# A pseudo-Riemannian metric on the tangent bundle of a Riemannian manifold 

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#### Abstract

On the tangent bundle of a Riemannian manifold $(M, g)$ we consider a pseudo-Riemannian metric defined by a symmetric tensor field $c$ on $M$ and four real valued smooth functions defined on $[0, \infty)$. We study the conditions under which the above pseudo-Riemannian manifold has constant sectional curvature.


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## 1 Necessary facts about the tangent bundle $T M$

Let $(M, g)$ be a smooth $n$-dimensional Riemannian manifold and let $\pi: T M \rightarrow M$ be its tangent bundle. Then $T M$ has a structure of a $2 n$-dimensional smooth manifold induced from the structure of smooth $n$-dimensional manifold of $M$ as follows: every local chart $(U, \phi)=\left(U, x^{1}, \ldots, x^{n}\right)$ on $M$ induced a local chart $\left(\pi^{-1}(U), \Phi\right)=$ $\left(\pi^{-1}(U), x^{1}, \ldots, x^{n}, y^{1}, \ldots, y^{n}\right)$ on $T M$, where we made an abuse of notation,identifying $x^{i}$ with $\pi^{*} x^{i}=x^{i} \circ \pi$ and $y^{i}$ being the vector space coordinates of $y \in \pi^{-1}(U)$ with respect to the natural local frame $\left(\left(\frac{\partial}{\partial x^{1}}\right)_{\pi(y)}, \ldots,\left(\frac{\partial}{\partial x^{n}}\right)_{\pi(y)}\right)$ i.e. $y=y^{i}\left(\frac{\partial}{\partial x^{i}}\right)_{\pi(y)}$

This special structure of $T M$ allows us to introduce the notion of $M$-tensor fields on it (see [3]). An $M$-tensor field of type $(p, q)$ on $T M$ is defined by sets of $n^{p+q}$ functions depending on $x^{i}$ and $y^{i}$, assigned to induced local charts $\left(\pi^{-1}(U), \Phi\right)$ on $T M$, thus the change rule is that of the components of a tensor field of type $(p, q)$ on $M$, when a change of local charts on the base manifold is performed. Remark that the components $y^{i}$ define an $M$-tensor field of type $(1,0)$ on $T M$. It is also obvious that a usual tensor field of type $(p, q)$ on $M$ may be thought as an $M$-tensor field of type $(p, q)$ on $T M$. In the case of a covariant tensor field, the corresponding $M$-tensor field on the tangent bundle $T M$ is nothing else but the pullback of the initial tensor field by the submersion $\pi: T M \rightarrow M$. Other useful $M$-tensor fields on $T M$ may be obtained as follows. Let $a:[0, \infty) \rightarrow R$ be a smooth function and let $\|y\|^{2}=g_{\pi(y)}(y, y)$ be the square of the norm of the tangent vector $y$. Then the components $a\left(\|y\|^{2}\right) \delta_{j}^{i}$ define a $M$-tensor field of type $(1,1)$ on $T M$. Similarly, if $g_{i j}(x)$ are the local coordinate

[^0]components of the metric tensor field $g$ on $M$, then the components $a\left(\|y\|^{2}\right) g_{i j}$ define a symmetric $M$-tensor field of type ( 0,2 ) on $T M$. The components $g_{0 i}=y^{j} g_{j i}$ define an $M$-tensor field of type $(0,1)$ on $T M$.

Recall that the Levi-Civita connection $\dot{\nabla}$ of the Riemannian metric $g$ defines the direct sum decomposition

$$
T T M=V T M \oplus H T M
$$

of the tangent bundle to $T M$ into the vertical distribution $V T M=k e r \pi_{*}$ and the horizontal distribution HTM. The vector fields $\left(\frac{\partial}{\partial y^{1}}, \ldots, \frac{\partial}{\partial y^{n}}\right)$ define a local frame field for $V T M$ and for the horizontal distribution $H T M$ we have the local frame field $\left(\frac{\delta}{\delta x^{1}}, \ldots, \frac{\delta}{\delta x^{n}}\right)$, where

$$
\frac{\delta}{\delta x^{i}}=\frac{\partial}{\partial x^{i}}-\Gamma_{i 0}^{h} \frac{\partial}{\partial y^{h}} ; \Gamma_{i 0}^{h}=\Gamma_{i k}^{h} y^{k}
$$

and $\Gamma_{i j}^{h}$ are the Christoffel symbols defined by the Riemannian metric $g$. In [5] the author proves the following

