

# On Pseudosymmetric Para-Kählerian Manifolds

Dorota Łuczyszyn

*Institute of Mathematics, Wrocław University of Technology  
Wybrzeże Wyspiańskiego 27, PL-50-370 Wrocław, Poland*

**Abstract.** In the present paper, we consider para-Kählerian manifolds satisfying various curvature conditions of the pseudosymmetric type. Let  $(M, J, g)$  be a para-Kählerian manifold. We prove the following theorems: The Ricci-pseudosymmetry of  $(M, J, g)$  reduces to the Ricci-semisymmetry. The pseudosymmetry as well as the Bochner-pseudosymmetry and the paraholomorphic projective-pseudosymmetry of the manifold  $(M, J, g)$  always reduces to the semisymmetry in dimensions  $> 4$ . The paraholomorphic projective-pseudosymmetry reduces to the pseudosymmetry in dimension 4. Moreover, we establish new examples of para-Kählerian manifolds being Ricci-semisymmetric (in dimensions  $\geq 6$ ) as well as pseudosymmetric (in dimension 4) or Bochner-pseudosymmetric (in dimension 4). We have given examples of semisymmetric para-Kählerian manifolds in [7] and [8].

## 1. Preliminaries

By a para-Kählerian manifold we mean a triple  $(M, J, g)$ , where  $M$  is a connected differentiable manifold of dimension  $n = 2m$ ,  $J$  is a  $(1, 1)$ -tensor field and  $g$  is a pseudo-Riemannian metric on  $M$  satisfying the conditions

$$J^2 = I, \quad g(JX, JY) = -g(X, Y), \quad \nabla J = 0,$$

for any  $X, Y \in \mathfrak{X}(M)$ , where  $\mathfrak{X}(M)$  is Lie algebra of vector fields on  $M$ ,  $\nabla$  is the Levi-Civita connection of  $g$  and  $I$  is the identity tensor field.

Let  $(M, J, g)$  be a para-Kählerian manifold. By  $R(X, Y)$  we denote its curvature operator,  $R(X, Y) = [\nabla_X, \nabla_Y] - \nabla_{[X, Y]}$ . The Riemann-Christoffel curvature tensor  $R$ , the Ricci curvature tensor  $S$  and the scalar curvature  $r$  are defined by

$$\begin{aligned} R(X, Y, Z, W) &= g(R(X, Y)Z, W), \\ S(X, Y) &= \text{Tr} \{ Z \mapsto R(Z, X)Y \}, \\ r &= \text{Tr}_g S. \end{aligned}$$

Let  $\tilde{S}$  be the Ricci operator given by  $S(X, Y) = g(\tilde{S}X, Y)$ . For these tensor fields, the following identities are satisfied

$$\begin{aligned} R(JX, JY) &= -R(X, Y), & R(JX, Y) &= -R(X, JY), \\ S(JX, Y) &= -S(JY, X), & S(JX, JY) &= -S(X, Y), \\ \text{Tr} \{ Z \mapsto R(X, Y)JZ \} &= -2S(X, JY), \\ \text{Tr} \{ Z \mapsto R(JZ, X)Y \} &= S(X, JY). \end{aligned} \tag{1}$$

Next, for a symmetric  $(0, 2)$ -tensor field  $A$  on  $M$  and  $X, Y \in \mathfrak{X}(M)$ , we define the endomorphism  $X \wedge_A Y$  of  $\mathfrak{X}(M)$  by

$$(X \wedge_A Y)Z = A(Y, Z)X - A(X, Z)Y, \quad Z \in \mathfrak{X}(M).$$

In the case when  $A = g$ , we shall write  $\wedge$  instead of  $\wedge_g$ . The Bochner curvature tensor  $B$  is defined by [1], [8]

$$\begin{aligned} B(X, Y) &= R(X, Y) - \frac{1}{n+4}(X \wedge (\tilde{S}Y) + (\tilde{S}X) \wedge Y - (JX) \wedge (\tilde{S}JY) \\ &\quad - (\tilde{S}JX) \wedge (JY) + 2g(JX, Y)\tilde{S}J + 2g(\tilde{S}JX, Y)J) \\ &\quad + \frac{r}{(n+4)(n+2)}(X \wedge Y - (JX) \wedge (JY) + 2g(JX, Y)J). \end{aligned}$$

