

# A Characterization of Isoparametric Hypersurfaces of Clifford Type

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**Abstract.** Let  $M$  be an isoparametric hypersurface with four distinct principal curvatures in the unit sphere  $\mathbb{S} \subseteq \mathbb{R}^{2l}$  with focal manifolds  $M_+$  and  $M_-$ . Let  $\mathcal{U}$  be a vector space of symmetric  $(2l \times 2l)$ -matrices such that each matrix in  $\mathcal{U} \setminus \{0\}$  is regular, and assume that  $M_+$  is the intersection of  $\mathbb{S}$  with the quadrics  $\{x \in \mathbb{R}^{2l} \mid \langle x, Ax \rangle = 0\}$ ,  $A \in \mathcal{U}$ . Then  $\mathcal{U}$  is generated by a Clifford system and  $M$  is an isoparametric hypersurface of Clifford type provided that  $\dim M_+ \geq \dim M_-$ . The proof of this theorem is based on properties of quadratic forms vanishing on  $M_+$  and on a structure theorem for isoparametric triple systems, which we prove in this paper.

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## 1. Introduction

Let  $M$  be an isoparametric hypersurface with four distinct principal curvatures in the unit sphere  $\mathbb{S}$  of the Euclidean vector space  $\mathbb{R}^{2l}$  such that for a suitable Cartan-Münzner polynomial  $F$  we have  $M = \mathbb{S} \cap F^{-1}(0)$ ,  $M_+ = \mathbb{S} \cap F^{-1}(1)$ , and  $M_- = \mathbb{S} \cap F^{-1}(-1)$ , cf. [6], Theorem 4. If  $F$  is defined by means of a Clifford sphere  $\Sigma$  as in [2], 4.1, then the focal manifold  $M_+$  is the intersection of  $\mathbb{S}$  with the quadrics  $\{x \in \mathbb{R}^{2l} \mid \langle x, Qx \rangle = 0\}$ ,  $Q \in \Sigma$ , see [2], 4.2. In this paper we prove a partial converse to this statement: Let  $\mathcal{U}$  be a subspace of the vector space  $\mathcal{S}_{2l}$  of symmetric  $(2l \times 2l)$ -matrices with the property that each matrix in  $\mathcal{U} \setminus \{0\}$  is regular, and assume that  $M_+$  is the intersection of  $\mathbb{S}$  with the quadrics  $\{x \in \mathbb{R}^{2l} \mid \langle x, Ax \rangle = 0\}$ ,  $A \in \mathcal{U}$ . Then  $\mathcal{U}$  is generated by a Clifford sphere and  $M$  is an isoparametric hypersurface of Clifford type provided that  $\dim M_+ \geq \dim M_-$ . The proof of this result is based on a structure theorem for isoparametric triple systems

and on properties of quadratic forms vanishing on  $M_+$ , see Theorem 2.1 and Proposition 3.1. Note that subspaces  $\mathcal{U}$  with the property that each matrix in  $\mathcal{U} \setminus \{0\}$  is regular are not rare at all: The  $n$ -dimensional subspaces with this property form an open subset in the Grassmannian of  $n$ -dimensional subspaces of  $\mathcal{S}_{2l}$ . In particular, every subspace of dimension  $\dim \mathbb{R}\Sigma$  which is sufficiently close to  $\mathbb{R}\Sigma$  in the Grassmann topology has this property.

Isoparametric triple systems were introduced by Dorfmeister and Neher in [1] and were investigated in several subsequent papers. Theorem 2.1 is related to the main result of [1]. In [4], we used isoparametric triple systems in our proof that the incidence structures associated with isoparametric hypersurfaces with four distinct principal curvatures in spheres are Tits buildings of type  $C_2$ .

In this paper, we will not give a detailed introduction to the theory of isoparametric hypersurfaces and the corresponding isoparametric triple systems. The reader is referred to [6], [2], [1], [7], or to [3], [4], where we treated isoparametric hypersurfaces from an incidence-geometric point of view. We will, however, present parts of these theories in the following sections as far as the topics of the present paper are concerned.