Lemma 1. If $n>1$ and $u, v$ are smooth function on $T M$ such that

$$
u g_{i j}+v g_{0 i} g_{0 j}=0, g_{0 i}=y^{j} g_{j i}, \quad y \in \pi^{-1}(U)
$$

on the domain of any induced local chart on $T M$, then $u=v=0$.

In a similar way we can obtain

Lemma 2. If $n>1$ and $u, v$ are smooth function on $T M$ such that

$$
u g_{j k} \delta_{i}^{h}-u g_{i j} \delta_{k}^{h}+v g_{0 i} g_{0 j} \delta_{k}^{h}-v g_{0 j} g_{0 k} \delta_{i}^{h}=0, g_{0 i}=y^{j} g_{j i}, \quad y \in \pi^{-1}(U)
$$

on the domain of any induced local chart on $T M$, then $u=v=0$.
Remark. From the relation

$$
u g_{j k} y_{i} y^{h}-u g_{i k} y_{j} y^{h}=0, \quad y \in \pi^{-1}(U)
$$

we obtain $u=0$.

Since we work in a fixed local chart $(U, \phi)$ on $M$ and in the corresponding induced local chart $\left(\pi^{-1}(U), \Phi\right)$ on $T M$, we shall use the following simpler notations

$$
\frac{\partial}{\partial y^{i}}=\partial_{i}, \quad \frac{\delta}{\delta x^{i}}=\delta_{i}
$$

We also denote by

$$
t=\frac{1}{2}\|y\|^{2}=\frac{1}{2} g_{\pi(y)}(y, y)=\frac{1}{2} g_{i j}(x) y^{i} y^{j}, y \in \pi^{-1}(U)
$$

## 2 A pseudo-Riemannian metric on $T M$

Let $c$ be a symmetric tensor field of type $(0,2)$ on $M$, and let $a_{1}, b_{1}, a_{2}, b_{2}:[0, \infty) \rightarrow R$ be smooth functions. Consider the following symmetric tensor field of type $(0,2)$ on $T M$ (see [6],[7],[4])

$$
\left\{\begin{array}{l}
G_{y}\left(X^{V}, Y^{V}\right)=0  \tag{2.1}\\
G_{y}\left(X^{H}, Y^{V}\right)=a_{1}(t) g_{\pi(y)}(X, Y)+b_{1}(t) g_{\pi(y)}(y, X) g_{\pi(y)}(y, Y) \\
G_{y}\left(X^{H}, Y^{H}\right)=a_{2}(t) c_{\pi(y)}(X, Y)+b_{2}(t) g_{\pi(y)}(y, X) g_{\pi(y)}(y, Y)
\end{array}\right.
$$

The expression of $G$ in local adapted frames is defined by the following $M$-tensor fields

$$
\begin{aligned}
G_{i j}^{1} & =G\left(\delta_{i}, \partial_{j}\right)=a_{1} g_{i j}+b_{1} g_{0 i} g_{0 j} \\
G_{i j}^{2} & =G\left(\delta_{i}, \delta_{j}\right)=a_{2} c_{i j}+b_{2} g_{0 i} g_{0 j}
\end{aligned}
$$

The associated matrix of $G$ with respect to the adapted local frame is

$$
\left(\begin{array}{cc}
0 & G_{i j}^{1} \\
G_{i j}^{1} & G_{i j}^{2}
\end{array}\right)
$$

The conditions for $G$ to be nondegenerate are ensured if

$$
a_{1}\left(a_{1}+2 t b_{1}\right) \neq 0
$$

Under these conditions the matrix $\left(G_{i j}^{1}\right)$ has the inverse with the entries

$$
H_{1}^{i j}=\frac{1}{a_{1}} g^{i j}+\frac{b_{1}}{a_{1}+2 t b_{1}} y^{i} y^{j}
$$