Recall that the Bochner curvature  $(0, 4)$ -tensor,  $B(X, Y, Z, W) = g(B(X, Y)Z, W)$ , has the same algebraic properties as the usual curvature tensor. Moreover, for this tensor, we have

$$\begin{aligned} B(JX, JY) &= -B(X, Y), \\ \text{Tr} \{ Z \mapsto B(Z, X)Y \} &= 0, \quad \text{Tr} \{ Z \mapsto B(JZ, X)Y \} = 0. \end{aligned} \tag{2}$$

The paraholomorphic projective curvature tensor  $P$  of  $(M, J, g)$  is defined in the following manner [9], [10], [7]

$$P(X, Y) = R(X, Y) - \frac{1}{n+2}(X \wedge_S Y - (JX) \wedge_S (JY) + 2g(\tilde{S}JX, Y)J).$$

Notice that this tensor has the following properties

$$\begin{aligned} P(X, Y) &= -P(Y, X), \quad \text{Tr} \{ Z \mapsto P(Z, X)Y \} = 0, \\ \sum_i \varepsilon_i P(X, e_i, e_i, W) &= \frac{1}{n+2}(nS(X, W) - rg(X, W)). \end{aligned} \tag{3}$$

In the above and in the sequel,  $(e_1, e_2, \dots, e_n)$  is an orthonormal frame and  $\varepsilon_i$  is the indicator of  $e_i$ ,  $\varepsilon_i = g(e_i, e_i) = \pm 1$ .

**2. Main result**

For a  $(0, k)$ -tensor ( $k \geq 1$ ) field  $T$  on a pseudo-Riemannian manifold  $(M, g)$ , we define a  $(0, k + 2)$ -tensor field  $R \cdot T$  by the condition

$$(R \cdot T)(U, V, X_1, \dots, X_k) = - \sum_{s=1}^k T(X_1, \dots, R(U, V)X_s, \dots, X_k). \tag{4}$$

A pseudo-Riemannian manifold  $(M, g)$  is called: semisymmetric if  $R \cdot R = 0$ ; Ricci-semisymmetric if  $R \cdot S = 0$  (see [2], [6], [11]).

To formulate the notions of various pseudosymmetry type curvature conditions, we define also a  $(0, k + 2)$ -tensor ( $k \geq 1$ ) field  $Q(g, T)$

$$Q(g, T)(U, V, X_1, \dots, X_k) = - \sum_{s=1}^k T(X_1, \dots, (U \wedge V)X_s, \dots, X_k). \tag{5}$$

A pseudo-Riemannian manifold  $(M, g)$  is said to be Ricci-pseudosymmetric [6] if there exists a function  $L_S : M \rightarrow \mathbb{R}$  such that

$$R \cdot S = L_S Q(g, S).$$

Clearly, every Ricci-semisymmetric manifold is also Ricci-pseudosymmetric. The converse is not true in general [6]. However, we shall prove that the Ricci-pseudosymmetry reduces to the Ricci-semisymmetry in the class of para-Kählerian metrics.

**Theorem 1.** *Every Ricci-pseudosymmetric para-Kählerian manifold is Ricci-semisymmetric.*

*Proof.* Assume that a para-Kählerian manifold  $(M, J, g)$  satisfies the condition

$$(R \cdot S)(U, V, X, Y) = L_S Q(g, S)(U, V, X, Y). \tag{6}$$

Note that in virtue of (1) and (4), we have

$$(R \cdot S)(JU, JV, X, Y) = -(R \cdot S)(U, V, X, Y).$$

Thus by (6), we have

$$L_S Q(g, S)(U, V, X, Y) = -L_S Q(g, S)(JU, JV, X, Y).$$

Suppose that  $L_S$  is non-zero at a certain point  $p \in M$ . Then the above equality gives

$$Q(g, S)(U, V, X, Y) = -Q(g, S)(JU, JV, X, Y),$$

or in view of (5)

$$\begin{aligned} &S(U, Y)g(V, X) - S(V, Y)g(U, X) + S(U, X)g(V, Y) \\ &- S(V, X)g(U, Y) = -S(Y, JU)g(X, JV) + S(Y, JV)g(X, JU) \\ &- S(X, JU)g(Y, JV) + S(X, JV)g(Y, JU). \end{aligned}$$

This, by contraction with respect to  $V, X$  and applying of (1), we find

$$S(Y, U) = \frac{r}{n}g(Y, U),$$

that is, the manifold is Einstein. This gives  $R \cdot S = 0$ , which completes the proof. □

Now, we give examples of Ricci-semisymmetric para-Kählerian manifolds.

