

## THE SCHRÖDER EQUATION AND ASYMPTOTIC PROPERTIES OF LINEAR DELAY DIFFERENTIAL EQUATIONS

JAN ČERMÁK

ABSTRACT. We study the asymptotic behaviour of solutions of the differential equation

$$\dot{x}(t) = -p(t)[x(t) - kx(t - \tau(t))] + q(t), \quad t \in I = [t_0, \infty),$$

where  $k \neq 0$  is a scalar,  $p$  is a positive function and  $\tau$  is a positive and unbounded delay. Our aim is to show that under some asymptotic bounds on  $q$  the behaviour (as  $t \rightarrow \infty$ ) of all solutions of this equation can be estimated via a solution of the Schröder equation

$$\varphi(t - \tau(t)) = \lambda\varphi(t), \quad t \in I$$

with a suitable positive parameter  $\lambda$ .

### 1. INTRODUCTION AND PRELIMINARIES

This paper discusses the asymptotic properties of solutions of the delay differential equation

$$(1.1) \quad \dot{x}(t) = -p(t)[x(t) - kx(t - \tau(t))] + q(t), \quad t \in I = [t_0, \infty),$$

where  $k \neq 0$  is a real constant,  $p, q \in C(I)$ ,  $p > 0$  on  $I$ ,  $\tau \in C^1(I)$ ,  $\tau > 0$ ,  $t - \tau(t) \rightarrow \infty$  as  $t \rightarrow \infty$  and  $0 < \zeta \leq \dot{\tau} < 1$  on  $I$  for a real scalar  $\zeta$ . Throughout this paper we assume that these assumptions on  $\tau$  are fulfilled (the remaining requirements on  $p$  and  $q$  will be introduced later).

Equation (1.1) with such a delay has been investigated in many particular cases. The well known pantograph equation

$$(1.2) \quad \dot{x}(t) = ax(\lambda t) + bx(t)$$

may serve as a prototype of (1.1). The name *pantograph* originated from the work of Ockendon & Taylor [18] on the collection of current by the pantograph head of an electric locomotive. Equations of similar forms appear in many applications such as astrophysics, probability theory on algebraic structures, spectral problem of the Schrödinger equations or quantum mechanics (see [1], [19] or [20]). Particularly, the nonhomogeneous pantograph equation

$$(1.3) \quad \dot{x}(t) = ax(\lambda t) + bx(t) + q(t)$$

---

1991 *Mathematics Subject Classification.* 34K25; Secondary 39B22.

*Key words and phrases.* Delay differential equation, Schröder equation, asymptotic behaviour.

This paper is in final form and no version of it will be submitted for publication elsewhere. The research was supported by the grant # 201/01/0079 of the Czech Grant Agency.

was derived in [7] as the mathematical model for a problem in electric locomotion. Among the works on equations (1.2), (1.3) we can mention especially those by Kato & McLeod [10] and Lim [15].

The qualitative investigations concerning (1.2) and (1.3) were later extended to more general cases, e.g., to the vector case and nonautonomous case, to equations with a variable (unbounded) delay and to neutral equations (see [8], [9], [13], [14] or [16]). For further related results see also [2], [6], and [11].

Particularly, Makay & Terjéki [17] established conditions under which all solutions of

$$\dot{x}(t) = -p(t)[x(t) - x(\lambda t)]$$

are asymptotically logarithmically periodic. The generalization of this result has been done in [5], where the asymptotic behaviour of all solutions of

$$(1.4) \quad \dot{x}(t) = -p(t)[x(t) - kx(t - \tau(t))]$$

was related to the behaviour of the Schröder functional equation

$$(1.5) \quad \varphi(t - \tau(t)) = \lambda\varphi(t), \quad t \in I,$$

where

$$(1.6) \quad \lambda = \sup\{1 - \dot{\tau}(t), t \in I\}.$$

Our aim is to establish asymptotic conditions on the forcing term  $q$  under which results of this type remain valid also for equation (1.1).

