

# ON EXISTENCE OF POSITIVE SOLUTION FOR INITIAL VALUE PROBLEM OF NONLINEAR FRACTIONAL DIFFERENTIAL EQUATIONS OF ORDER

$$1 < \alpha \leq 2$$

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**ABSTRACT.** The existence of positive solution for a class of nonlinear fractional differential equations are investigated by the method of upper and lower solutions and using Schauder and Banach fixed point theorems.

## 1. INTRODUCTION

The fractional differential equations (FDE) are considered as alternative models to nonlinear differential equations which induced extensive researches in various applicable fields such as physics, mechanics, chemistry, engineering, etc. (see [4], [6], [15]). In recent years, the theory of fractional differential equations has been given a great interest, especially to finding sufficient conditions for existence and uniqueness of the solutions of nonlinear FDE ([7]–[11], [13], and references therein). Many researchers (see [1], [2], [5], [12] and [14]) investigated the positivity of such solutions for FDE. More precisely, D. Delbosco and L. Rodino [3] proved the existence of the solutions to FDE using Banach and Schauder fixed point theorems; Zhang [12] investigated the existence and

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Received January 30, 2014.

2010 *Mathematics Subject Classification.* Primary 26A33; Secondary 34A12, 34G20.

*Key words and phrases.* fractional differential equations; positive solution; upper and lower solutions; existence and uniqueness; Banach and Schauder fixed point theorems.



Go back

Full Screen

Close

Quit



uniqueness of positive solution using the method of the upper and lower solution and cone fixed-point theorem; Lakshmikantham [13] obtained the existence of the local and global solutions using classical differential equation theorem. However, in the previous works, the nonlinear function in the FDE has to satisfy a monotonous characteristic or some control conditions. In fact, the FDEs with nonmonotone function can respond better to impersonal law, so it is very important to weaken monotone condition. Moreover, the cone fixed point theorems are used to get the existence of positive a solution.

Motivated by these works, in this paper, we mainly investigate the existence of solution to FDE of order  $1 < \alpha \leq 2$  without any monotonic conditions nor using cone fixed theorem, but by considering the so-called upper and lower control functions. These functions can be used in the technique of upper and lower solutions in connection with Schauder and Banach fixed-point theorems.

## 2. PRELIMINARIES

Let  $X = C(J)$ ,  $J = [0, 1]$  be the Banach space of all real-valued continuous functions defined on the compact interval  $J$ , endowed with the maximum norm. Define the subspace  $A = \{x \in X : x(t) \geq 0, t \in J\}$  of  $X$ . By a positive solution  $x \in X$ , we mean a function  $x(t) > 0$ ,  $0 < t \leq 1$  and  $x(0) = 0$ .

Let  $a, b \in \mathbb{R}^+$  such that  $b > a$ . For any  $x \in [a, b]$ , we define the upper-control function  $U(t, x) = \sup\{f(t, \lambda) : a \leq \lambda \leq x\}$ , and lower-control function  $L(t, x) = \inf\{f(t, \lambda) : x \leq \lambda \leq b\}$ . Obviously,  $U(t, x)$ , and  $L(t, x)$  are monotonous non-decreasing on the argument  $x$  and  $L(t, x) \leq f(t, x) \leq U(t, x)$ .

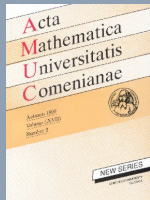


Go back

Full Screen

Close

Quit



We assume hereafter that  $f: J \times X \rightarrow X$  is a continuous function such that the fractional integral

$$I^\alpha f(t, x(t)) = \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds$$

exists for any order  $0 < \alpha \leq 2$ . Moreover, the Caputo fractional derivative  $D^\alpha x = I^{2-\alpha} x^{(2)}$ ,  $x \in X$  exists for any order  $1 < \alpha \leq 2$ .