We shall denote by

$$
\partial_{h} G_{i j}^{1}=\frac{\partial G_{i j}^{1}}{\partial y^{h}}, \partial_{h} G_{i j}^{2}=\frac{\partial G_{i j}^{2}}{\partial y^{h}}, \quad \delta_{h} G_{i j}^{1}=\frac{\delta G_{i j}^{1}}{\delta x^{h}}, \delta_{h} G_{i j}^{2}=\frac{\delta G_{i j}^{2}}{\delta x^{h}}
$$

The following formulae can be easily checked and will be useful in our next computation:

$$
\left\{\begin{array}{l}
\dot{\nabla}_{i} G_{j k}^{1}=\delta_{i} G_{j k}^{1}-\Gamma_{i j}^{h} G_{h k}^{1}-\Gamma_{i k}^{h} G_{j h}^{1}=0  \tag{2.2}\\
\dot{\nabla}_{i} G_{j k}^{2}=\delta_{i} G_{j k}^{2}-\Gamma_{i j}^{h} G_{h k}^{2}-\Gamma_{i k}^{h} G_{j h}^{2}=a_{2} \dot{\nabla}_{i} c_{j k} \\
\dot{\nabla}_{i} H_{1}^{j k}=\delta_{i} H_{1}^{j k}+\Gamma_{i h}^{j} H_{1}^{h k}+\Gamma_{i h}^{k} H_{1}^{j h}=0 \\
\dot{\nabla}_{i} \partial_{j} G_{k l}^{1}=\delta_{i} \partial_{j} G_{k l}^{1}-\Gamma_{i j}^{h} \partial_{h} G_{k l}^{1}-\Gamma_{i k}^{h} \partial_{j} G_{h l}^{1}-\Gamma_{i l}^{h} \partial_{j} G_{k h}^{1}=0 \\
\dot{\nabla}_{i} \partial_{j} G_{k l}^{2}=\delta_{i} \partial_{j} G_{k l}^{2}-\Gamma_{i j}^{h} \partial_{h} G_{k l}^{2}-\Gamma_{i k}^{h} \partial_{j} G_{h l}^{2}-\Gamma_{i l}^{h} \partial_{j} G_{k h}^{2}=a_{2}^{\prime} g_{0 j} \dot{\nabla}_{i} c_{k l}
\end{array}\right.
$$

Proposition 3. The Levi-Civita connection $\nabla$ of the pseudo-Riemannian manifold $(T M, G)$ has the following expression in the local adapted frame $\left(\partial_{1}, \ldots, \partial_{n}\right.$, $\left.\delta_{1}, \ldots, \delta_{n}\right)$

$$
\begin{array}{ll}
\nabla_{\partial_{i}} \partial_{j}=Q_{i j}^{h} \partial_{h}, & \nabla_{\delta_{i}} \partial_{j}=\left(\Gamma_{i j}^{h}+\widetilde{P}_{j i}^{h}\right) \partial_{h}+P_{j i}^{h} \delta_{h}, \\
\nabla_{\partial_{i}} \delta_{j}=P_{i j}^{h} \delta_{h}+\widetilde{P}_{i j}^{h} \partial_{h}, & \nabla_{\delta_{i}} \delta_{j}=\left(\Gamma_{i j}^{h}+\widetilde{S}_{i j}^{h}\right) \delta_{h}+S_{i j}^{h} \partial_{h},
\end{array}
$$

where the $M$-tensor fields $Q_{i j}^{h}, P_{i j}^{h}, \widetilde{P}_{i j}^{h}, S_{i j}^{h}, \widetilde{S}_{i j}^{h}$ are given by:

$$
\begin{gathered}
Q_{i j}^{h}=\frac{1}{2} H_{1}^{h k}\left(\partial_{i} G_{j k}^{1}+\partial_{j} G_{i k}^{1}\right), \\
P_{i j}^{h}=\frac{1}{2} H_{1}^{h k}\left(\partial_{i} G_{j k}^{1}-\partial_{k} G_{i j}^{1}\right), \\
\widetilde{P}_{i j}^{h}=\frac{1}{2} H_{1}^{h k} \partial_{i} G_{j k}^{2}-\frac{1}{2} H_{1}^{r l}\left(\partial_{i} G_{j l}^{1}-\partial_{l} G_{i j}^{1}\right) G_{r k}^{2} H_{1}^{k h}, \\
S_{i j}^{h}=\frac{a_{2}}{2}\left(\dot{\nabla}_{i} c_{j k}+\dot{\nabla}_{j} c_{k i}-\dot{\nabla}_{k} c_{i j}\right) H_{1}^{k h}- \\
-a_{1} R_{0 i j k} H_{1}^{k h}+\frac{1}{2} H_{1}^{s l}\left(\partial_{l} G_{i j}^{2}\right) G_{s k}^{2} H_{1}^{k h}, \\
\widetilde{S}_{i j}^{h}=-\frac{1}{2} H_{1}^{h k} \partial_{k} G_{i j}^{2}
\end{gathered}
$$

$R_{l i j k}$ denoting the local coordinate components of the Riemann-Christoffel tensor of the Levi-Civita connection $\dot{\nabla}$ on $M$ and $R_{0 i j k}=y^{l} R_{l i j k}$

Remark. Replacing the expressions of $G_{i j}^{1}, G_{i j}^{2}, H_{1}^{i j}, \partial_{i} G_{j k}^{1}, \partial_{i} G_{j k}^{2}$ by their local coordinate components we obtain some quite complicated expressions.

The curvature tensor field $K$ of the connection $\nabla$ is defined by the well-known formula

$$
K(X, Y) Z=\nabla_{X} \nabla_{Y} Z-\nabla_{Y} \nabla_{X} Z-\nabla_{[X, Y]} Z, \quad X, Y, Z \in \Gamma(T M)
$$

Proposition 4. The local coordinate expression of the curvature tensor field in the adapted local frame $\left(\partial_{1}, \ldots, \partial_{n}, \delta_{1}, \ldots, \delta_{n}\right)$ is given by

$$
\begin{aligned}
K\left(\partial_{i}, \partial_{j}\right) \partial_{k} & =Y Y Y Y_{k i j}^{h} \partial_{h}, \\
K\left(\partial_{i}, \partial_{j}\right) \delta_{k} & =Y Y X Y_{k i j}^{h} \partial_{h}+Y Y X X_{k i j}^{h} \delta_{h}, \\
K\left(\partial_{i}, \delta_{j}\right) \partial_{k} & =Y X Y Y_{k i j}^{h} \partial_{h}+Y X Y X_{k i j}^{h} \delta_{h}, \\
K\left(\partial_{i}, \delta_{j}\right) \delta_{k} & =Y X X Y_{k i j}^{h} \partial_{h}+Y X X X_{k i j}^{h} \delta_{h}, \\
K\left(\delta_{i}, \delta_{j}\right) \partial_{k} & =X X Y Y_{k i j}^{h} \partial_{h}+X X Y X_{k i j}^{h} \delta_{h}, \\
K\left(\delta_{i}, \delta_{j}\right) \delta_{k} & =X X X Y_{k i j}^{h} \partial_{h}+X X X X_{k i j}^{h} \delta_{h},
\end{aligned}
$$