Note that equation (1.1) with a positive coefficient at  $x(t)$  has been studied in [3], where the asymptotics of solutions have been determined by means of the behaviour of a solution of the auxiliary differential equation

$$\dot{x}(t) = p(t)x(t).$$

Nevertheless, we show that certain similarities in the asymptotics of solutions in both sign cases can be observed.

By a solution of equation (1.1) (and other delay equations occurring in this paper) we mean a real valued function  $x \in C([\tau(t_0), \infty))$  satisfying the given equation for all  $t \in [t_0, \infty)$ . Similarly we introduce the notion of a solution for the Schröder equation (1.5).

Using the step method we can easily prove the following existence result.

**Proposition 1.** *Consider equation (1.5), where  $\lambda$  is given by (1.6). Let  $\varphi_0 \in C^1(I_0)$ , where  $I_0 = [t_0 - \tau(t_0), t_0]$ , be a positive function satisfying  $\dot{\varphi}_0 > 0$  on  $I_0$  and*

$$(\varphi_0 \circ (\text{id} - \tau))^{(j)}(t_0) = \lambda\varphi_0^{(j)}(t_0), \quad j = 0, 1.$$

*Then there exists a unique positive solution  $\varphi \in C^1(I_0 \cup I)$  of (1.5) such that  $\varphi(t) \rightarrow \infty$  as  $t \rightarrow \infty$ ,  $\dot{\varphi}$  is positive and bounded on  $I$  and  $\varphi \equiv \varphi_0$  on  $I_0$ .*

## 2. RESULTS AND PROOFS

In this section, we present asymptotic bounds for all solutions  $x$  of (1.1). We recall that all the assumptions imposed on  $\tau$  in Section 1 are fulfilled and suppose that  $\varphi$  is a solution of the corresponding Schröder equation with the properties guaranteed by Proposition 1.

First we state the following auxiliary result.

**Proposition 2.** *Let  $\varphi$  be a solution of (1.5) from Proposition 1. Let  $x$  be a solution of the equation*

$$(2.1) \quad \dot{x}(t) = -a(t)x(t) + b(t)x(t - \tau(t)) + f(t), \quad t \in I,$$

where  $a, b, f \in C(I)$ ,  $a(t) \geq L/(\varphi(t))^\alpha$ ,  $0 < |b(t)| \leq Ka(t)$  for all  $t \in I$  and suitable reals  $L, K > 0$ ,  $\alpha < 1$ . If  $f(t) = O((\varphi(t))^\beta)$  as  $t \rightarrow \infty$  for a real  $\beta$ , then

$$x(t) = O((\varphi(t))^\gamma) \quad \text{as } t \rightarrow \infty, \quad \gamma > \max(\alpha + \beta, \log K / \log \lambda^{-1}).$$

*Proof.* This result has been proved in particular cases  $a(t) \equiv a = \text{const} > 0$  ([4, Lemma 3.3]) and  $f \equiv 0$  ([5, Theorem 3.1]). The generalization of both proofs to our case is quite simple and is therefore omitted.  $\square$

**Proposition 3.** *Let  $\varphi$  be a solution of (1.5) from Proposition 1. Let  $x$  be a solution of (1.1), where  $k \neq 0$ ,  $p, q \in C^1(I)$ ,  $p(t) \geq L/(\varphi(t))^\alpha$ ,  $\dot{p}(t) \leq Mp(t)/(\varphi(t))^\theta$  for suitable reals  $L, M > 0$  and  $\alpha < \theta \leq 1$ . If  $q(t) = O((\varphi(t))^\beta)$  as  $t \rightarrow \infty$ ,  $\dot{q}(t) = O((\varphi(t))^{\beta-\tilde{\theta}})$  as  $t \rightarrow \infty$  for suitable reals  $\beta$  and  $\alpha < \tilde{\theta} < \theta$ , then*

$$(2.2) \quad x(t) = O((\varphi(t))^\delta) \quad \text{as } t \rightarrow \infty$$

and

$$(2.3) \quad \dot{x}(t) = O((\varphi(t))^{\delta-\tilde{\theta}}) \quad \text{as } t \rightarrow \infty,$$

where  $\delta > \max(\alpha + \beta, \log |k| / \log \lambda^{-1})$ .