**Example 1.** Let  $(x_i)$  be the Cartesian coordinates in  $\mathbb{R}^6$  and  $\partial_i = \partial/\partial x^i$ . Define a pseudo-Riemannian metric  $g$  by

$$[g(\partial_i, \partial_j)] = \begin{bmatrix} x_6 + x_3^2 & 0 & 1 & 0 & 0 & 0 \\ 0 & x_5 + x_4^2 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

and a  $(1, 1)$ -tensor field  $J$  by

$$\begin{aligned} J\partial_1 &= -\partial_1 + (x_6 + x_3^2)\partial_3, & J\partial_2 &= \partial_2 - (x_5 + x_4^2)\partial_4, \\ J\partial_3 &= \partial_3, & J\partial_4 &= -\partial_4, & J\partial_5 &= -\partial_5, & J\partial_6 &= \partial_6. \end{aligned}$$

It is a straightforward verification that  $(J, g)$  is a para-Kählerian structure on  $\mathbb{R}^6$  which is Ricci-semisymmetric and non-semisymmetric (e.g., the component  $(R \cdot R)_{131212} = -1/2 \neq 0$ ). To get Ricci-semisymmetric non-semisymmetric manifolds in dimensions  $n = 6 + 2p, p \geq 1$ , it is sufficient to take the product of the para-Kählerian manifold  $(\mathbb{R}^6, J, g)$  and the standard para-Kählerian flat space  $(\mathbb{R}^{2p}, J_0, g_0)$ . □

A pseudo-Riemannian manifold  $(M, g)$  is said to be pseudosymmetric [6] if there exists a function  $L_R : M \rightarrow \mathbb{R}$  such that

$$R \cdot R = L_R Q(g, R). \tag{7}$$

Clearly, every semisymmetric manifold is also pseudosymmetric. The converse is not true in general [6].

**Theorem 2.** *Let  $(M, J, g)$  be a pseudosymmetric para-Kählerian manifold.*

- (a) *If  $\dim M = 4$ , then  $(M, J, g)$  is Ricci flat.*
- (b) *If  $\dim M > 4$ , then  $(M, J, g)$  is semisymmetric.*

*Proof.* Assume that the condition (7) is satisfied everywhere on  $M$ . Now, in the same way as in the proof of Theorem 1, we have

$$L_R Q(g, R)(U, V, X, Y, Z, W) = -L_R Q(g, R)(JU, JV, X, Y, Z, W). \tag{8}$$

Suppose that the function  $L_R$  is non-zero at a point  $p \in M$ . Therefore, (8) takes the form

$$Q(g, R)(U, V, X, Y, Z, W) = -Q(g, R)(JU, JV, X, Y, Z, W).$$

Contracting, the last relation with respect to  $X, V$ , we obtain

$$\sum_i \epsilon_i Q(g, R)(U, e_i, e_i, Y, Z, W) = -\sum_i \epsilon_i Q(g, R)(JU, Je_i, e_i, Y, Z, W)$$

which, with the help (5), can be rewritten in the following form

$$\begin{aligned} &nR(U, Y, Z, W) - R(U, Y, Z, W) + R(Y, U, Z, W) + R(Z, Y, U, W) \\ &+ R(W, Y, Z, U) + g(U, Z)S(Y, W) - g(U, W)S(Y, Z) = \\ &+ R(U, Y, Z, W) - R(Y, U, Z, W) - R(JU, W, Y, JZ) + R(JU, Z, Y, JW) \\ &+ 2g(Y, JU)S(Z, JW) - g(Z, JU)S(W, JY) + g(W, JU)S(Z, JY). \end{aligned}$$

Hence, using (1) and the first Bianchi identity, we get

$$\begin{aligned} &(n - 4)R(U, Y, Z, W) - 2g(Y, JU)S(Z, JW) + g(Z, JU)S(W, JY) \\ &- g(W, JU)S(Z, JY) + g(U, Z)S(Y, W) - g(U, W)S(Y, Z) = 0. \end{aligned} \tag{9}$$

(a) Let  $n = 4$ . Substituting  $JY$  instead of  $Y$  in (9), contracting the obtained relation with respect to  $Y, U$  and using (1), we find  $S = 0$ .