where we have denoted

$$
\begin{aligned}
& Y Y Y Y_{k i j}^{h}= \partial_{i} Q_{j k}^{h}+Q_{j k}^{l} Q_{i l}^{h}-\partial_{j} Q_{i k}^{h}-Q_{i k}^{l} Q_{j l}^{h} \\
& Y Y X Y_{k i j}^{h}= \partial_{i} \widetilde{P}_{j k}^{h}+\widetilde{P}_{i l}^{h} P_{j k}^{l}+\widetilde{P}_{j k}^{l} Q_{i l}^{h}-\partial_{j} \widetilde{P}_{i k}^{h}-\widetilde{P}_{j l}^{h} P_{i k}^{l}-\widetilde{P}_{i k}^{l} Q_{j l}^{h} \\
& Y Y X X_{k i j}^{h}=\partial_{i} P_{j k}^{h}+P_{j k}^{l} P_{i l}^{h}-\partial_{j} P_{i k}^{h}-P_{i k}^{l} P_{j l}^{h} \\
& Y X Y Y_{k i j}^{h}= \partial_{i} \widetilde{P}_{k j}^{h}+\widetilde{P}_{k j}^{l} Q_{i l}^{h}+\widetilde{P}_{i l}^{h} P_{k j}^{l}-\widetilde{P}_{l j}^{h} Q_{i k}^{l} \\
& Y X Y X_{k i j}^{h}=\partial_{i} P_{k j}^{h}+P_{k j}^{l} P_{i l}^{h}-P_{l l}^{h} Q_{i k}^{l} \\
& Y X X Y_{k i j}^{h}=\partial_{i} S_{j k}^{h}+S_{j k}^{l} Q_{i l}^{h}+\widetilde{S}_{j k}^{l} \widetilde{P}_{i l}^{h}-S_{j l}^{h} P_{i k}^{l}-\widetilde{P}_{i k}^{l} \widetilde{P}_{l j}^{h}-\dot{\nabla}_{j} \widetilde{P}_{i k}^{h} \\
& Y X X X_{k i j}^{h}= \partial_{i} \widetilde{S}_{j k}^{h}+\widetilde{S}_{j k}^{l} P_{i l}^{h}-\widetilde{S}_{j l}^{h} P_{i k}^{l}-\widetilde{P}_{i k}^{l} P_{l j}^{h} \\
& X X Y Y_{k i j}^{h}=\dot{\nabla}_{i} \widetilde{P}_{k j}^{h}+\widetilde{P}_{l j}^{l} \widetilde{P}_{l i}^{h}+P_{k j}^{l} S_{i l}^{h}-\dot{\nabla}_{j} \widetilde{P}_{k i}^{h}-\widetilde{P}_{k i}^{l} \widetilde{P}_{l j}^{h}-P_{k i}^{l} S_{j l}^{h}+ \\
&+R_{k i j}^{h}+R_{0 i j}^{l} Q_{l k}^{h} \\
& X X Y X_{k i j}^{h}=\widetilde{P}_{k j}^{l} P_{l i}^{h}+P_{k j}^{l} \widetilde{S}_{i l}^{h}-\widetilde{P}_{k i}^{l} P_{l j}^{h}-P_{k i}^{l} \widetilde{S}_{j l}^{h} \\
& X X X Y_{k i j}^{h}=\dot{\nabla}_{i} S_{j k}^{h}+S_{S l}^{h} \widetilde{S}_{j k}^{l}+S_{j k}^{l} \widetilde{P}_{l i}^{h}-\dot{\nabla}_{j} S_{i k}^{h}-S_{j l}^{h} \widetilde{S}_{i k}^{l}-S_{i k}^{l} \widetilde{P}_{l j}^{h}+R_{0 i j}^{l} \widetilde{P}_{l k}^{h} \\
& X X X X_{k i j}^{h}=\dot{\nabla}_{i} \widetilde{S}_{j k}^{h}+\widetilde{S}_{j k}^{l} \widetilde{S}_{h l l}^{h}+S_{j k}^{l} P_{l i}^{h}-\dot{\nabla}_{j} \widetilde{S}_{i k}^{h}-\widetilde{S}_{i k}^{l} \widetilde{S}_{j l}^{h}-S_{i k}^{l} P_{l j}^{h}+ \\
&+R_{k i j}^{h}+R_{0 i j}^{l} P_{l k}^{h}
\end{aligned}
$$