*Proof.* The asymptotic relation (2.2) follows immediately from Proposition 2. We prove the validity of (2.3).

If we introduce the function  $y = \dot{x}$ , then  $y$  defines a solution of the delay equation

$$\dot{y}(t) = -\left[p(t) - \frac{\dot{p}(t)}{p(t)}\right]y(t) + k(1 - \dot{\tau}(t))p(t)y(t - \tau(t)) + \dot{q}(t) - \frac{\dot{p}(t)}{p(t)}q(t), \quad t \in I,$$

which is equation (2.1) with coefficients  $a(t) = p(t) - \dot{p}(t)/p(t)$ ,  $b(t) = k(1 - \dot{\tau}(t))p(t)$  and  $f(t) = \dot{q}(t) - q(t)\dot{p}(t)/p(t)$ ,  $t \in I$ . To apply Proposition 2 to this transformed equation we verify its assumptions. First,

$$a(t) = p(t) - \frac{\dot{p}(t)}{p(t)} \geq p(t) - \frac{M}{(\varphi(t))^\theta} \geq \frac{L}{(\varphi(t))^\alpha} - \frac{M}{(\varphi(t))^\theta} \geq \frac{L^*}{(\varphi(t))^\alpha}$$

for a suitable  $L^* > 0$ . Further, let  $N = |k|\lambda^{\tilde{\theta}}$ . Then

$$0 < |b(t)| = |k|(1 - \dot{\tau}(t))p(t) \leq |k|\lambda p(t) \leq N\left(p(t) - \frac{\dot{p}(t)}{p(t)}\right) = Na(t)$$

for all  $t$  large enough. Finally,

$$f(t) = \dot{q}(t) - \frac{\dot{p}(t)}{p(t)}q(t) = O((\varphi(t))^{\beta-\tilde{\theta}}) \quad \text{as } t \rightarrow \infty.$$

Since

$$\frac{\log N}{\log \lambda^{-1}} = \frac{\log |k|\lambda^{\tilde{\theta}}}{\log \lambda^{-1}} = \frac{\log |k|}{\log \lambda^{-1}} - \tilde{\theta},$$

a repeated application of Proposition 2 yields

$$y(t) = \dot{x}(t) = O((\varphi(t))^{\delta-\tilde{\theta}}) \quad \text{as } t \rightarrow \infty. \quad \square$$

Now we formulate the main result which is a refinement of the previous asymptotic estimates.

**Theorem.** *Let  $\varphi$  be a solution of (1.5) from Proposition 1. Let  $x$  be a solution of (1.1) and assume that all the assumptions of Proposition 3 are fulfilled. If we put  $\omega := \log |k|/\log \lambda^{-1}$ , then*

$$\begin{aligned} x(t) &= O((\varphi(t))^\omega) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta < \omega, \\ x(t) &= O((\varphi(t))^\omega \log \varphi(t)) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta = \omega, \\ x(t) &= O((\varphi(t))^{\alpha+\beta}) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta > \omega. \end{aligned}$$

First we recall the following auxiliary asymptotic result on a special difference equation. This result will be utilized in the proof of Theorem.