(b) Let  $n > 4$ . Contracting (9) with respect to  $Y, Z$ , we find

$$S(U, W) = \frac{r}{n}g(U, W).$$

This implies  $R \cdot S = 0$ . Using this fact in (9), we obtain  $R \cdot R = 0$ . □

Examples of semisymmetric para-Kählerian manifolds can be found in [7] and [8]. Below, we give an example of a 4-dimensional pseudosymmetric para-Kählerian manifold which is non-semisymmetric.

**Example 2.** Let  $U$  be the open subset of  $\mathbb{R}^4$  consisting of points at which  $x_1 > 0$ . Define a pseudo-Riemannian metric  $g$  by

$$[g(\partial_i, \partial_j)] = \begin{bmatrix} -2x_1 & 0 & 0 & 0 \\ 0 & 2x_1 & 0 & 0 \\ 0 & 0 & 2x_1^{-1} & -x_2x_1^{-1} \\ 0 & 0 & -x_2x_1^{-1} & 2x_2^2x_1^{-1} - 2x_1 \end{bmatrix}$$

and a  $(1, 1)$ -tensor field  $J$  by

$$\begin{aligned} J\partial_1 &= \partial_2, & J\partial_2 &= \partial_1, & J\partial_3 &= -x_2x_1^{-1}\partial_3 - (2x_1)^{-1}\partial_4, \\ J\partial_4 &= (2x_2^2x_1^{-1} - 2x_1)\partial_3 + x_2x_1^{-1}\partial_4. \end{aligned}$$

One verifies that  $(J, g)$  is para-Kählerian structure on  $U$ . Moreover, it can be checked that the structure is non-semisymmetric and pseudosymmetric with  $L_R = (2x_1^3)^{-1}$ .  $\square$

Now, we consider a para-Kählerian manifold, whose Bochner curvature tensor fulfills the condition

$$R \cdot B = L_B Q(g, B),$$

where  $L_B$  is a function on  $M$ . Such a manifold will be called Bochner-pseudosymmetric. In the special case when  $R \cdot B = 0$ , the manifold is said to be Bochner-semisymmetric [8].

**Theorem 3.** *Every Bochner-pseudosymmetric para-Kählerian manifold of dimension  $n > 4$  is Bochner-semisymmetric.*

*Proof.* Let  $(M, J, g)$  be a para-Kählerian manifold which is Bochner-pseudosymmetric. In the same manner as in the proof of Theorem 1, we find

$$L_B Q(g, B)(U, V, X, Y, Z, W) = -L_B Q(g, B)(JU, JV, X, Y, Z, W).$$

Let  $L_B$  be non-zero at  $p \in M$ . Then we have

$$Q(g, B)(U, V, X, Y, Z, W) = -Q(g, B)(JU, JV, X, Y, Z, W),$$

or in view of (5) with  $T = B$

$$\begin{aligned} & B(U, Y, Z, W)g(V, X) - B(V, Y, Z, W)g(U, X) + B(X, U, Z, W)g(V, Y) \\ & - B(X, V, Z, W)g(U, Y) + B(X, Y, U, W)g(V, Z) - B(X, Y, V, W)g(U, Z) \\ & + B(X, Y, Z, U)g(V, W) - B(X, Y, Z, V)g(U, W) \\ & = B(JV, Y, Z, W)g(X, JU) - B(JU, Y, Z, W)g(X, JV) \\ & + B(X, JV, Z, W)g(Y, JU) - B(X, JU, Z, W)g(Y, JV) + B(X, Y, JV, W)g(Z, JU) \\ & - B(X, Y, JU, W)g(Z, JV) + B(X, Y, Z, JV)g(W, JU) - B(X, Y, Z, JU)g(W, JV). \end{aligned}$$

Contracting the last identity with respect to  $X, V$  and next using (2) and the first Bianchi identity for  $B$ , we find

$$(n - 4)B(U, Y, Z, W) = 0.$$

This gives immediately  $B = 0$ , which completes the proof.  $\square$

**Remark 1.** In paper [8], we have shown that for a para-Kählerian manifold, the Bochner semisymmetry always implies the semisymmetry at points where the Bochner tensor does not vanish.