Remark. Note that, as a first step, the formulae for the local expression of $K$ also contain some other terms involving the Christoffel symbols $\Gamma_{i j}^{h}$. However, all of these terms are involved in the derivative $\dot{\nabla}$. For example

$$
\dot{\nabla}_{i} \widetilde{P}_{j k}^{h}=\delta_{i} \widetilde{P}_{j k}^{h}-\Gamma_{i j}^{l} \widetilde{P}_{l k}^{h}-\Gamma_{i k}^{l} \widetilde{P}_{j l}^{h}+\Gamma_{i l}^{h} \widetilde{P}_{j k}^{l},
$$

but using the expression of $\widetilde{P}_{i j}^{h}$ and taking account of relations (2.2) we obtain after a straightforward computation that

$$
\dot{\nabla}_{i} \widetilde{P}_{j k}^{h}=\frac{a_{2}^{\prime}}{2} H_{1}^{h l} g_{0 j} \dot{\nabla}_{i} c_{k l}-\frac{a_{2}}{2} H_{1}^{s l}\left(\partial_{j} G_{k l}^{1}-\partial_{l} G_{j k}^{1}\right)\left(\dot{\nabla}_{i} c_{s r}\right) H_{1}^{r h}
$$

Remark also that the terms $\dot{\nabla}_{i} Q_{j k}^{h}$ and $\dot{\nabla}_{i} P_{j k}^{h}$ do not appear because they are zero as follows from the formulae (2.2).

Now, we have to replace the expression of the $M$ tensor fields $Q_{i j}^{h}, P_{i j}^{h}, \widetilde{P}_{i j}^{h}, S_{i j}^{h}$, $\widetilde{S}_{i j}^{h}$ in order to obtain the explicit expression of the components of $K$. However, the final expressions are quite complicated, but they may be obtained after some long and hard computation made by using the Mathematica package RICCI.

Recall that the pseudo-Riemannian manifold $(T M, G)$ has constant sectional curvature $k$ if its curvature tensor field $K$ is given by

$$
K(X, Y) Z=K_{0}(X, Y) Z=k(G(Y, Z) X-G(X, Z) Y), \forall X, Y, Z \in \Gamma(T M)
$$

In order to find under which conditions $(T M, G)$ has constant sectional curvature we shall consider the differences between the components of the tensor fields $K$ and $K_{0}$ and we shall denote them by Diff. For example

$$
D i f f Y Y Y Y_{k i j}^{h}=Y Y Y Y_{k i j}^{h}-Y Y Y Y_{0 k i j}^{h}
$$

The explicit expression of Diff $Y Y Y Y_{k i j}^{h}$ is

$$
\operatorname{Diff} Y Y Y Y_{k i j}^{h}=\frac{a_{1}^{\prime}-b_{1}}{2\left(a_{1}+2 t b_{1}\right)}\left(g_{j k} \delta_{i}^{h}-g_{i j} \delta_{k}^{h}\right)+
$$

$$
\begin{gathered}
+\frac{1}{4 a_{1}^{2}\left(a_{1}+2 t b_{1}\right)}\left(3 a_{1} a_{1}^{\prime 2}-2 a_{1}^{2} a_{1}^{\prime \prime}-3 a_{1} b_{1}^{2}+2 a_{1}^{2} b_{1}^{\prime}+2 a_{1}^{\prime 2} b_{1} t-4 a_{1} a_{1}^{\prime \prime} b_{1} t-\right. \\
\left.-2 b_{1}^{3} t+4 a_{1} a_{1}^{\prime} b_{1}^{\prime} t\right)\left(\delta_{k}^{h} g_{0 i} g_{0 j}-\delta_{i}^{h} g_{0 j} g_{0 k}\right) .
\end{gathered}
$$

From Lemma 2 it follows that Diff $Y Y Y Y_{k i j}^{h}=0$ if and only if $b_{1}=a_{1}^{\prime}$. By replacing $b_{1}=a_{1}^{\prime}$ in the expression of Diff $Y Y X Y_{k i j}^{h}$ we obtain

$$
\text { Diff YYXY } Y_{k i j}^{h}=-k a_{1} g_{j k} \delta_{i}^{h}+k a_{1} g_{i k} \delta_{j}^{h}+k a_{1}^{\prime} \delta_{j}^{h} g_{0 i} g_{0 k}-k a_{1}^{\prime} \delta_{i}^{h} g_{0 j} g_{0 k}
$$

Using again Lemma 2 and taking account that $a_{1} \neq 0$ it follows that Diff $Y Y X Y_{k i j}^{h}=0$ if and only if $k=0$. Under the conditions $b_{1}=a_{1}^{\prime}$ and $k=0$ we have

$$
\text { Diff } Y Y X X_{k i j}^{h}=\operatorname{Diff} Y X Y X_{k i j}^{h}=D i f f X X Y X_{k i j}^{h}=0
$$