## 2. Structure theorem for isoparametric triple systems

Let  $V$  denote a Euclidean vector space with unit sphere  $\mathbb{S}$ . An *isoparametric hypersurface* in  $\mathbb{S}$  is a compact, connected smooth hypersurface of  $\mathbb{S}$  with constant principal curvatures. Each isoparametric hypersurface gives rise to an *isoparametric family* of parallel hypersurfaces. The sphere  $\mathbb{S}$  is foliated by these parallel hypersurfaces and the two focal manifolds, see [6], Theorem 4. All these manifolds may be described by means of a Cartan-Münzner polynomial, see [6], Theorem 2. More precisely, there exists a homogeneous polynomial function  $F : V \rightarrow \mathbb{R}$  such that the family of isoparametric hypersurfaces is given by  $\mathbb{S} \cap F^{-1}(\rho)$ ,  $-1 < \rho < 1$ , and the two focal manifolds are  $M_+ = \mathbb{S} \cap F^{-1}(1)$  and  $M_- = \mathbb{S} \cap F^{-1}(-1)$ . We set  $M = \mathbb{S} \cap F^{-1}(0)$ . Every isoparametric family has the geometric property that a great circle  $S$  which intersects  $M$  orthogonally at one point intersects  $M$  and the two focal manifolds orthogonally at each intersection point. Moreover, the points of  $S \cap M_+$  and  $S \cap M_-$  follow on  $S$  alternatingly at spherical distance  $\pi/g$ , where  $g$  denotes the number of distinct principal curvatures of  $M$ , see [6], Section 6, cf. also [5], Proposition 3.2. We say that such a great circle  $S$  is normal to  $M$ .

For  $g = 4$ , there is a triple product  $\{\cdot, \cdot, \cdot\}$  on  $V$  associated with the Cartan-Münzner polynomial  $F$ . In this way,  $(V, \langle \cdot, \cdot \rangle, \{\cdot, \cdot, \cdot\})$  becomes an isoparametric triple system, see [1]. The focal manifolds are given by  $M_+ = \{x \in \mathbb{S} \mid \{x, x, x\} = 3x\}$  and  $M_- = \{y \in \mathbb{S} \mid \{y, y, y\} = 6y\}$ . For  $x, y \in V$  and  $\lambda \in \mathbb{R}$  we put  $T(x, y) : V \rightarrow V : z \mapsto \{x, y, z\}$ ,  $T(x) = T(x, x)$ , and  $V_\lambda(x) = \{z \in V \mid T(x)(z) = \lambda z, \langle x, z \rangle = 0\}$ . If  $x \in M_+$  and  $y \in M_-$  then we have  $V = \text{span}\{x\} \oplus V_3(x) \oplus V_1(x) = \text{span}\{y\} \oplus V_0(y) \oplus V_2(y)$  (Peirce decompositions). The dimensions of the Peirce spaces  $V_3(x)$ ,  $V_1(x)$ ,  $V_0(y)$ , and  $V_2(y)$  are given by  $m_1 + 1$ ,  $m_1 + 2m_2$ ,  $m_2 + 1$ , and  $2m_1 + m_2$ , respectively, where  $m_1$  and  $m_2$  denote the multiplicities of the principal curvatures of  $M$ , see [1], Theorem 2.2. Furthermore, the following identities hold ( $u_0, v_0, w_0 \in V_0(y)$ ,  $u_3, v_3, w_3 \in V_3(x)$ ):

- (1)  $\{u_0, y, v_0\} = 0,$
- (2)  $\{u_0, v_0, w_0\} = 2(\langle u_0, v_0 \rangle w_0 + \langle v_0, w_0 \rangle u_0 + \langle w_0, u_0 \rangle v_0),$
- (3)  $\{u_3, x, v_3\} = 3\langle u_3, v_3 \rangle x,$
- (4)  $\{u_3, v_3, w_3\} = \langle u_3, v_3 \rangle w_3 + \langle v_3, w_3 \rangle u_3 + \langle w_3, u_3 \rangle v_3.$

These identities correspond to equations 2.3, 2.6, 2.10, and 2.13 in [1]. In particular, we have  $\mathbb{S} \cap V_3(x) \subseteq M_+$  and  $\mathbb{S} \cap V_0(y) \subseteq M_-$  by identities (2) and (4). The points of  $M_+$  (of  $M_-$ ) with spherical distance  $\pi/4$  from  $y$  (from  $x$ ) are precisely the points in  $\mathbb{S} \cap ((1/\sqrt{2})y + V_0(y))$  (in  $\mathbb{S} \cap ((1/\sqrt{2})x + V_3(x))$ , respectively), cf. [4], Section 2 and 3.1. Hence, on every great circle through  $x \in M_+$  and a point  $z_3 \in \mathbb{S} \cap V_3(x) \subseteq M_+$  there is a point  $(1/\sqrt{2})(x + z_3) \in M_-$  and, in fact, such a great circle is normal to  $M$ , cf. [6], Section 6, and [4], Corollary 3.3. Analogously, every great circle through  $y \in M_-$  and a point of  $\mathbb{S} \cap V_0(y)$  is normal to  $M$ . We are now ready to prove the following structure theorem:

**2.1 Theorem.** *Let  $(V, \langle \cdot, \cdot \rangle, \{ \cdot, \cdot, \cdot \})$  be an isoparametric triple system. Let  $S$  be a great circle of  $\mathbb{S}$  normal to  $M$  which intersects  $M_+$  at the four points  $\pm p, \pm q$  and  $M_-$  at the four points  $\pm r, \pm s$ . Then  $V$  decomposes as an orthogonal sum*

$$V = \text{span}\{p, q, r, s\} \oplus V'_3(p) \oplus V'_3(q) \oplus V'_0(r) \oplus V'_0(s),$$

where  $V'_3(p), V'_3(q), V'_0(r), V'_0(s)$  are defined by  $V_3(p) = V'_3(p) \oplus \text{span}\{q\}$ ,  $V_3(q) = V'_3(q) \oplus \text{span}\{p\}$ ,  $V_0(r) = V'_0(r) \oplus \text{span}\{s\}$ , and  $V_0(s) = V'_0(s) \oplus \text{span}\{r\}$ .

*Proof.* The points of  $M_+$  and  $M_-$  follow on  $S$  alternatingly at spherical distance  $\pi/4$ . Hence we have  $\langle p, q \rangle = \langle r, s \rangle = 0$ , and without loss of generality we may assume that  $r = (1/\sqrt{2})(p + q)$  and  $q = (1/\sqrt{2})(r + s)$ .

First we want to justify the definition of  $V'_3(p)$  by  $V_3(p) = V'_3(p) \oplus \text{span}\{q\}$ . For this purpose we have to show that  $q \in V_3(p)$ . We have  $\langle r, p \rangle = 1/\sqrt{2}$  and hence  $r \in \mathbb{S} \cap ((1/\sqrt{2})p + V_3(p))$ , as mentioned above. This implies that  $q \in V_3(p)$  because of  $r = (1/\sqrt{2})(p + q)$ . Analogously we see that the definitions of  $V'_3(q), V'_0(r)$ , and  $V'_0(s)$  make sense.

Next we consider the action of the operators  $T(p, q)$  and  $T(r, s)$  on these subspaces of  $V$ . For  $x \in V'_0(s)$  we have  $T(r, s)(x) = \{r, s, x\} = 0$  by identity (1). In the same way we see that  $T(r, s)$  maps  $V'_0(r)$  to  $\{0\}$ . Now let  $y \in V'_3(q)$ . As remarked above, we have  $r = (1/\sqrt{2})q + r_3$  and  $s = (1/\sqrt{2})q + s_3$  with  $r_3, s_3 \in V_3(q)$ . Note that  $\langle r_3, y \rangle = \langle s_3, y \rangle = 0$  and  $\langle r_3, s_3 \rangle = -1/2$ . Then the identities (3) and (4) imply that

$$T(r, s)(y) = \{(1/\sqrt{2})q + r_3, y, (1/\sqrt{2})q + s_3\} = (3/2)y - (1/2)y = y,$$

i.e.  $T(r, s)$  acts on  $V'_3(q)$  as the identity. Analogously,  $T(r, s)$  acts on  $V'_3(p)$  as  $-\text{id}$ . Hence we have proved that  $T(r, s)|_{V'_0(r)} = T(r, s)|_{V'_0(s)} = 0$ ,  $T(r, s)|_{V'_3(q)} = \text{id}$ , and  $T(r, s)|_{V'_3(p)} = -\text{id}$ .