Consider the following nonlinear fractional differential equation

$$(1) \quad \begin{cases} D^\alpha x(t) = f(t, x(t)), & 0 < t \leq 1, \\ x(0) = 0, & x'(0) = \theta > 0, \end{cases}$$

where  $1 < \alpha \leq 2$ . Equation (1) is the equivalent to the integral equation (see [7])

$$(2) \quad x(t) = \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds.$$

To transform equation (2) to be applicable to Schauder fixed point, we define an operator  $\Phi: A \rightarrow A$  by

$$(3) \quad (\Phi x)(t) = \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds, \quad t \in J,$$

where the figured fixed point must satisfy the identity operator equation  $\Phi x = x$ .

The following assumptions are needed for the next results.

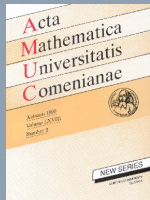


Go back

Full Screen

Close

Quit



**H1** Let  $x^*(t)$ ,  $x_*(t) \in A$ , such that  $a \leq x_*(t) \leq x^*(t) \leq b$  and

$$\begin{cases} D^\alpha x^*(t) \geq U(t, x^*(t)), \\ D^\alpha x_*(t) \leq L(t, x_*(t)) \end{cases}$$

for any  $t \in J$ .

**H2** For  $t \in J$  and  $x, y \in X$ , there exists a positive real number  $\beta < 1$  such that

$$|f(t, y) - f(t, x)| \leq \beta \|y - x\|.$$

The functions  $x^*(t)$  and  $x_*(t)$  are respectively called the pair of upper and lower solutions for Equation (1).

### 3. EXISTENCE OF POSITIVE SOLUTION

In this section, we consider the results of existence problem for many cases of the FDE (1). Moreover, we introduce the sufficient conditions of the uniqueness problem of (1).

**Theorem 3.1.** *Assume that (H1) is satisfied, then the FDE (1) has at least one solution  $x \in X$  satisfying  $x_*(t) \leq x(t) \leq x^*(t)$ ,  $t \in J$ .*

*Proof.* Let  $C = \{x \in A : x_*(t) \leq x(t) \leq x^*(t), t \in J\}$ , endowed with the norm  $\|x\| = \max_{t \in J} |x(t)|$ , then we have  $\|x\| \leq b$ . Hence,  $C$  is a convex, bounded, and closed subset of the Banach space  $X$ . Moreover, the continuity of  $f$  implies the continuity of the operator  $\Phi$  on  $C$  defined by (3). Now, if  $x \in C$ , there exists a positive constant  $c$  such that  $\max\{f(t, x(t)) : t \in J, x(t) \leq b\} < c$ . Then

$$|(\Phi x)(t)| \leq \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |f(s, x(s))| ds \leq \theta + \frac{ct^\alpha}{\Gamma(\alpha+1)}.$$

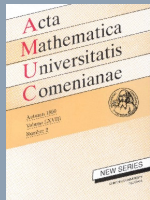


Go back

Full Screen

Close

Quit



Thus,

$$\|\Phi x\| \leq \theta + \frac{c}{\Gamma(\alpha + 1)}.$$

Hence,  $\Phi(C)$  is uniformly bounded. Next, we prove the equicontinuity of  $\Phi$ . Let  $x \in C$ ,  $\varepsilon > 0$ ,  $\delta > 0$ , and  $0 \leq t_1 < t_2 \leq 1$  such that  $|t_2 - t_1| < \delta$ . If  $\delta = \min \left\{ 1, \frac{\varepsilon \Gamma(\alpha + 1)}{2(\theta \Gamma(\alpha + 1) + 2c)}, \left( \frac{\varepsilon \Gamma(\alpha + 1)}{4c} \right)^{\frac{1}{\alpha}} \right\}$ , then