**Proposition 4** ([15, Lemma 1]). *Let  $z$  be a solution of the difference equation*

$$z(s) = lz(s-c) + g(s), \quad s \in J = [s_0, \infty),$$

where  $c > 0$  is a real constant,  $l$  is a complex constant such that  $|l| = \exp\{-\rho c\}$  for a suitable  $\rho > 0$  and  $g$  is a continuous function fulfilling the property  $q(s) = O(\exp\{-\kappa s\})$  as  $s \rightarrow \infty$  for a suitable  $\kappa > 0$ . Then

$$\begin{aligned} z(s) &= O(\exp\{-\rho s\}) & \text{as } s \rightarrow \infty & \quad \text{if } \rho < \kappa, \\ z(s) &= O(s \exp\{-\rho s\}) & \text{as } s \rightarrow \infty & \quad \text{if } \rho = \kappa, \\ z(s) &= O(\exp\{-\kappa s\}) & \text{as } s \rightarrow \infty & \quad \text{if } \rho > \kappa. \end{aligned}$$

*Proof of Theorem.* Let  $\delta > \max(\alpha + \beta, \omega)$ . We set

$$s = \log \varphi(t), \quad z(s) = (\varphi(t))^{-\delta} x(t)$$

in (1.1) and obtain the differential-difference equation

$$\begin{aligned} z'(s) &= -[p(h(\exp\{s\}))h'(\exp\{s\})\exp\{s\} + \delta]z(s) \\ (2.4) \quad &+ k\lambda^\delta p(h(\exp\{s\}))h'(\exp\{s\})\exp\{s\}z(s-c) \\ &+ \exp\{-\delta s\}q(h(\exp\{s\}))h'(\exp\{s\})\exp\{s\}, \quad s \in \varphi(I), \end{aligned}$$

where  $c = \log \lambda^{-1}$  and  $h \equiv \varphi^{-1}$  on  $\varphi(I)$ . By Proposition 3,  $z(s) = O(1)$  as  $s \rightarrow \infty$ . To estimate  $z'$  we write

$$z'(s) = \frac{d}{ds}[x(t)(\varphi(t))^{-\delta}] = O(h'(\exp\{s\}) \exp\{(1 - \tilde{\theta})s\}) \quad \text{as } s \rightarrow \infty.$$

Then we consider equation (2.4) in the form

$$(2.5) \quad z(s) = k\lambda^\delta z(s - c) + \frac{z'(s) + \delta z(s) - q(h(\exp\{s\}))h'(\exp\{s\}) \exp\{s\} \exp\{-\delta s\}}{-p(h(\exp\{s\}))h'(\exp\{s\}) \exp\{s\}}.$$

Using the asymptotic properties

$$q(h(\exp\{s\})) = O(\exp\{\beta s\}), \quad \frac{1}{p(h(\exp\{s\}))} = O(\exp\{\alpha s\}) \quad \text{as } s \rightarrow \infty$$

and the above derived estimates on  $z$  and  $z'$  we can rewrite (2.5) into the asymptotic form

$$z(s) = k\lambda^\delta z(s - c) + O(\exp\{-\sigma s\}) \quad \text{as } s \rightarrow \infty,$$

where  $\sigma = \min(\tilde{\theta} - \alpha, \delta - \alpha - \beta) > 0$ . To prove the required asymptotic bounds we utilize the previous Proposition 4.

First let  $\omega > \alpha + \beta$ . If  $\omega < \beta + \tilde{\theta}$ , then  $\sigma = \delta - \alpha - \beta$  for a suitable  $\delta \in (\omega, \beta + \tilde{\theta})$ ,  $z(s) = O(\exp\{(\omega - \delta)s\})$  as  $s \rightarrow \infty$ , hence  $x(t) = O((\varphi(t))^\omega)$  as  $t \rightarrow \infty$ . If  $\omega \geq \beta + \tilde{\theta}$ , then  $\sigma = \tilde{\theta} - \alpha$  for a suitable  $\delta \in (\omega, \omega + \tilde{\theta} - \alpha)$ ,  $z(s) = O(\exp\{(\omega - \delta)s\})$  as  $s \rightarrow \infty$ , hence  $x(t) = O((\varphi(t))^\omega)$  as  $t \rightarrow \infty$ .