Using the above identities, it can be shown in the same way that  $T(p, q)|_{V'_3(p)} = T(p, q)|_{V'_3(q)} = 0$ ,  $T(p, q)|_{V'_0(r)} = -\text{id}$ , and  $T(p, q)|_{V'_0(s)} = \text{id}$ . Since the operators  $T(p, q)$  and  $T(r, s)$  are self-adjoint, we get  $\text{span}\{p, q, r, s\} \oplus V'_3(p) \oplus V'_3(q) \oplus V'_0(r) \oplus V'_0(s) \leq V$ . The claim follows because of  $\dim V = 2 + 2m_1 + 2m_2$ . □

### 3. Quadratic forms vanishing on a focal manifold

Every quadratic form on the Euclidean vector space  $\mathbb{R}^{2l}$  may be described by a uniquely determined symmetric matrix. The subspace  $\mathcal{A}(M_+) = \{A \in \mathcal{S}_{2l} \mid \langle x, Ax \rangle = 0 \text{ for every } x \in M_+\}$  of  $\mathcal{S}_{2l}$  corresponds to the vector space of quadratic forms vanishing on  $M_+$ . This subspace may be of interest in the classification of isoparametric hypersurfaces with four distinct principal curvatures in spheres. The following proposition explains the structure of  $\mathcal{A}(M_+)$ .

**3.1 Proposition.** *Let  $M_+$  and  $M_-$  be the focal manifolds of an isoparametric hypersurface with four distinct principal curvatures in the unit sphere  $\mathbb{S} \subseteq \mathbb{R}^{2l}$  and let  $\mathcal{A}(M_+) = \{A \in \mathcal{S}_{2l} \mid \langle x, Ax \rangle = 0 \text{ for every } x \in M_+\}$ . Then the following two statements hold:*

- (i) *For every  $A, B \in \mathcal{A}(M_+)$  we have  $ABA \in \mathcal{A}(M_+)$ .*
- (ii) *For every  $A \in \mathcal{A}(M_+)$  we have  $A = \sum_{i=1}^r \lambda_i(Q_{\lambda_i} - Q_{-\lambda_i})$  with  $Q_{\lambda_i} - Q_{-\lambda_i} \in \mathcal{A}(M_+)$ , where the  $\pm\lambda_i$  denote the non-zero eigenvalues of  $A$  and the  $Q_{\pm\lambda_i}$  denote the orthogonal projections onto the eigenspaces of these eigenvalues. Moreover, the eigenvalues  $\lambda_i$  and  $\lambda_{-i}$  have the same multiplicity  $\mu_i \geq m_2 + 1$ , and their eigenspaces are contained in  $\mathbb{R}M_-$ .*

*Proof.* Let  $A, B \in \mathcal{A}(M_+)$  and  $x \in M_+$ . The quadratic form  $b_1 : \mathbb{R}^{2l} \rightarrow \mathbb{R}^{2l} : z \mapsto \langle z, Az \rangle$  vanishes on  $M_+$ . The differential  $D(b_1)_x$  vanishes on the tangent space  $T_x M_+$ , i.e. we have  $\langle Ax, u \rangle = 0$  for every  $u \in T_x M_+$ . By [4], 3.3, we have  $T_x M_+ = V_1(x)$ . We conclude that  $Ax \in V_3(x)$ . Hence we get  $(1/\|Ax\|)Ax \in M_+$  provided that  $Ax \neq 0$ . In any case we have  $\langle Ax, B(Ax) \rangle = 0$ . Since  $x \in M_+$  was chosen arbitrarily, we get  $\langle y, (ABA)y \rangle = 0$  for every  $y \in M_+$ . This proves (i).