$$\begin{aligned} & |(\Phi x)(t_1) - (\Phi x)(t_2)| \\ & \leq \theta(t_2 - t_1) \\ & \quad + \left| \frac{1}{\Gamma(\alpha)} \int_0^{t_1} (t_1 - s)^{\alpha-1} f(s, x(s)) ds - \frac{1}{\Gamma(\alpha)} \int_0^{t_2} (t_2 - s)^{\alpha-1} f(s, x(s)) ds \right| \\ & \leq \theta(t_2 - t_1) + \left| \frac{1}{\Gamma(\alpha)} \int_0^{t_1} \left( (t_1 - s)^{\alpha-1} - (t_2 - s)^{\alpha-1} \right) f(s, x(s)) ds \right| \\ & \quad + \left| \frac{1}{\Gamma(\alpha)} \int_{t_1}^{t_2} (t_2 - s)^{\alpha-1} f(s, x(s)) ds \right| \\ & \leq \theta(t_2 - t_1) + \frac{c}{\Gamma(\alpha + 1)} (t_2^\alpha - t_1^\alpha + 2(t_2 - t_1)^\alpha) \\ & \leq \left( \theta + \frac{2c}{\Gamma(\alpha + 1)} \right) \delta + \frac{2c\delta^\alpha}{\Gamma(\alpha + 1)} \\ & < \varepsilon. \end{aligned}$$

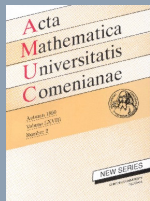


Go back

Full Screen

Close

Quit



Therefore,  $\Phi(C)$  is equicontinuous. The Arzelè-Ascoli Theorem implies that  $\Phi: A \rightarrow A$  is compact. The only thing to apply Schauder fixed point is to prove that  $\Phi(C) \subseteq C$ . Let  $x \in C$ , then by hypotheses, we have

$$\begin{aligned}(\Phi x)(t) &= \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds \\ &\leq \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} U(s, x(s)) ds \\ &\leq \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} U(s, x^*(s)) ds \leq x^*(t),\end{aligned}$$

and

$$\begin{aligned}(\Phi x)(t) &= \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} f(s, x(s)) ds \\ &\geq \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} L(s, x(s)) ds \\ &\geq \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} L(s, x_*(s)) ds \geq x_*(t).\end{aligned}$$



Go back

Full Screen

Close

Quit



Hence,  $x_*(t) \leq (\Phi x)(t) \leq x^*(t)$ ,  $t \in J$ , that is,  $\Phi(C) \subseteq C$ . According to Schauder fixed point theorem, the operator  $\Phi$  has at least one fixed point  $x \in C$ . Therefore, the FDE (1) has at least one positive solution  $x \in X$  and  $x_*(t) \leq x(t) \leq x^*(t)$ ,  $t \in J$ .  $\square$

Next, we consider many particular cases of the previous theorem.

**Corollary 3.2.** *Assume that there exist continuous functions  $k_1(t)$  and  $k_2(t)$  such that  $0 < k_1(t) \leq f(t, x(t)) \leq k_2(t) < \infty$ ,  $(t, x(t)) \in J \times [0, +\infty)$ . Then, the FDE (1) has at least one positive solution  $x \in X$ . Moreover,*

$$(4) \quad \theta t + I^\alpha k_1(t) \leq x(t) \leq \theta t + I^\alpha k_2(t).$$

*Proof.* By the given assumption and the definition of control function, we have  $k_1(t) \leq L(t, x) \leq U(t, x) \leq k_2(t)$ ,  $(t, x(t)) \in J \times [a, b]$ . Now, we consider the equations

$$(5) \quad \begin{aligned} D^\alpha x(t) &= k_1(t), & x(0) &= 0, & x'(0) &= \theta \\ D^\alpha x(t) &= k_2(t), & x(0) &= 0, & x'(0) &= \theta. \end{aligned}$$