Computing Diff $X X X X_{k i j}^{h}$ and taking $y=0$ it follows that $R=0$, so $(M, g)$ is flat. Taking $y=0$ in the formulae Diff $Y X X X_{k i j}^{h}=0$ we obtain

$$
\left\{\begin{array}{l}
n a_{2}^{\prime}(0) c_{j k}=-2 b_{2}(0) g_{j k} \\
a_{2}^{\prime}(0) c_{j k}=-(n+1) b_{2}(0) g_{j k}
\end{array}\right.
$$

from which we have

$$
\left(n^{2}+n-2\right) b_{2}(0) g_{j k}=0
$$

Assuming that $n>1$ it follows that $b_{2}(0)=0$, so $a_{2}^{\prime}(0) c_{j k}=0$.
Now we may consider the following cases:
(i) $a_{2}^{\prime}=0, b_{2}=0$ so the pseudo-Riemannian metric $G$ is given by

$$
\left\{\begin{array}{l}
G\left(\partial_{i}, \partial_{j}\right)=0  \tag{2.3}\\
G\left(\delta_{i}, \partial_{j}\right)=a_{1} g_{i j}+a_{1}^{\prime} g_{0 i} g_{0 j} \\
G\left(\delta_{i}, \delta_{j}\right)=a_{2} c_{i j}
\end{array}\right.
$$

where $a_{1}:[0, \infty) \rightarrow R$ is a smooth function and $a_{2}$ is a nonzero constant. Computing the remaining differences we have

$$
\begin{gathered}
\text { Diff } Y X Y Y_{k i j}^{h}=\text { Diff } Y X X Y_{k i j}^{h}=\text { Diff } Y X X X_{k i j}^{h}= \\
=\text { Diff } X X Y Y_{k i j}^{h}=\text { Diff } X X X X_{k i j}^{h}=0
\end{gathered}
$$

and

$$
\begin{aligned}
& \text { Diff } X X X Y_{k i j}^{h}=\frac{a_{2}}{2 a_{1}}\left(\dot{\nabla}_{i} \dot{\nabla}_{k} c_{j}^{h}-\dot{\nabla}_{j} \dot{\nabla}_{k} c_{i}^{h}+\dot{\nabla}_{j} \dot{\nabla}^{h} c_{i k}-\dot{\nabla}_{i} \dot{\nabla}^{h} c_{j k}\right)+ \\
& \quad+\frac{a_{1}^{\prime} a_{2}}{2 a_{1}\left(a_{1}+2 t a_{1}^{\prime}\right)}\left(\dot{\nabla}_{i} \dot{\nabla}_{l} c_{j k}-\dot{\nabla}_{i} \dot{\nabla}_{k} c_{l j}+\dot{\nabla}_{j} \dot{\nabla}_{k} c_{l i}-\dot{\nabla}_{j} \dot{\nabla}_{l} c_{i k}\right) y^{h} y^{l}
\end{aligned}
$$

Taking $y=0$ in Diff $X X X Y_{k i j}^{h}=0$ it follows that

$$
\dot{\nabla}_{i} \dot{\nabla}_{k} c_{j}^{h}-\dot{\nabla}_{j} \dot{\nabla}_{k} c_{i}^{h}+\dot{\nabla}_{j} \dot{\nabla}^{h} c_{i k}-\dot{\nabla}_{i} \dot{\nabla}^{h} c_{j k}=0
$$

Observing that the first bracket of the expression of Diff $X X X Y_{k i j}^{h}$ is zero if and only if the second bracket of it is zero we may state:

Theorem 5. If the tangent bundle (TM,G) has constant sectional curvature, where $G$ has the entries given by (2.3), then it must be flat. Moreover, $(T M, G)$ is flat if and only if $(M, g)$ is flat and the tensor field $c$ satisfies the condition

$$
\begin{equation*}
\dot{\nabla}_{i} \dot{\nabla}_{l} c_{j k}-\dot{\nabla}_{i} \dot{\nabla}_{k} c_{l j}+\dot{\nabla}_{j} \dot{\nabla}_{k} c_{l i}-\dot{\nabla}_{j} \dot{\nabla}_{l} c_{i k}=0 \tag{2.4}
\end{equation*}
$$