Now let  $\omega = \alpha + \beta$ . If we take any  $\delta \in (\omega, \omega + \tilde{\theta} - \alpha)$ , then  $\sigma = \delta - \alpha - \beta$ ,  $z(s) = O(s \exp\{(\omega - \delta)s\})$  as  $s \rightarrow \infty$ , hence  $x(t) = O((\varphi(t))^\omega \log \varphi(t))$  as  $t \rightarrow \infty$ .

Finally let  $\omega < \alpha + \beta$ . If we take a suitable  $\delta \in (\alpha + \beta, \tilde{\theta} + \beta)$ , then  $\sigma = \delta - \alpha - \beta$ ,  $z(s) = O(\exp\{(\alpha + \beta - \delta)s\})$  as  $s \rightarrow \infty$ , hence  $x(t) = O((\varphi(t))^{\alpha + \beta})$  as  $t \rightarrow \infty$ .  $\square$

*Remark.* As we have already mentioned in Section 1, equation (1.1) with a positive coefficient at  $x(t)$  was the subject of asymptotic investigations in [3]. It is natural to expect that the behaviour of the solutions at infinity described in [3] is quite different from that described in the previous Theorem. Indeed, if  $p$  is nondecreasing and  $q$  fulfils some asymptotic bounds, then for any solution  $x$  of (1.1) (with the positive sign at  $x(t)$ ) there exists a (possibly zero) constant  $L \in \mathbb{R}$  such that

$$(2.6) \quad \exp\left\{-\int_{t_0}^{\infty} p(s)ds\right\} x(t) \rightarrow L \quad \text{as } t \rightarrow \infty$$

(see [3, Lemma 1]). Of course, the exponential behaviour (if  $L \neq 0$ ) of solutions cannot be estimated via terms occurring in the previous Theorem. However, if relation (2.6) holds with  $L = 0$ , then using our notation we have  $x(t) = O((\varphi(t))^\omega)$  as  $t \rightarrow \infty$  for any such solution (see [3, Lemma 2]).

### 3. EXAMPLES

In this section, we illustrate the presented asymptotic estimates in some particular cases of equation (1.1). First note that equation (1.1) involves the nonhomogeneous linear delay equation with constant coefficients

$$(3.1) \quad \dot{x}(t) = ax(t - \tau(t)) + bx(t) + q(t), \quad t \in I,$$

where  $a \neq 0$ ,  $b < 0$  are real scalars. Applying the previous Theorem to equation (3.1) (i.e., with  $p \equiv -b$  and  $k = a/(-b)$ ) we obtain the estimates derived in [4, Theorem 2.3]. Hence, we have generalized these estimates to the nonautonomous equation (1.1) (moreover, some assumptions considered in [4] have been weakened).

Another particular case of (1.1) is the corresponding homogeneous equation, i.e. equation of the form (1.4) investigated in [5]. In the cited paper the asymptotics of all solutions of (1.4) are related to the behaviour of the function  $(\varphi(t))^\omega$  occurring in the previous Theorem. Here we have posed conditions on  $q$  and its derivative under which a similar asymptotic formula holds for the solutions of the nonhomogeneous equation (1.1).

Now we pay our attention to equation (1.1) with a specified form of a lag. To apply the conclusions of Theorem we should be able to solve the corresponding Schröder equation. As an illustration we consider equation (1.1) with a linearly transformed argument (i.e.,  $t - \tau(t) = \lambda t + \mu$ ) and equation (1.1) with a power argument (i.e.,  $t - \tau(t) = t^\xi$ ). In both cases we can find the required solution of (1.5), (1.6) as follows:

$$\begin{aligned} \varphi(\lambda t + \mu) = \lambda \varphi(t) &\rightarrow \varphi(t) = t - \mu/(1 - \lambda), \\ \varphi(t^\xi) = \xi \varphi(t) &\rightarrow \varphi(t) = \log t. \end{aligned}$$

In the general case (if we cannot find the explicit form of a solution of the Schröder equation) we can either use some asymptotic treatment on this equation (see [12]) or replace this functional equation by the corresponding functional inequality.