Let  $A^{(1)} \in \mathcal{A}(M_+) \setminus \{0\}$ . For each  $\lambda \in \mathbb{R}$  we denote by  $Q_\lambda$  the orthogonal projection onto the subspace  $E_\lambda = \{x \in \mathbb{R}^{2l} \mid A^{(1)}x = \lambda x\}$ . The distinct absolute values of non-zero eigenvalues of  $A^{(1)}$  are denoted by  $\lambda_1, \lambda_2, \dots, \lambda_r$  such that  $\lambda_1 > \lambda_2 > \dots > \lambda_r$ . Then we have  $A^{(1)} = \sum_{i=1}^r \lambda_i(Q_{\lambda_i} - Q_{-\lambda_i})$ . By (i), the sequence  $((A^{(1)}/\lambda_1)^{2n+1})_{n \in \mathbb{N}}$  is contained in  $\mathcal{A}(M_+)$ . Hence we get  $\lim_{n \rightarrow \infty} (A^{(1)}/\lambda_1)^{2n+1} = Q_{\lambda_1} - Q_{-\lambda_1} \in \mathcal{A}(M_+)$ . We set  $A^{(2)} = A^{(1)} - \lambda_1(Q_{\lambda_1} - Q_{-\lambda_1}) \in \mathcal{A}(M_+)$ . Then we get  $\lim_{n \rightarrow \infty} (A^{(2)}/\lambda_2)^{2n+1} = Q_{\lambda_2} - Q_{-\lambda_2} \in \mathcal{A}(M_+)$ . By proceeding in this way, we obtain  $Q_{\lambda_i} - Q_{-\lambda_i} \in \mathcal{A}(M_+)$  for  $i = 1, \dots, r$ . Choose  $i \in \{1, \dots, r\}$  arbitrarily. In order to complete the proof of (ii) it suffices to show that  $\lambda_i$  and  $-\lambda_i$  are both eigenvalues of  $A^{(1)}$  with the same multiplicity  $\mu_i \geq m_2 + 1$  and that their eigenspaces are contained in  $\mathbb{R}M_-$ . Let  $x_i$  denote an eigenvector of  $A^{(1)}$  to an eigenvalue with absolute value  $\lambda_i$  with  $\|x_i\| = 1$ . If this eigenvalue is positive, we put  $\varepsilon = 1$ , otherwise  $\varepsilon = -1$ . Note that the quadratic form  $b_2 : \mathbb{R}^{2l} \rightarrow \mathbb{R} : y \mapsto \langle y, (Q_{\lambda_i} - Q_{-\lambda_i})y \rangle$  takes its maximum 1 (minimum  $-1$ ) on  $\mathbb{S}$  at  $x_i$  for  $\varepsilon = 1$  ( $\varepsilon = -1$ ). Let  $S$  denote a great circle of  $\mathbb{S}$  through  $x_i$  normal to  $M$ . By Theorem 2.1, we have for  $V = \mathbb{R}^{2l}$

$$V = \text{span}\{p, q, r, s\} \oplus V'_3(p) \oplus V'_3(q) \oplus V'_0(r) \oplus V'_0(s),$$

where  $\pm p, \pm q$  ( $\pm r, \pm s$ ) are the four intersection points of  $M_+$  ( $M_-$ ) with  $S$ . The map  $b_2|_{\text{span}\{p, q, r, s\}}$  is a quadratic form on the two-dimensional vector space  $\text{span}\{p, q, r, s\}$ . It vanishes at  $\pm p, \pm q$  and hence takes its maximum 1 on  $S$  at  $\pm r$  and its minimum  $-1$  at  $\pm s$ ,

or vice versa. Hence we get  $x_i \in S \cap M_-$ . Without loss of generality we may assume that  $x_i = r$ . Then we have  $b_2(r) = \varepsilon$  and  $b_2(s) = -\varepsilon$ . This implies that  $(Q_{\lambda_i} - Q_{-\lambda_i})(r) = \varepsilon r$  and  $(Q_{\lambda_i} - Q_{-\lambda_i})(s) = -\varepsilon s$ . Now choose  $s' \in V_0(r) \cap \mathbb{S}$  arbitrarily. Then the great circle of  $\mathbb{S}$  through  $r$  and  $s'$  is normal to  $M$  and we see as before that  $(Q_{\lambda_i} - Q_{-\lambda_i})(s') = -\varepsilon s'$ . Hence, we obtain  $V_0(r) \subseteq E_{(-\varepsilon)\lambda}$ . Analogously, we get  $V_0(s) \subseteq E_{\varepsilon\lambda}$ . We choose orthonormal bases of  $V_3'(p)$ ,  $V_3'(q)$ ,  $V_0(r)$ , and  $V_0(s)$ . In this way we get an orthonormal base of  $V$ , and we describe the quadratic form  $b_2$  by a matrix with respect to this base. The trace of this matrix is equal to 0 since  $b_2(x) = b_2(y) = 0$  (because of  $V_0(r), V_0(s) \subseteq \mathbb{R}M_+$ ),  $b_2(z) = -\varepsilon\langle z, z \rangle$ , and  $b_2(w) = \varepsilon\langle w, w \rangle$  for  $x \in V_3'(p)$ ,  $y \in V_3'(q)$ ,  $z \in V_0(r)$ ,  $w \in V_0(s)$ , where  $\dim V_0(r) = \dim V_0(s) = m_2 + 1$ . We conclude that also the trace of the matrix  $Q_{\lambda_i} - Q_{-\lambda_i}$  is equal to 0. Hence,  $\lambda_i$  and  $-\lambda_i$  are eigenvalues of  $A^{(1)}$  with the same multiplicity  $\mu_i \geq m_2 + 1$ . This completes the proof.  $\square$