A symmetric tensor field $c$ of type $(0,2)$ on $M$ is Codazzi tensor field if

$$
\left(\dot{\nabla}_{X} c\right)(Y, Z)=\left(\dot{\nabla}_{Y} c\right)(X, Z), \quad X, Y, Z \in \Gamma(M)
$$

Note that the condition (2.4) is fulfilled if $c$ is parallel with respect to $\nabla$ or it is a Codazzi tensor field on $M$.
(ii) $a_{2}=0, b_{2}=0$ so the pseudo-Riemannian metric $G$ is given by

$$
\left\{\begin{array}{l}
G\left(\partial_{i}, \partial_{j}\right)=0  \tag{2.5}\\
G\left(\delta_{i}, \partial_{j}\right)=a_{1} g_{i j}+a_{1}^{\prime} g_{0 i} g_{0 j} \\
G\left(\delta_{i}, \delta_{j}\right)=0
\end{array}\right.
$$

where $a_{1}:[0, \infty) \rightarrow R$ is a smooth function. In this case all the differences Diff are zero, so we have the following

Theorem 6. If the tangent bundle ( $T M, G$ ) has constant sectional curvature, where $G$ has the entries given by (2.5), then it must be flat. Moreover, $(T M, G)$ is flat if and only if $(M, g)$ is flat.
(iii) $a_{2}=0$, so the pseudo-Riemannian metric $G$ is given by

$$
\left\{\begin{array}{l}
G\left(\partial_{i}, \partial_{j}\right)=0  \tag{2.6}\\
G\left(\delta_{i}, \partial_{j}\right)=a_{1} g_{i j}+a_{1}^{\prime} g_{0 i} g_{0 j} \\
G\left(\delta_{i}, \delta_{j}\right)=b_{2} g_{0 i} g_{0 j}
\end{array}\right.
$$

where $a_{1}, b_{2}:[0, \infty) \rightarrow R$ are smooth functions, $b_{2}(0)=0$. In this case we have

$$
\text { Diff } X X Y Y_{k i j}^{h}=u g_{j k} y_{i} y^{h}-u g_{i k} y_{j} y^{h}
$$

where $u=\frac{b_{2}\left(a_{1} b_{2}-2 a_{1}^{\prime} b_{2} t+2 a_{1} b_{2}^{\prime} t\right)}{4 a_{1}\left(a_{1}+2 a_{1}^{\prime} t\right)^{2}}$. From Diff $X X Y Y_{k i j}^{h}=0$ we have, using the remark made in the first section,

$$
b_{2}\left(a_{1} b_{2}-2 a_{1}^{\prime} b_{2} t+2 a_{1} b_{2}^{\prime} t\right)=0
$$

Remark that $b_{2}=0$ is a solution of this equation. Next we shall prove that $b_{2}=0$ is the unique solution of this equation. First of all let us observe that

$$
\left(\frac{t b_{2}^{2}}{a_{1}^{2}}\right)^{\prime}=\frac{a_{1} b_{2}^{2}+2 t a_{1} b_{2} b_{2}^{\prime}-2 a_{1}^{\prime} b_{2}^{2} t}{a_{1}^{3}}=0, \forall t \geq 0
$$

It follows that $t b_{2}^{2} a_{1}^{-2}$ is a constant function, but since $b_{2}(0)=0$, we must have $t b_{2}^{2}(t) a_{1}^{-2}(t)=0, \forall t \geq 0$, so $b_{2}(t)=0$, for all $t \geq 0$. As a consequence of Theorem 6 we obtain:

Theorem 7. If the tangent bundle $(T M, G)$ has constant sectional curvature, where $G$ has the entries given by (2.6), then it must be flat. Moreover, $(T M, G)$ is flat if and only if $(M, g)$ is flat and $b_{2}=0$.

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