The assertion of Theorem 3 does not hold in dimension 4; see the following example.

**Example 3.** Let  $h$  be a function on  $\mathbb{R}$  such that  $h \neq 0$  and  $h' \neq 0$  at any point. On  $\mathbb{R}^4$ , define a pseudo-Riemannian metric  $g$  by

$$[g(\partial_i, \partial_j)] = \begin{bmatrix} -h'(x_1)/2 & 0 & 0 & 0 \\ 0 & h(x_1) & 0 & 0 \\ 0 & 0 & h'(x_1)/2 & -x_2 h'(x_1) \\ 0 & 0 & -x_2 h'(x_1) & -h(x_1) + 2x_2^2 h'(x_1) \end{bmatrix}$$

and a (1, 1)-tensor field  $J$  by

$$J\partial_1 = \partial_3, \quad J\partial_2 = 2x_2\partial_3 + \partial_4, \quad J\partial_3 = \partial_1, \quad J\partial_4 = \partial_2 - 2x_2\partial_2.$$

Then  $(J, g)$  is a para-Kählerian structure which is non-pseudosymmetric and Bochner pseudosymmetric with

$$L_B = \frac{h(x_1)h''(x_1) - h'^2(x_1)}{h^2(x_1)h'(x_1)}. \quad \square$$

A para-Kählerian manifold  $(M, J, g)$  will be called paraholomorphic projective-pseudosymmetric if there exists a function  $L_P : M \rightarrow \mathbb{R}$  such that

$$R \cdot P = L_P Q(g, P).$$

**Theorem 4.** *Let  $(M, J, g)$  be a paraholomorphic projective-pseudosymmetric para-Kählerian manifold.*

- (a) *If  $\dim M = 4$ , then  $(M, J, g)$  is Ricci flat and pseudosymmetric.*
- (b) *If  $\dim M > 4$ , then  $(M, J, g)$  is semisymmetric.*

*Proof.* If  $R \cdot P = 0$  at a certain point of  $M$ , then  $R \cdot R = 0$  at this point (it was really shown in the paper [7], Theorem 1, since this is a pointwise property). In the sequel, we assume that  $R \cdot P \neq 0$  at a point of  $M$ . Let  $G$  be the contracted tensor  $P$ ,

$$G(X, W) = \sum_i \epsilon_i P(X, e_i, e_i, W).$$

Thus, by (3), we have

$$G(X, W) = \frac{1}{n+2}(nS(X, W) - rg(X, W)). \quad (10)$$

Since  $(M, J, g)$  is paraholomorphic projective-pseudosymmetric, the following formula is fulfilled

$$(R \cdot P)(U, V, X, Y, Z, W) = L_P Q(g, P)(U, V, X, Y, Z, W). \quad (11)$$

Contracting (11) with respect to  $Y, Z$  and using (4) and (5), we obtain

$$(R \cdot G)(U, V, X, W) = L_P Q(g, P)(U, V, X, W).$$

Hence, using (10) and (4), we get

$$(R \cdot S)(U, V, X, W) = L_P Q(g, S)(U, V, X, W).$$

This by Theorem 1 implies  $R \cdot S = 0$ . Note that  $L_P$  is non-zero at  $p$ . Then  $Q(g, S) = 0$  at this point. Therefore, in virtue of (3) and (11), we find  $R \cdot R = L_P Q(g, R)$ . Thus,  $(M, J, g)$  is pseudosymmetric. To finish the proof it is sufficient to use Theorem 2.  $\square$

**Final remarks.** 1. The notion of the para-Kählerian manifold used in the presented paper is different from that applied in papers [6], [5], where the structure tensor  $J$  is an almost complex structure and the metric  $g$  is positive definite.

2. The local components of geometric objects (that is, the Levi-Civita connection, the Riemann, Ricci, Bochner and paraholomorphic projective curvature tensors and the scalar curvature) in our examples were calculated with the help of *Mathematica* programs.

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