A)$  and  $f^{-1}(B)$  are  $\gamma$ -b-open in  $X$  containing  $x$  and  $y$  respectively, we have  $f^{-1}(A) \cap f^{-1}(B) = \phi$ . Thus,  $X$  is  $\gamma$ -b- $T_2$ .

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