**Corollary 1.** *Let  $x$  be a solution of*

$$(3.2) \quad \dot{x}(t) = -p(t)[x(t) - kx(\lambda t + \mu)] + q(t), \quad t \in I = [\mu/(1 - \lambda), \infty),$$

where  $k \neq 0$ ,  $0 < \lambda < 1$ ,  $\mu \in \mathbb{R}$ ,  $p, q \in C^1(I)$ ,  $p(t) \geq L/t^\alpha$ ,  $\dot{p}(t) \leq Mp(t)/t^\theta$  for suitable reals  $L, M > 0$  and  $\alpha < \theta \leq 1$ . If  $q(t) = O(t^\beta)$  as  $t \rightarrow \infty$ ,  $\dot{q}(t) = O(t^{\beta-\tilde{\theta}})$  as  $t \rightarrow \infty$  for suitable reals  $\beta$ ,  $\alpha < \tilde{\theta} < \theta$  and if  $\omega := \log |k|/\log \lambda^{-1}$ , then

$$(3.3) \quad \begin{aligned} x(t) &= O(t^\omega) && \text{as } t \rightarrow \infty && \text{if } \alpha + \beta < \omega, \\ x(t) &= O(t^\omega \log t) && \text{as } t \rightarrow \infty && \text{if } \alpha + \beta = \omega, \\ x(t) &= O(t^{\alpha+\beta}) && \text{as } t \rightarrow \infty && \text{if } \alpha + \beta > \omega. \end{aligned}$$

*Proof.* The assertion follows from Theorem applied to equation (3.2).  $\square$

**Example 1.** Consider the equation

$$(3.4) \quad \dot{x}(t) = -t^{-\alpha}[x(t) - kx(\lambda t + \mu)] + t^\beta, \quad t \in I = [\mu/(1 - \lambda), \infty),$$

where  $k \neq 0$ ,  $0 < \lambda < 1$ ,  $\alpha < 1$  and  $\beta, \mu$  are reals. If  $\omega := \log |k|/\log \lambda^{-1}$ , then estimates (3.3) hold for any solution  $x$  of (3.4).

Quite similarly as Corollary 1 we can derive

**Corollary 2.** *Let  $x$  be a solution of*

$$(3.5) \quad \dot{x}(t) = -p(t)[x(t) - kx(t^\xi)] + q(t), \quad t \in I = [1, \infty),$$

where  $k \neq 0$ ,  $0 < \xi < 1$ ,  $p, q \in C^1(I)$ ,  $p(t) \geq L/(\log t)^\alpha$ ,  $\dot{p}(t) \leq Mp(t)/(\log t)^\theta$  for suitable reals  $L, M > 0$  and  $\alpha < \theta \leq 1$ . If  $q(t) = O((\log t)^\beta)$  as  $t \rightarrow \infty$ ,  $\dot{q}(t) = O((\log t)^{\beta-\tilde{\theta}})$  as  $t \rightarrow \infty$  for reals  $\beta$ ,  $\alpha < \tilde{\theta} < \theta$  and if  $\omega := \log |k|/\log \xi^{-1}$ , then

$$(3.6) \quad \begin{aligned} x(t) &= O((\log t)^\omega) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta < \omega, \\ x(t) &= O((\log t)^\omega \log \log t) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta = \omega, \\ x(t) &= O((\log t)^{\alpha+\beta}) & \text{as } t \rightarrow \infty & \quad \text{if } \alpha + \beta > \omega. \end{aligned}$$

**Example 2.** Consider the equation

$$(3.7) \quad \dot{x}(t) = -(\log t)^{-\alpha}[x(t) - kx(t^\xi)] + (\log t)^\beta, \quad t \in I = [1, \infty),$$

where  $k \neq 0$ ,  $0 < \xi < 1$ ,  $\alpha < 1$  and  $\beta$  are reals. If  $\omega := \log |k|/\log \xi^{-1}$ , then estimates (3.6) hold for any solution  $x$  of (3.7).