Obviously, equations (5) are equivalent to

$$x(t) = \theta t + I^\alpha k_1(t),$$

$$x(t) = \theta t + I^\alpha k_2(t).$$

Hence, the first implies  $x(t) - \theta t = I^\alpha k_1(t) \leq I^\alpha(L(t, x(t)))$ , and the second implies  $x(t) - \theta t = I^\alpha k_2(t) \geq I^\alpha(U(t, x(t)))$ , which are the upper and lower solutions of Equation (5), respectively. An application of Theorem 3.1 yields that the FDE (1) has at least one solution  $x \in X$  and satisfies Equation (4).  $\square$

**Corollary 3.3.** *Assume that  $0 < \sigma < k(t) = \lim_{x \rightarrow \infty} f(t, x) < \infty$  for  $t \in J$ . Then the FDE (1) has at least a positive solution  $x \in X$ .*

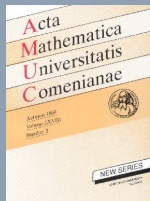


Go back

Full Screen

Close

Quit



*Proof.* By assumption, if  $x > \rho > 0$ , then  $0 \leq |f(t, x) - k(t)| < \sigma$  for any  $t \in J$ . Hence,  $0 < k(t) - \sigma \leq f(t, x) \leq k(t) + \sigma$  for  $t \in J$  and  $\rho < x < +\infty$ . Now if  $\max\{f(t, x) : t \in J, x \leq \rho\} \leq \nu$ , then  $k(t) - \sigma \leq f(t, x) \leq k(t) + \sigma + \nu$  for  $t \in J$ , and  $0 < x < +\infty$ . By Corollary 3.2, the FDE (1) has at least one positive solution  $x \in X$  satisfying

$$\theta t + I^\alpha k(t) - \frac{\sigma t^\alpha}{\Gamma(\alpha + 1)} \leq x(t) \leq \theta t + I^\alpha k(t) + \frac{(\sigma + \nu)t^\alpha}{\Gamma(\alpha + 1)}.$$

□

**Corollary 3.4.** Assume that  $0 < \sigma \leq f(t, x(t)) \leq \gamma x(t) + \eta < \infty$  for  $t \in J$ , and  $\sigma, \eta$  and  $\gamma$  are positive constants. Then, the FDE (1) has at least one positive solution  $x \in C[0, \delta]$ , where  $0 < \delta < 1$ .

*Proof.* Consider the equation

$$(6) \quad \begin{aligned} D^\alpha x(t) &= \gamma x(t) + \eta, & 0 < t \leq 1, \\ x(0) &= 0, & x'(0) = \theta > 0. \end{aligned}$$

Equation (6) is equivalent to integral equation

$$\begin{aligned} x(t) &= \theta t + \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} (\gamma x(s) + \eta) ds \\ &= \theta t + \frac{\eta t^\alpha}{\Gamma(\alpha + 1)} + \frac{\gamma}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} x(s) ds. \end{aligned}$$



Go back

Full Screen

Close

Quit





Let  $\omega$  and  $\phi$  be positive real numbers. Choose an appropriate  $\delta \in (0, 1)$  such that  $0 < \frac{\gamma\delta^\alpha}{\Gamma(\alpha+1)} < \phi < 1$  and  $\omega > (1-\phi)^{-1} \left( \theta\delta + \frac{\eta\delta^\alpha}{\Gamma(\alpha+1)} \right)$ . Then if  $0 \leq t \leq \delta$ , the set  $B_\omega = \{x \in X : |x(t)| \leq \omega, 0 \leq t \leq \delta\}$  is convex, closed, and bounded subset of  $C[0, \delta]$ . The operator  $F: B_\omega \rightarrow B_\omega$  given by

$$(Fx)(t) = \theta t + \frac{\eta t^\alpha}{\Gamma(\alpha+1)} + \frac{\gamma}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} x(s) ds$$

is compact as in the proof of Theorem 3.1. Moreover,

$$|(Fx)(t)| \leq \theta t + \frac{\eta t^\alpha}{\Gamma(\alpha+1)} + \frac{\gamma t^\alpha}{\Gamma(\alpha+1)} \|x\|.$$