#### 4. Main theorem

In this section we apply the results of Proposition 3.1 in order to prove a characterization of isoparametric hypersurfaces of Clifford type under the assumption that  $\dim M_+ \geq \dim M_-$ . This assumption is equivalent to  $m_1 \leq m_2$  because of  $\dim M_+ = m_1 + 2m_2$  and  $\dim M_- = m_2 + 2m_1$ , see [6], proof of Theorem 4, cf. [4], 3.1. Note that this condition is satisfied for all isoparametric hypersurfaces of Clifford type except for a small number of exceptions, see [2], 4.3 and 7.

**4.1 Theorem.** *Let  $M$  be an isoparametric hypersurface in  $\mathbb{S} \subseteq \mathbb{R}^{2l}$  with four distinct principal curvatures and assume that the two focal manifolds  $M_+$  and  $M_-$  satisfy  $\dim M_+ \geq \dim M_-$ . Let  $\mathcal{U}$  denote a subspace of  $\mathcal{S}_{2l}$  such that  $\mathcal{U} \setminus \{0\}$  consists of regular matrices. Then the following two statements are equivalent.*

- (i)  $M_+ = \{x \in \mathbb{S} \mid \langle x, Ax \rangle = 0 \text{ for every } A \in \mathcal{U}\}$ .
- (ii) *The subspace  $\mathcal{U}$  is generated by a Clifford system, and  $M$  is an isoparametric hypersurface of Clifford type associated with this Clifford system.*

*Proof.* We have already mentioned that (ii) implies (i), see [2], 4.2 (ii). In order to prove (i)  $\Rightarrow$  (ii), choose  $A \in \mathcal{U} \setminus \{0\}$  arbitrarily. Assume that  $A$  has at least two eigenvalues with different absolute values. Then, by Proposition 3.1, the matrix  $A$  has at least four distinct eigenvalues, each of which has at least multiplicity  $m_2 + 1$ . We conclude that  $4(m_2 + 1) \leq 2l = 2(m_1 + m_2 + 1)$ . This is equivalent to  $m_2 + 1 \leq m_1$  and contradicts  $m_1 \leq m_2$ . Hence, all eigenvalues of  $A$  have the same absolute value and we obtain  $A^2 = \langle A, A \rangle \text{id}$  with respect to the scalar product  $\langle B, C \rangle = (1/2l) \text{trace}(BC)$  on  $\mathcal{S}_{2l}$ . Since  $M_+$  is a submanifold of codimension at least 2 in  $\mathbb{S}$ , the subspace  $\mathcal{U}$  is at least two-dimensional. We denote by  $\{P_0, P_1, \dots, P_m\}$  an orthonormal base of  $\mathcal{U}$ . Then we have  $P_i^2 = \text{id}$  for  $i = 0, \dots, m$ . Furthermore, for  $i, j \in \{0, \dots, m\}$  with  $i \neq j$  we have  $\|(1/\sqrt{2})(P_i + P_j)\| = 1$ , hence  $(1/2)(P_i - P_j)^2 = \text{id}$ , which implies that  $P_i P_j + P_j P_i = 0$ . Therefore  $(P_0, P_1, \dots, P_m)$  is a Clifford system. By (i), we have  $M_+ = \{x \in \mathbb{S} \mid \langle x, P_i x \rangle = 0 \text{ for } i = 0, \dots, m\}$ . Since families of isoparametric hypersurfaces are uniquely determined by one of their focal manifolds (cf. [5], 3.2, or [6], Section 6), we conclude that  $M$  is an isoparametric hypersurface of Clifford type associated with

the Cartan-Münzner polynomial  $F : \mathbb{R}^{2l} \rightarrow \mathbb{R} : x \mapsto \langle x, x \rangle^2 - 2 \sum_{i=0}^m \langle P_i x, x \rangle^2$ , cf. [2], 4.1, 4.2 (ii). This completes the proof.  $\square$

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