#### 4. ACKNOWLEDGEMENT

The author would like to thank the referee for his valuable remarks.

#### REFERENCES

1. V.A. Ambartsumian, *On the fluctuation of the brightness of the Milky Way*, Doklady Akad. Nauk USSR **44** (1944), 223–226.
2. H. Beretoglu, M. Pituk, *Asymptotic constancy for nonhomogeneous linear differential equations with unbounded delays*, Discrete and Continuous Dynamical Systems, A Supplement Volume for the Wilmington Meeting 2002, (2003), 100–107.
3. J. Čermák, *Asymptotic behaviour of solutions of some differential equations with an unbounded delay*, Electron. J. Qual. Theory Differ. Equ. **2** (2000), 1–8.
4. J. Čermák, *A change of variables in the asymptotic theory of differential equations with unbounded delays*, J. Comput. Appl. Math. **143** (2002), 81–93.
5. J. Čermák, *The asymptotic of solutions for a class of delay differential equations*, (to appear).
6. J. Diblík, *Asymptotic representation of solutions of equation  $\dot{y}(t) = \beta(t)[y(t) - y(t - \tau(t))]$* , J. Math. Anal. Appl. **217** (1998), 200–215.
7. L. Fox, D.F. Mayers, J.R. Ockendon, A.B. Tayler, *On a functional differential equation*, J. Inst. Maths. Applics. **8** (1971), 271–307.
8. A. Iserles, *On generalized pantograph functional-differential equation*, European J. Appl. Math. **4** (1993), 1–38.
9. A. Iserles, Y. Liu, *On neutral functional-differential equations with proportional delays*, J. Math. Anal. Appl. **208** (1997), 73–95.
10. T. Kato, J.B. McLeod, *The functional-differential equation  $y'(x) = ay(\lambda x) + by(x)$* , Bull. Amer. Math. Soc. **77** (1971), 891–937.
11. T. Krisztin, *A note on the convergence of the solutions of a linear functional-differential equation*, J. Math. Anal. Appl. **145** (1990), 17–25.
12. M. Kuczma, B. Choczewski, R. Ger, *Iterative Functional Equations*, Encyclopedia of Mathematics and Its Applications, Cambridge Univ. Press, Cambridge, England, 1990.
13. H. Lehninger, Y. Liu, *The functional-differential equation  $y'(t) = Ay(t) + By(qt) + Cy'(qt) + f(t)$* , Euro. J. Appl. Math. **9** (1998), 81–91.
14. E. B. Lim, *Asymptotic behavior of solutions of the functional differential equation  $x'(t) = Ax(\lambda t) + Bx(t)$ ,  $\lambda > 0$* , J. Math. Anal. Appl. **55** (1976), 794–806.

15. E. B. Lim, *Asymptotic bounds of solutions of the functional differential equation  $x'(t) = ax(\lambda t) + bx(t) + f(t)$ ,  $0 < \lambda < 1$* , SIAM J. Math. Anal. **9** (1978), 915–920.
16. Y. Liu, *Asymptotic behaviour of functional-differential equations with proportional time delays*, Euro. J. Appl. Math. **7** (1996), 11–30.
17. G. Makay, J. Terjéki, *On the asymptotic behavior of the pantograph equations*, Electron. J. Qual. Theory Differ. Equ. **2** (1998), 1–12.
18. J. R. Ockendon, A. B. Taylor, *The dynamics of a current collection system for an electric locomotive*, Proc. Roy. Soc. London, Ser. A **322** (1971), 447–468.
19. A. Shabat, *The infinite dimensional dressing dynamical system*, Inverse Problems **8** (1992), 303–308.
20. V. Spiridonov, *Universal superpositions of coherent states and self-similar potentials*, Physical Review A **52** (1995), 1909–1935.

Technical University of Brno, Brno, Czech Republic  
*E-mail address:* cermakh@um.fme.vutbr.cz

(Received September 30, 2003)