If  $x \in B_\omega$ , then

$$|(Fx)(t)| \leq (1-\phi)\omega + \phi\omega = \omega,$$

that is  $\|Fx\| \leq \omega$ . Hence, the Schauder fixed theorem ensures that the operator  $F$  has at least one fixed point in  $B_\omega$ , and then Equation (6) has at least one positive solution  $x^*(t)$ , where  $0 < t < \delta$ . Therefore, if  $t \in J$  one can asserts that

$$x^*(t) = \theta t + \frac{\eta t^\alpha}{\Gamma(\alpha+1)} + \frac{\gamma}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} x^*(s) ds.$$

The definition of control function implies  $U(t, x^*(t)) \leq \gamma x^*(t) + \eta = D^\alpha x^*(t)$ , then  $x^*$  is an upper positive solution of the FDE (1). Moreover, one can consider  $x_*(t) = \theta t + \frac{\sigma t^\alpha}{\Gamma(\alpha+1)}$  as a lower positive solution of Equation (1). By Theorem 3.1, the FDE (1) has at least one positive solution  $x \in C[0, \delta]$ , where  $0 < \delta < 1$  and  $x_*(t) \leq x(t) \leq x^*(t)$ .  $\square$



Go back

Full Screen

Close

Quit



The last result is the uniqueness of the positive solution of (1) using Banach contraction principle.

**Theorem 3.5.** *Assume that (H1) and (H2) are satisfied. Then the FDE (1) has a unique positive solution  $x \in X$ .*

*Proof.* From Theorem 3.1, it follows that the FDE (1) has at least one positive solution in  $C$ . Hence, we need only to prove that the operator  $\Phi$  defined in (3) is a contraction on  $X$ . In fact, for any  $x, y \in X$ , we have

$$\begin{aligned} |(\Phi x)(t) - (\Phi y)(t)| &\leq \frac{1}{\Gamma(\alpha)} \int_0^t (t-s)^{\alpha-1} |f(s, x(s)) - f(s, y(s))| ds \\ &\leq \frac{\beta t^\alpha}{\Gamma(\alpha+1)} \|x - y\|. \end{aligned}$$

If  $1 < \alpha \leq 2$ , then  $1 < \Gamma(\alpha+1) \leq 2$  implies  $\frac{\beta t^\alpha}{\Gamma(\alpha+1)} < 1$ . Hence, the operator  $\Phi$  is a contraction mapping. Therefore, the FDE (1) has a unique positive solution  $x \in X$ .  $\square$

Finally, we give an example to illustrate our results.

**Example 3.6.** *We consider the fractional equation*

$$(7) \quad \begin{cases} D^{\frac{3}{2}} x(t) = 1 + \frac{t e^{-tx(t)}}{1 + \cos t}, & 0 < t \leq 1 \\ x(0) = 0, & x'(0) = \theta > 0, \end{cases}$$

where  $f(t, x) = 1 + \frac{t e^{-tx}}{1 + \cos t}$ . Since  $\lim_{x \rightarrow \infty} (1 + \frac{t e^{-tx}}{1 + \cos t}) = 1$  and  $1 \leq 1 + \frac{1}{2} t e^{-tx} \leq f(t, x) \leq 1 + t e^{-tx} \leq 1 + t \leq 2$  for  $(t, x) \in [0, 1] \times [0, +\infty)$ , hence by any of the above Corollaries, the

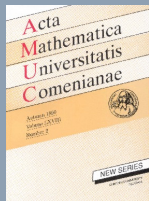


Go back

Full Screen

Close

Quit



equation (7) has a positive solution. We lost the uniqueness property of the existed solution due to the contraction principle is not applicable on the function  $f(t, x)$ .

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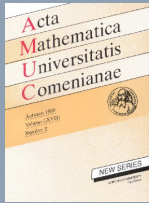


Go back

Full Screen

Close

Quit



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Go back

Full Screen

Close

Quit